Non-Linear Dynamics of Caisson Well-Protectors During Hurricane Andrew Report to U.S. Minerals Management Service Herndon, Virginia



By James Wiseman and Professor Robert Bea Marine Technology and Management Group

Department of Civil and Environmental Engineering University of California at Berkeley

August 1997

Table of Contents

1

0	INTRODUCTION						
.0	BACKGROUND						
0.	PROBLE	EM STATEMENT	2				
.0	LITERA	TURE REVIEW	3				
	4.1	Governing Equations of Dynamics	3				
	4.2	Choice of Single Degree of Freedom System	5				
	4.3	5					
	4.4	Ultimate Limit State Condition	6				
	4.5	Wave Loading - Method of Determining Waveheights	7				
	4.6	Review of Linear Wave Theory	8				
.0	ANALY	SIS	8				
	5.1	Environmental Conditions	9				
	5.2	Structural Analysis	11				
	5.3	Time History Analysis	12				
0	OBSERV	ATIONS	16				
0) CONCLUSIONS						
	0 0 0 0 0	 0 INTROD 0 BACKGI 0 PROBLE 0 LITERA 4.1 4.2 4.3 4.4 4.5 4.6 0 ANALYS 5.1 5.2 5.3 0 OBSERV 0 CONCL 	 INTRODUCTION BACKGROUND PROBLEM STATEMENT LITERATURE REVIEW 4.1 Governing Equations of Dynamics 4.2 Choice of Single Degree of Freedom System 4.3 Choice of Elasto-Perfectly Plastic System 4.4 Ultimate Limit State Condition 4.5 Wave Loading - Method of Determining Waveheights 4.6 Review of Linear Wave Theory ANALYSIS 5.1 Environmental Conditions 5.2 Structural Analysis 5.3 Time History Analysis OBSERVATIONS CONCLUSIONS 				

References

--

ς.

. .

Appendix

Non-Linear Dynamics of Caisson Well Protectors During Hurricane Andrew

1.0 INTRODUCTION

The Gulf of Mexico is home to thousands of offshore structures. In the early stages of offshore development, most installations were large drilling and production platforms. Later, as fields matured, and energy companies decided to produce from small fields, smaller structures were designed to support only a few wells, without any drilling or production equipment. Hydrocarbons are piped from these "minimal structures" to larger platforms for processing. "Minimal structures" don't have a strict definition; however, three types of structures usually fall in this category. They are: 1) caissons, 2) braced caissons, and 3) tripods (listed in order of size from smallest to largest). This study focuses only on caissons, which consist of a driven pile, from 3 to 8 feet in diameter, that support a maximum of four wells (most caissons support only one well).



Figure 1 Typical Caisson Elevation

They usually have only one deck, used for maintenance, and a boat landing. Some of the larger caissons can have a helideck and some test equipment. Figure 1 is an elevation of a typical 48 inch diameter caisson. Note that the only equipment it supports is a small davit, and a navigation light/horn.

ļ

2.0 BACKGROUND

In the aftermath of Hurricane Andrew, there was an urgent need to re-assess the capacity of minimal structures in the Gulf of Mexico. Many of the structures damaged were nearnew, and were designed for a storm the size of Andrew. Many structural analysts believed that design criteria needed to be updated, a lengthy and expensive process.

This study focuses on caissons that were in close proximity to the path of Hurricane Andrew (within 50 miles of the storm track). Hundreds of caissons were rendered inoperable in this area. Damages range from a few degrees of lean for some structures, to complete toppling for others.

3.0 PROBLEM STATEMENT

The goal of this study is to determine, if possible, the role that dynamics played in the failure of many of the caissons subjected to Hurricane Andrew, and specifically, if failure of individual caissons was due to dynamic effects alone, and not just simple overloading. Previous studies [3, 9] did not explicitly consider dynamics in evaluations of caisson performance during hurricane Andrew. A secondary goal of this project is to develop a simple tool to analyze caissons for dynamic effects using Newmark's method. [14] This is intended to be a quick check for structures that may be overloaded due to dynamic effects.

The first structure studied was located in Block 10-South Pelto. This 36 inch diameter caisson suffered an 11 degree lean after the storm passed. Specific attention will be paid to this caisson because it failed. If this caisson was able to withstand the maximum static wave forces generated at its location, it must have failed due to dynamic effects.

The second structure studied was located in Block 52 - South Timbalier. It was a 96 inch diameter "coke bottle" caisson standing in sixty feet of water. It was severed five feet above the mudline.

2

The third structure studied was located on Block 120-Ship Shoal. It stands in 40 feet of water and has a diameter of 4 feet. This structure was toppled by the storm, but the data does not give its failure mode.

4.0 LITERATURE REVIEW.

The structural data used in this project was taken by Barnett and Casbarian, following Hurricane Andrew, in 1994. Under contract to the Minerals Management Service (MMS), Barnett and Casbarian collected data for thousands of caissons in the Gulf of Mexico, including the condition of the caissons after the storm event.

Starting in the 1970's designers began to adopt a methodology in which a caisson was designed for an extreme static wave load, and then resized for effects of dynamics, using a Dynamic Amplification Factor (DAF). Hong suggested a DAF of 1.4 be used. [8] The API adopted this procedure for its guidelines. [4]

After model testing, in 1996. Kriebel et al. determined that the API guidelines overpredicted the water particle velocities and forces by 10% to 15% in most cases. However, random breaking waves sometimes generated forces that were 1.5 to 2.2 times as large as were analytically predicted. [9] According to Kriebel, "For these and other breaking waves, measured wave loads were strongly effected by dynamic amplification effects due to ringing of the structure following wave impact." In this case, Dynamic Amplification Factors (DAF's) ranged from 1.15, for five times the caisson's natural period, to very large values, at resonance (no values larger than 1.15 were measured, only predicted). [9]

To capture second order effects, and resonance, some type of time dependent approach needs to be used. Recently, time-history analysis using the finite-difference method has been accepted as the preferred method of dynamic analysis. The data from the timehistory analysis will be compared with the actual condition of the three caissons, as recorded by Barnett and Casbarian, to evaluate the analytical model.

4.1 Governing Equations Of Dynamics

Single degree of freedom systems are often represented as a spring, dashpot, and mass (Figure 2).



When the mass is perturbed, it oscillates back and forth at it's natural period, and if a damper (dashpot) is present, the oscillations die off until the mass returns to its equilibrium position. The equation describing this motion is Newton's second law:

$$\sum f = ma$$
[10]

<u>Figure 2</u> SDOF Oscillator

Summing forces and differentiating twice with respect to time gives,

$$mx = f(t) - cx - kx \tag{10}$$

Rearranging terms yields a familiar second order differential equation,

$$mx + cx + kx = f(t)$$
Where:
m = Mass of oscillator
c = Damping coefficient
k = Spring stiffness constant
f(t) = Arbitrary force

This equation has a solution of the form $x = A\sin(\omega t) + B\cos(\omega t)$

The natural period of this system depends only on k and m. It can be shown that for a SDOF system, the natural period, denoted T_n , is:

$$T_{n} = 2 \cdot \pi \cdot \sqrt{\frac{M}{K}}$$
 [10]

When the force perturbing the system is periodic, its response can take many different forms. When the period of the forcing function is close to the natural period of the structure, its motion starts to grow exaggerated. This phenomenon, called dynamic amplification (DA), can lead to structural overload. In the case of offshore oil platforms, periodic wave forces can cause overloading, leading to brace buckling and yielding of structural members. At this point, the stiffness of the system can change drastically. Non-linear analysis dictates that at each time step in the analysis, the stiffness must be reevaluated, and the equation must be solved again. This is necessary for complex, multidegree of freedom systems, but is not necessary for caissons, as detailed in section 4.2. 1

4.2 Choice Of Single Degree Of Freedom System

A caisson well protector very closely resembles the classic "mass on a flexible rod" system analyzed by students worldwide. The bending of this rod is the system's only degree of freedom; it can be analyzed in a very simple manner using software that is readily available. The properties of the system--such as mass, stiffness, and strength--can be varied easily, and the effects of these changes are readily interpreted. The dynamic behavior of a single degree of freedom (SDOF) system can be well-captured using Newmark's constant acceleration method. [14] For these reasons, a SDOF system was chosen for this analysis.



SDOF Structural Model

4.3 Choice of EPP System

For the non-linear portion of the analysis, it was decided to use an elasto-perfectly plastic system. That is to say, once the system reaches a certain load, it loses its stiffness. This is a good model for this structure, because once the ultimate plastic moment is reached, the structure forms a plastic hinge.

4.4 Ultimate Limit State Condition

Many oil platforms have failed in hurricanes, at least 200 major failed due to Hurricane Andrew – even more minimal structures failed. Most importantly, the failure -- or ultimate limit state condition -- for each type of offshore structure needs to be defined. In this study, failure is defined in two ways. Total failure is defined as the point at which the structure has been deflected so much that it can no longer support its vertical gravity loads, and collapses. The second type of failure is a loss of serviceability. Caissons are designed to produce oil or gas; if they are not producing, then they have failed. Caissons



Figure 4 SDOF System at Failure

that are deformed plastically, so that they are left with a permanent set, may not be able to produce hydrocarbons because the well may not be able to be controlled or worked-over. This is termed serviceability failure. Total failure occurs well after the structure has ceased fulfilling its service requirements. ١.

In order to understand the processes leading up to failure, a few terms need to be defined. When loads on a structure are small, it behaves linear-elastically. However, the structure has a defined

yield point; when internal stresses reach the yield stress, the structure will start to deform plastically. A measure of the magnitude of these stresses is called the overload ratio:

$$\eta = \frac{f_{\text{max}}}{f_{\text{yield}}} \tag{10}$$

Where F_y is the minimum force that causes yielding and F_{max} is the force applied to the structure.

In this study, the structures are assumed to behave elasto-perfectly plastically. That is to say, once the structures' yield point has been reached, it loses all its stiffness. This is a valid assumption for this simple study, when one considers that when overloaded dramatically, a caisson may buckle locally, or fail the soil due to cyclic degradation. Because of this zero post-yielding stiffness, the structure forms a failure mechanism, and starts to accelerate when it reaches an overload ration of one or greater. This phenomenon is displayed in Figure 5.



During the time $t_1 - t_0 = \Delta t$ the structure is deforming plastically. The length of this duration (Dt) determines the amount of plastic deformation.

The extent of a structure's plastic deformation can be described as an amount of displacement. However, usually yielding is defined as a ratio of the structures total deformation compared to its max. elastic deformation. This ratio is the structures ductility

demand, and is represented below as μ .

$$\mu = \frac{\Delta \max}{\Delta y}$$
[10]

Most structures are designed to fail in a ductile manner, and caissons nearly always fail in this way, because they do not have any joints to fracture, or braces to buckle.

4.5 Wave Loading – Method of Determining Wave Heights for the Analysis. A sea-state spectrum for Hurricane Andrew, considered by many to be a 200 year storm, was used as a basis for determining the wave heights at the sites studied. Combined with hindcast significant waveheights generated by the Minerals Management Service, a water surface profile was developed that reflected the confused nature of the sea generated by the storm. Wave energy was concentrated in three periods: T= 14s, 12s, and 10s, with heights of 10, 15, and 10 ft. respectively. By superimposing these three waves it was possible to generate a representative water surface profile. The profile indicated that waves traveling out of phase with eachother would super-impose to form "packets" of three large waves (called freak waves by sailors). These large wave-heights were used in MATLAB to do the dynamic analysis. Using the maximum wave heights for each site -- in all cases this was determined by the breaking criteria -- horizontal forces on the structure were determined, using depth stretched linear wave theory. This force was used to perform a static pushover analysis to determine the structure's ultimate moment capacity, based on the assumption that the maximum moment in a pile occurs 3-5 diameters below the mudline [4]. Applying the dynamic structural analysis will show if these wave forces are able to fail the structure.

Ļ

4.6 Review of Linear Wave Theory

While it is thought that linear wave theory is not a very good predictor of the water surface condition generated by a hurricane, it is well known and documented that it is excellent for modeling the wave induced motions over submerged cylindrical members. The velocity and acceleration of particles in the water column can be expressed as:

$$u_{\mathbf{X}} = \frac{\mathbf{pi} \cdot \mathbf{H}}{T} \cdot \frac{\cosh(\mathbf{k} \cdot \mathbf{s})}{\sinh(\mathbf{k} \cdot \mathbf{d})} \qquad \qquad \mathbf{a}_{\mathbf{X}} = \frac{2 \cdot \mathbf{pi}^2 \cdot \mathbf{H}}{T^2} \cdot \frac{\cosh(\mathbf{k} \cdot \mathbf{s})}{\sinh(\mathbf{k} \cdot \mathbf{d})}$$

This equation yields the kinematics near the still water level only. In order to extrapolate these values above or below the still water level, some form of stretching needs to be used. The most accurate way to accomplish this is the use of depth stretching, [1] where the SWL kinematics are stretched up to the instantaneous water surface, then brought down to the desired level. Analytically, this is accomplished by substituting s = z + d into the above equation.

Once the kinematics have been determined, the forces on individual members can be calculated using the Morisson, O'Brien, Johnson and Schaaf equation:

$$\mathbf{F}_{tot} = \mathbf{C}_{d} \cdot \frac{\mathbf{p}}{2} \cdot \mathbf{D} \cdot \mathbf{L} \cdot \mathbf{u}_{\mathbf{X}} \cdot \left(\left| \mathbf{U}_{\mathbf{X}} \right| \right) + \mathbf{C}_{m} \cdot \mathbf{p} \cdot \mathbf{V} \cdot \mathbf{a}_{\mathbf{X}}$$
[10]

For slender tubular members, such as the ones shown in figure 1, the wave forces are dominated by drag (the structure does not alter the characteristics of the wave). In fact, over 90% of the total force is due to drag. [1] The selection of a proper Cd becomes critical. Five steps need to be taken to determine the proper coefficient for each member. These steps are taken in the analysis to account for: Reynolds and KC number variations, member orientation, member roughness, and proximity to the free surface and/or mudline.

5.0 ANALYSIS

The analysis of the subject structures is a three-stage process, using three different software programs: Excel, Mathcad, and Matlab. Excel is used to superimpose the three waves derived from the sea-state spectrum, and to plot the water surface profiles. Mathcad is used for derivation of the caissons' structural characteristics, such as bending capacity, mass, stiffness, and resistance to local buckling. It is also used to determine the two structures natural periods. Finally, Matlab is used to perform a time-history analysis of the structures' behavior under periodic loading.

5.1 Environmental Conditions The first step in the analysis is to determine the maximum waveheight at each of the three sites. Data from the Minerals Management Service shows the track that Andrew took through the Gulf of Mexico, and then over the Mississippi Delta. It also shows the significant wave-heights as contours (See figure 6).

Using a lognormal distribution of wave-heights [1] and based on a sample of 200 waves (an average number for a big storm), one can determine the maximum waveheight.

$$H_{\text{max}} = H_{\text{s}} \sqrt{\frac{\ln(N)}{2}}$$

$$N = 200$$



Figure 6 Waveheight Contours at SS and ST Area

In some cases, this maximum height exceeded the breaking criteria, and had to be lowered in order to give accurate results.



Figure 7 Simplified Spectrum

A Hurricane Andrew wave spectrum was also used to determine the environmental conditions at the sites. As explained in section 4.5, it was not used so much to give the wave-heights, as to express the characteristics of the water-surface fluctuations.

A simplified spectrum is shown at left as figure 7. Figure 8 shows the sea surface eight hours after the center of the storm passed the location of the photographer. Note that there are distinct large

swells. These swells are represented by the large peak in the spectrum. The other wave periods passed this location before the photo was taken, leaving only the large regular waves. Regardless, Figure 8 still shows the enormity of the long period waves. The simplified spectrum was used to generate representative water surface profiles, given



Figure 8 Surface Conditions 10 Hours After the Storm Center Passed

in the appendix. The profiles show that when the three different waves, of random phases, are superimposed, they form distinct large wave "packets." These packets usually consist of two or three very large waves, which rapidly die off, to be followed by another packet. This is significant for the dynamic analysis, in that only three cycles of a large periodic force should be applied to the structures.

5.2 Structural Analysis

The three caisson structures were analyzed using Mathcad, because the program is visual and also very good at carrying units. The following characteristics were determined for each caisson: 1) point of apparent fixity, 2) stiffness, 3) weight, including inner casings and added mass, 4) natural period, 5) elastic and ultimate capacity, 6) possibility of local buckling, and 7) overload ratio. A summary table of the structural characteristics for the three caissons follows.

	Water	Diameter	Length to	Stiffness	Natural	Ultimate	Overload
	Depth	(in)	Fixity (ft)	(K/ft)	Period	Capacities	Ratio
	(ft)				(Sec)	(kips)	
Caisson 1	36	36	48.5	45	1.5	F _e =35.0	.98
			}			F _p =44.5	
Caisson 2	60	96	100	128.6	2.4	F _e =221	.588
						F _p =280	
				j			
Caisson 3	46	48	66	65.3	1.7	F _e =68.1	.787
						F _p =86.5	

The analyses for the three caissons is given in the appendix.

Because Caisson #2 is so much stiffer and stronger, it was analyzed using Lpile+, to ensure that the structure behaves in a ductile manner and does not simply rotate or "kick" due to soil failure. The results of this analysis are given in the appendix; they show that the caisson bends and deflects in a ductile manner.



Figure 9 Caisson Deck Plan

5.3 Time History Analysis

Following are the results of the time-history analysis. The Matlab code, first coded by J. Stear and G. Fenves, first calculates a sinusoidal water surface profile, with the number of waves defined by the user (in these cases, three or four). The program then uses the structures' geometry to determine wave forces. Since the caissons all have boat landings, the program adds on a deck/boatlanding force, when the wave is in contact with the landing. This landing was assumed to be 10 feet tall, and 12 feet wide. Since the structure is heavily framed, it is modelled as a block, with a C_d of 2.5 (See Figure 9).



Caisson #1 - Water Surface Profile and Force-Time Relationship

Caisson #1 - Displacement History and Force Displacement Relationship





Caisson #2 - Water Surface Profile and Force-Time Relationship

I,

Caisson #2 - Displacement History and Force Displacement Relationship





Caisson #3 – Water Surface Profile and Force-Time Relationship

I_

References

- Bea, R. G., "Wind and Wave Forces on Marine Structures" Class notes for CE205B, UC Berkeley, Fall 1996.
- [2] Smith, C.E., "Offshore Platform Damage Assessment in the Aftermath of Hurricane Andrew" Proceedings, 25th Meeting USNR Panel on Wind and Seismic Effects. Tsukuba, Japan May 17-20, 1993
- [3] Barnett & Casbarian, Inc. "Development of an Acceptance Criteria for Caisson Structures After Extreme Environmental Loading - Draft Report" August 1994, Houston, Texas
- [4] American Petroleum Institute, "API RP 2A-LRFD Section D 2.2.4a Local Buckling" APE, April 1, 1994
- [5] Personal Communication. Robert G. Bea, Professor and Vice Chair of Civil Engineering. University of California, Berkeley. December 1996.
- [6] Petrauskas C., Botelho D.L., Krieger W.F., and Griffin J.J, "A reliability Model for Offshore Platforms and its Application to ST151 "H" and "K" Platforms During Hurricane Andrew (1992)" Chevron Petroleum Technology Company La Habra, CA
- [7] Stear, James. Response of an Offshore Structure to Single and Series Waves. CE 205b, University of California, Berkeley. December 14, 1995
- [8] Hong, S. T. and Brooks, J. C., "Dynamic Behavior and Design of Offshore Caissons," Offshore Technology Conference, OTC 2555, 1976
- [9] Kriebel, D.L., Berek, E.P., Chakrabarti, S.K. and Waters, J.K, "Wave-Current Loading on a Shallow Water Caisson" Offshore Technology Conference, OTC 8067, 1996
- [10] D. T. McDonald, K. Bando, R. G. Bea, and R. J. Sobey. Near Surface Wave Forces on Horizontal Members and Decks of Offshore Platforms, Final Report, Coastal and Hydraulic Engineering, Department of Civil Engineering, University of California, Berkeley, December 18, 1990
- [11] MATLAB Version 4.2c, The Mathworks
- [12] MATHCAD Version 6.0+, Mathsoft Apps
- [13] Stahl, B. and Baur, M.P. "Design Methodology for Offshore Platform

Conductors" Offshore Technology Conference, OTC 3902, 1980

I,

[14] Newmark, N.M. "A Method of Computation for Structural Dynamics," Transactions ASCE, 1962

Appendix

. .

۱.

Water Surface Profiles Structural Analysis Using Mathcad [12] Lpile+ Plots Matlab Scripts Sheet1



Sheet1

4

Ŧ





ľ



Depth (Inches) (1000's)

Cntl-P to Print Screen



ł



Depth (Inches) (1000's)

Cntl-P to Print Screen

Caisson #1 South Pelto 10

30" diameter caisson in 36 feet of water.

1

1) Define geometry and constants for Mathcad

2) Define caisson structural characteristics

LI	6∙ft	WT 1 1.375 in	D _{il} 30-in WT ₁	I 1 .049087 D 4 D 11	$I_1 = 0.328 \cdot ft^4$
L 2	10∙ft	WT 2 = 1.375 in	$D_{12} > 30 \text{ in } WT_2$	$1_2 = .049087 \cdot \left(D_0^4 = D_{12}^4 \right)$	$1_2 = 0.328 \cdot ft^4$
L 3	10-ft	WT ₃ = 1.625 in	D ₁₃ 30·in WT ₃	$I_3 = .049087 \cdot \left(D_0^4 - D_{13}^4 \right)$	$I_3 = 0.383 \cdot ft^4$
L 4	30∙ft	WT 4 - 1.75 in	D i4 = 30 in - WT 4	$I_4 = .049087 \cdot \left(D_0^4 = D_{14}^4 \right)$	$I_4 = 0.41 \cdot ft^4$
L 5	10 · ft	WT 5 1.675·in	D ₁₅ = 30·in = WT ₅	1_5 .049087 $(D_0^4 - D_{15}^4)$	$I_5 = 0.394 \cdot ft^4$
L 6	10-ft	WT ₆ ≈ 1.375 in	D _{i6} 30·in WT ₆	$I_{6} = .049087 \cdot \left[D_{0}^{4} - D_{16}^{4} \right]$	$1_6 = 0.328 \cdot ft^4$
L 7	10∙ f t	WT 7 .875 in	D ₁₇ 30 in WT ₇	I ₇ .049087 D ₀ ⁴ D ₁₇ ⁴	$1_7 = 0.214 \cdot ft^4$
L 8	145 ft	WT 8 .5 in	D _{i8} - 30-in WT ₈	I ₈ .049087 D ₀ ⁴ D _{i8} ⁴	$I_8 = 0.125 \cdot ft^4$

Determine point of apparent fixity:

d $5 \cdot D_0$ d = 12.5 · ft

This point lies in depth 4

3) Determine caisson stiffness

 $L_{eff} = 36 \cdot ft + 12.5 \cdot ft \qquad L_{eff} = 48.5 \cdot ft \qquad 1_{av} = .049087 \cdot D_0^4 \qquad D_{i4}^4 \qquad 1_{av} = 0.41 \cdot ft^4$ $K = \frac{3 \cdot E \cdot I_{av}}{L_{eff}^3} \qquad K = 44.997 \cdot \frac{kips}{ft}$

4) Calculate the cantilever's weight for dynamics calculations

LI	75∙ft	WT 1	1.375-in	$D_{11} = 30 \cdot in$	WT 1	$\mathbf{A}_1 = \pi^{\mathbf{i}} \big(\mathbf{D}_0 \big)$	$w_{T_1} \cdot w_{T_1}$	$A_{1} = 0.859 \cdot ft^{2}$
L ₂ .	10∙ft	WT ₂	1.375-in	D _{i2} - 30·in	WT ₂	$A_2 = \pi \cdot (D_0)$	WT ₂ WT ₂	$A_2 = 0.859 \cdot ft^2$
L ₃	10∙ft	WT ₃	1.625·in	D _{i3} - 30·in -	WT 3	$A_3 = \pi \cdot \left\{ D_0 \right\}$	WT 3 WT 3	$A_3 = 1.006 \cdot ft^2$
L4	22.5∙ft	WT ₄	1.75·in	D _{j4} 30-in	WT ₄	$A_4 = \pi \cdot (D_0)$	WT ₄ WT ₄	$A_4 = 1.079 \cdot ft^2$

W₁ 490
$$\cdot \frac{lbf}{R^3} \cdot A_1 \cdot L_1$$
 W₁ = 31.557 $\cdot kips$
W₂ 490 $\cdot \frac{lbf}{R^3} \cdot A_2 \cdot L_2$ W₂ = 4.208 $\cdot kips$
W₃ 490 $\cdot \frac{lbf}{R^3} \cdot A_3 \cdot L_3$ W₃ = 4.929 $\cdot kips$
W₄ - 490 $\cdot \frac{lbf}{R^3} \cdot A_4 \cdot L_4$ W₄ = 11.891 $\cdot kips$

Inner casings:

$$W_{c1} = \pi \cdot (20 \cdot \text{in} - .44 \cdot \text{in}) \cdot .44 \cdot \text{in} \cdot (69 \cdot \text{ft} + 12.5 \cdot \text{ft}) \cdot 490 \cdot \frac{\text{lbf}}{\text{ft}^3}$$

$$W_{c2} = \left(68 \cdot \frac{\text{lbf}}{\text{ft}}\right) \cdot 81.5 \cdot \text{ft}$$

$$W_{c3} = \left(47 \cdot \frac{\text{lbf}}{\text{ft}}\right) \cdot 81.5 \cdot \text{ft}$$

$$W_{st} = W_1 + W_2 + W_3 + W_4 + W_{c1} + W_{c2} + W_{c3}$$

$$W_{st} = 69.455 \cdot \text{kips}$$

ł

W deck 15 kips W bl - 5 kips

Calculate added hydrodynamic mass:

.

.

$$\bigvee_{tot} \frac{(30 \cdot in)^2}{4} \cdot 36 \cdot ft \qquad W_H = 2 \cdot 64 \cdot \frac{lbf}{ft^3} \cdot V \qquad W_H = 22.619 \cdot kips \qquad [1]$$

$$W_{tot} = W_{st} - W_{deck} - W_{bl} \cdot W_H \qquad W_{tot} = 112.075 \cdot kips$$

$$M = \frac{W_{tot}}{32.2 \cdot \frac{ft}{sec^2}} \qquad M = 3.481 \cdot ft^{-1} \cdot sec^2 \cdot kips \qquad T_n = 2 \cdot \pi \cdot \frac{M}{K} \qquad T_n = 1.747 \cdot sec$$

These natural periods fall within the acceptable range of one to five seconds.

5) Determine caisson's ultimate elastic and plastic capacity Note: Steel is A36

$$S_{4} = .098175 \cdot \frac{D_{0}^{4} - D_{14}^{4}}{D_{0}} \qquad M_{el} = 36 \cdot \frac{kips}{in^{2}} \cdot S_{4} \qquad M_{el} = 2.039 \cdot 10^{4} \cdot kips \cdot in$$

$$F_{el} = \frac{M_{el}}{48.5 \cdot ft} \qquad F_{el} = 35.039 \cdot kips$$

$$Z = 1.27 \cdot S_{4} \qquad M_{plas} = 36 \cdot \frac{kips}{in^{2}} \cdot Z \qquad M_{plas} = 2.59 \cdot 10^{4} \cdot kips \cdot in$$

$$F_{plas} = \frac{M_{plas}}{48.5 \cdot ft} \qquad F_{plas} = 44.499 \cdot kips$$

6) Check for local buckling of the caisson.

 $\frac{D_{o}}{WT_{4}} = 17.143 \qquad F_{y} = 36 \qquad \frac{2070}{F_{y}} = 57.5 \qquad \frac{17.14 < 57.5}{\text{This section is not likely to buckle locally}}$

1

6) Calculate caisson's overload ratio (η)

۰.

F wave 40 kips	^F plas	40.8 kips	(This value was used in the analysis, instead of
η F _{wave} F _{plas}	η = 0.98		44 kips.)

This caisson is not overloaded by the maximum static wave force. This will prove significant in the dynamic analysis.

Caisson #2 South Timbalier 52

96" diameter caisson in 60 feet of water. Casings are not grouted. Ļ

1) Define geometry and constants for Mathcad
kips 1000 lbf E 29000
$$\cdot \frac{kips}{in^2}$$
 I .049087 $\cdot \left(D_0^{-4} - D_1^{-4} \right)$
A .785398 $\cdot \left(D_0^{-2} - D_1^{-2} \right)$
S .098175 $\cdot \left(\frac{D_0^{-4} - D_1^{-4}}{D_0} \right)$

2) Define caisson structural characteristics

L1	15.5∙ft	wт ₁	1.25∙in	D ₁₁ 72·in	wt 1	I ₁ = .049087 (D ₀ ⁴ - D ₁₁ ⁴)	$1_{1} = 4.304 \cdot ft^{4}$
L 2	9.5∙ft	wt ₂	1.25 · in	$D_{i2} = 72 \cdot in$	wr ₂	$I_2 = .049087 \cdot \left(D_0^4 - D_{12}^4 \right)$	$I_2 = 4.304 \cdot ft^4$
L 3	25∙ft	WT ₃	1.25 in	D _{i3} 84 in -	WT 3	I_3 .049087 D_0^4 D_{i3}^4	$1_3 = 6.86 \cdot ft^4$
L ₄	20∙ft	wt ₄	1.25 · in	D _{i4} 96 in	WT ₄	$l_4 = .049087 \cdot \left(D_0^4 + D_{14}^4 \right)$	$I_4 = 10.269 \cdot ft^4$
L 5	30•ft	WT 5 -	1.5 in	D ₁₅ 96.in	WT 5	$I_5 = .049087 \cdot (D_0^4 - D_{15}^4)$	$I_5 = 12.275 \cdot ft^4$
L ₆	25∙ft	wt ₆	1.25 in	D _{i6} = 96 · in -	WT ₆	$I_6 = .049087 \cdot \left(D_0^4 - D_{16}^4 \right)$	$1_6 = 10.269 \cdot ft^4$
L 7	5∙ft	WT 7	1.0·in	D ₁₇ = 96 in	WT 7	$1_7 = .049087 \cdot \left(D_0^4 - D_{17}^4 \right)$	$1_7 = 8.248 \cdot \text{ft}^4$
L 8 =	10∙ft	WT 8	.75·in	D ₁₈ 96-in	WT 8	I 8 .049087 (D 4 - D 18	$I_8 = 6.21 \cdot ft^4$
Lg.	20•ft	WT 9	.5-in	D _{i9} - 96∙in	WT 9	$1_9 = .049087 \cdot (D_0^4 - D_{i9}^4)$	$I_{9} = 4.156 \cdot ft^{4}$

Determine point of apparent fixity:

d $5 \cdot D_0$ d = 40 · ft

This point lies in depth 5

3) Determine caisson stiffness $L_{eff} = 60 \cdot ft - 40 \cdot ft$ $L_{eff} = 100 \cdot ft$ $I_{av} = .049087 \cdot \left(D_0^4 - D_{i4}^4\right)$ $I_{av} = 10.269 \cdot ft^4$ $K = \frac{3 \cdot E \cdot I_{av}}{L_{eff}^3}$ $K = 128.652 \cdot \frac{kips}{ft}$

4) Calculate the Cantilever's weight

Ll	105∙ft	WT 1	1.25 · in	D _{il}	72∙in	WT 1	Al	π· D 0	$WT_{1} : WT_{1}$	$A_1 = 1.929 \cdot ft^2$
L ₂	9.5·ft	WT ₂	1.25 · in	D _{i2}	72∙in	wt ₂	A 2 :	$\pi \cdot D_0$	WT 2 WT 2	$A_2 = 1.929 \cdot ft^2$
L 3	25∙ft	WT 3	1.25 · in	D _{i3}	84 in	WT ₃	Α3-	$\pi \cdot D_0$	WT 3 WT 3	$A_3 = 2.257 \cdot ft^2$
L 4	20∙ft	WT ₄	1.25 · in	D _{i4} -	96 in -	WT ₄	Α4	$\pi \cdot D_0$	WT 4 - WT 4	$A_4 = 2.584 \cdot ft^2$
L 5	30∙ft	wт ₅	1.5∙in	D _{i5}	96∙in	WT 5	Α5	p D _o	WT ₅ WT ₅	$A_5 = 3.093 \cdot ft^2$

W 1 490.
$$\frac{lbf}{h^3}$$
 · A 1 · L 1 W 1 = 99.268 · kips
W 2 490. $\frac{lbf}{h^3}$ · A 2 · L 2 W 2 = 8.981 · kips
W 3 490. $\frac{lbf}{h^3}$ · A 3 · L 3 W 3 = 27.644 · kips
W 4 490. $\frac{lbf}{h^3}$ · A 4 · L 4 W 4 = 25.322 · kips
W 5 490. $\frac{lbf}{h^3}$ · A 5 · L 5 W 5 = 45.46 · kips

Inner casings:

$$W_{c1} = \pi \cdot (30 \cdot in - .4 \cdot in) \cdot .4 \cdot in \cdot (129.5 \cdot ft) \cdot 490 \cdot \frac{lbf}{ft^3}$$
$$W_{c2} = \pi \cdot (22 \cdot in - .25 \cdot in) \cdot .25 \cdot in \cdot (129.5 \cdot ft) \cdot 490 \cdot \frac{lbf}{ft^3}$$
$$W_{c3} = \pi \cdot (20 \cdot in - 1 \cdot in) \cdot 1 \cdot in \cdot (129.5 \cdot ft) \cdot 490 \cdot \frac{lbf}{ft^3}$$

$$W_{deck}$$
 50 kips
 W_{st}
 W_{1}
 W_{2}
 W_{3}
 W_{4}
 3^{-1}
 W_{c1}
 W_{c2}
 W_{c3}
 W_{b1}
 7 kips
 W_{st}
 = 311.881 kips

-- -

.

Ļ

Calculate added hydrodynamic mass: $(06 in)^2$

$$V = \pi \cdot \frac{(96 \cdot in)^2}{4} \cdot 60 \cdot ft \qquad W_H = 2 \cdot 64 \cdot \frac{lbf}{ft^3} \cdot V \qquad W_H = 386.039 \cdot kips \qquad [1]$$

$$W_{tot} = W_{st} + W_{deck} + W_{bl} + W_H \qquad W_{tot} = 754.919 \cdot kips$$

$$M = \frac{W_{tot}}{32.2 \cdot \frac{ft}{sec^2}} \qquad M = 23.445 \cdot ft^{-1} \cdot sec^2 \cdot kips \qquad T_n = 2 \cdot \pi \cdot \frac{M}{K} \qquad T_n = 2.682 \cdot sec$$

These natural periods fall within the acceptable range of one to five seconds.

5) Determine caisson's ultimate elastic and plastic capacity Note: Steel is Grade 50

 $S_{5} = .098175 \cdot \left(\frac{D_{0}^{4} - D_{15}^{4}}{D_{0}}\right) \qquad M_{el} = 50 \cdot \frac{kips}{in^{2}} \cdot S_{5} \qquad M_{el} = 2.651 \cdot 10^{5} \cdot kips \cdot in$ $F_{el} = \frac{M_{el}}{100 \cdot ft} \qquad F_{el} = 220.949 \cdot kips$ $Z = 1.27 \cdot S_{5} \qquad M_{plas} = 50 \cdot \frac{kips}{in^{2}} \cdot Z \qquad M_{plas} = 3.367 \cdot 10^{5} \cdot kips \cdot in$ $F_{plas} = \frac{M_{plas}}{100 \cdot ft} \qquad F_{plas} = 280.605 \cdot kips$

ł

6) Check for local buckling of the caisson.

 $\frac{D_{o}}{WT_{5}} = 64 \qquad F_{y} = 50 \quad \frac{2070}{F_{y}} = 41.4 \qquad \begin{array}{c} 64 > 41.4 \\ \text{This section has the possibility to buckle} \\ \text{locally} \\ \text{[AISCC-LRFD]} \end{array}$

6) Calculate caisson's overload ratio (η)

F wave 130 kips F plas 221 kips

$$\eta = \frac{F_{wave}}{F_{plas}} \qquad \eta = 0.588$$

This caisson is not overloaded by the maximum static wave force.

Caisson #3 Ship Shoal 113

48" diameter caisson in 46 feet of water. Casings are not grouted. I

1) Define geometry and constants for Mathcad Casings
kips = 1000·lbf
$$E = 29000 \cdot \frac{kips}{in^2}$$
 $1 = .049087 \cdot \left(D_0^4 - D_i^4 \right)$
A .785398 $\cdot \left(D_0^2 - D_i^2 \right)$
S .098175 $\cdot \left(\frac{D_0^4 - D_i^4}{D_0} \right)$

2) Define caisson structural characteristics

$L_1 = 21 \cdot ft$	WT ₁ .75∙in	$D_{11} = 48 \text{ in } WT_1$	l ₁ 049087 · D ₀ ⁴ - D ₁₁ ⁴	$I_1 = 0.767 \cdot ft^4$
L ₂ 10-ft	WT ₂ = 1.25 in	D _{i2} 48·in - WT ₂	$I_2 = .049087 \cdot \left(D_0^4 - D_{12}^4 \right)$	$I_2 = 1.259 \cdot ft^4$
L ₃ 10∙ft	WT 3 = 1.5 in	D _{i3} = 48·in - WT ₃	$I_3 = .049087 \cdot \left(D_0^{-4} - D_{i3}^{-4} \right)$	$I_3 = 1.499 \cdot ft^4$
L ₄ = 45·ft	WT 4 1.75 in	D _{i4} 48 in WT ₄	$I_4 = .049087 \left(D_0^4 - D_{i4}^4 \right)$	$I_4 = 1.735 \cdot ft^4$
$L_5 = 10 \cdot ft$	WT 5 1.5 in	D ₁₅ 48 in WT ₅	$I_5 = .049087 \cdot (D_0^4 - D_{15}^4)$	$1_5 = 1.499 \cdot ft^4$
L ₆ 10∙ft	WT 6 - 1.25 in	D _{i6} 48 in WT ₆	$I_6 = .049087 \cdot \left(D_0^4 - D_{16}^4 \right)$	$I_6 = 1.259 \cdot ft^4$
L ₇ 5·ft	WT 7 1.0 in	D ₁₇ = 48 in = WT ₇	I ₇ .049087 D ₀ ⁴ D ₁₇ ⁴	$I_7 = 1.015 \cdot ft^4$
L ₈ 40 ft	WT 875 in	D _{i8} 48∙in WT ₈	I_8 .049087 D_0^4 D_{18}^4	$I_8 = 0.767 \cdot ft^4$

Determine point of apparent fixity:

d $5 \cdot D_0$ d = 20 \cdot ft

This point lies in depth 4

3) Determine caisson stiffness

$$L_{eff} = 46 \cdot ft = 20 \cdot ft \qquad L_{eff} = 66 \cdot ft \qquad I_{av} = .049087 \cdot D_{o}^{4} = D_{i5}^{4} = I_{av} = 1.499 \cdot ft^{4}$$

$$K = \frac{3 \cdot E \cdot I_{av}}{L_{eff}^{3}} \qquad K = 65.307 \cdot \frac{kips}{ft}$$

4) Calculate the Cantilever's weight

$$W_{1} = 490 \cdot \frac{lbf}{h^{3}} A_{1} \cdot L_{1} \qquad W_{1} = 40.914 \cdot kips$$

$$W_{2} = 490 \cdot \frac{lbf}{h^{3}} A_{2} \cdot L_{2} \qquad W_{2} = 6.247 \cdot kips$$

$$W_{3} = 490 \cdot \frac{lbf}{h^{3}} A_{3} \cdot L_{3} \qquad W_{3} = 7.456 \cdot kips$$

$$W_{4} = 490 \cdot \frac{lbf}{h^{3}} A_{3} \cdot L_{4} \qquad W_{4} = 21.631 \cdot kips$$
Inner casings:
$$W_{c1} = \pi \cdot (30 \cdot in - .44 \cdot in) \cdot .44 \cdot in \cdot (107 \cdot ft) \cdot 490 \cdot \frac{lbf}{h^{3}}$$

$$W_{c2} = 65 \cdot \frac{lbf}{ft} \cdot 107 \cdot ft$$

$$W_{c3} = (40 \cdot \frac{lbf}{h} \cdot 107 \cdot ft)$$

$$W_{c4} = 26 \cdot \frac{lbf}{h} \cdot 107 \cdot ft$$

$$W_{c4} = 20 \cdot kips \qquad W_{st} = W_{1} + W_{2} + W_{3} + W_{c1} + W_{c2} + W_{c3} + W_{c4}$$

$$W_{b1} = 5 \cdot kips \qquad W_{st} = 105.142 \cdot kips$$
Calculate added hydrodynamic mass:
$$W_{c1} = W_{c2} + W_{c3} + W_{c1} + W_{c2} + W_{c3} + W_{c4}$$

ł.

 $V = \pi \cdot \frac{(48 \cdot in)^2}{4} \cdot 46 \cdot ft \qquad W_H = 2 \cdot 64 \cdot \frac{lbf}{ft^3} \cdot V \qquad W_H = 73.991 \cdot kips \qquad [1]$ $W_{tot} = W_{st} \cdot W_{deck} = W_{bl} - W_H \qquad W_{tot} = 204.133 \cdot kips$ $M = \frac{W_{tot}}{32.2 \cdot \frac{ft}{sec^2}} \qquad M = 6.34 \cdot ft^{-1} \cdot sec^2 \cdot kips \qquad T_n = 2 \cdot \pi \cdot \frac{M}{K} \qquad T_n = 1.958 \cdot sec$

These natural periods fall within the acceptable range of one to five seconds.

4) Determine caisson's ultimate elastic and plastic capacity Note: Steel is Grade 36

$$S_{5} = .098175 \cdot \frac{D_{0}^{4} \cdot D_{14}^{4}}{D_{0}} \qquad M_{el} = 36 \cdot \frac{kips}{in^{2}} \cdot S_{5} \qquad M_{el} = 5.396 \cdot 10^{4} \cdot kips \cdot in$$

$$F_{el} = \frac{M_{el}}{66 \cdot ft} \qquad F_{el} = 68.13 \cdot kips$$

$$Z = 1.27 \cdot S_{5} \qquad M_{plas} = 36 \cdot \frac{kips}{in^{2}} \cdot Z \qquad M_{plas} = 6.853 \cdot 10^{4} \cdot kips \cdot in$$

$$F_{plas} = \frac{M_{plas}}{66 \cdot ft} \qquad F_{plas} = 86.525 \cdot kips$$

6) Check for local buckling of the caisson.

 $\frac{D_{o}}{WT_{4}} = 27.429 \qquad F_{y} \quad 36 \quad \frac{2070}{F_{y}} = 57.5 \qquad \frac{27.43 < 57.5}{\text{This section is not likely to buckle locally}} \\ \text{[AISCC-LRFD]}$

6) Calculate caisson's overload ratio (η)

 $F_{wave} = 50 \cdot kips$ $F_{plas} = 68.1 \cdot kips$ $68.1 \, kips$ was used in the analysis. $\eta = \frac{F_{wave}}{F_{plas}}$ $\eta = 0.734$

This caisson is not overloaded by the maximum static wave force. This will prove significant in the dynamic analysis.

function Cais1

global Tw kw H Cd Cm theta Cddeck wide wkf rho D I ld hs fy fr;

١.

psi=0.05; w=87.5; k=3; fr=40.8; fy=40.8; g=32.2*12; mu=1;hwave=[30]; cyc=[4]; Tw=8; D=30; rho=(64/32.2)*(1/(1000*144*144)); wavenum=length(hwave); cycnum=length(cyc); Cd=1.2; Cm=1.5; Cddeck=2.5; d=36*12; hs=32*12; wkf=0.88; wide=12*12; dt=Tw/100; L=g*Tw*Tw/(2*pi); m=w/g; wn=sqrt(k/m); c=2*m*wn*psi; kw=2*pi/L; for i=1:wavenum H=hwave(i)*12; for j=1:cycnum p=[zeros(1000,1)]; for ii=1:cyc(j)*100+1 theta=(2*pi/Tw)*((ii-1)*dt)+(pi/2); eta(ii)=(H/2)*cos(theta);if ((eta(ii)+d)<=hs) l=round(eta(ii)+d); p1=sum(PFD(0:1:1)); p2=sum(PFI(0:1:1)); p3=0; else

l=round(eta(ii)+d); p1=sum(PFD(0:1:1)); p2=sum(PFI(0:1:1)); ld=round((eta(ii)+d)-hs); if (ld>10*12) ld=10*12; disp('Deck Inundation') p3=sum(PFDdeck(0:1:1d)); else p3=0; end end

```
p(ii)=p1+p2+p3;
```

end time=[0:dt:(length(p)-1)*dt]; time1=[0:dt:(length(eta)-1)*dt];

figure(1)

clf

subplot(2,1,1) plot(time1,eta./12) xlabel('Time (sec)') ylabel('Surface Elevation (ft)')

subplot(2,1,2) plot(time,p) ylabel('Wave Force (kips)') xlabel('Time (sec)')

Deckmax=max(abs(p3)) pause

% figure(1)

% clf

% plot(eta)

```
% figure(2)
```

```
% clf
```

```
% plot(p)
```

disp('p assembled')

fy=40.8;

fr=40.8;

[u,f]=NNL1(m,c,k,fy,fr,p,dt);

epp(j,i)=max(abs(u));

- % figure(3)
- % clf
- % plot(u)
- % figure(4)
- % clf
- % plot(u,f)

disp('epp done')

% [u,f]=NNL1(m,c,k,sigmay,sigmar2,p,dt);

. .

- % deg(i,j)=max(abs(u));
- % figure(5)
- % clf
- % plot(u)
- % figure(6)
- % clf
- % plot(u,f)
- % disp('deg done')

end

end

time=[0:dt:(length(u)-1)*dt];

figure(2)

subplot(2,1,1) plot(time,u) xlabel('Time (sec)') ylabel('Deck Displ. (in)')

subplot(2,1,2) plot(u,f) ylabel('Force (kips)') xlabel('Deck Displ. (in)')

% mesh(hwave,cyc',epp./16);

% title('Ductility Demand on B/EPP Structure') % xlabel('Wave Height (ft)') % ylabel('Number of Waves') Į

function Cais2

global Tw kw H Cd Cm theta Cddeck wide wkf rho D l ld hs fy fr;

I,

psi=0.05; w=727; k=15.16; fr=221; fy=221; g=32.2*12; mu=1; hwave=[44]; cyc=[3]; Tw=10; D=72; rho=(64/32.2)*(1/(1000*144*144)); wavenum=length(hwave); cycnum=length(cyc); Cd=1.2; Cm=1.5; Cddeck=2.5; d=60*12; hs=56*12; wkf=0.88; wide=20*12; dt=Tw/100; L=g*Tw*Tw/(2*pi);m=w/g; wn=sqrt(k/m); c=2*m*wn*psi; kw=2*pi/L; for i=1:wavenum H=hwave(i)*12; for j=1:cycnum p=[zeros(1000,1)]; for ii=1:cyc(j)*100+1 theta=(2*pi/Tw)*((ii-1)*dt)+(pi/2);eta(ii)=(H/2)*cos(theta);if $((eta(ii)+d) \le hs)$ l=round(eta(ii)+d); p1=sum(PFD(0:1:1)); p2=sum(PFI(0:1:1)); p3=0; else

l=round(eta(ii)+d); p1=sum(PFD(0:1:1)); p2=sum(PFI(0:1:1)); Id=round((eta(ii)+d)-hs); if (ld>10*12) ld=10*12; p3=sum(PFDdeck(0:1:1d)); disp('Deck Inundation') else p3=0; end end

p(ii)=p1+p2+p3;

end time=[0:dt:(length(p)-1)*dt]; time1=[0:dt:(length(eta)-1)*dt];

figure(1)

clf

subplot(2,1,1) plot(time1,eta./12) xlabel('Time (sec)') ylabel('Surface Elevation (ft)')

subplot(2,1,2) plot(time,p) ylabel('Wave Force (kips)') xlabel('Time (sec)')

Deckmax=max(p3) pause

% figure(1)

% clf

% plot(eta)

% figure(2)

% clf

% plot(p)

disp('p assembled')

fy=221;

fr=221;

[u,f]=NNL2(m,c,k,fy,fr,p,dt);

% title('Ductility Demand on B/EPP Structure') % xlabel('Wave Height (ft)') % ylabel('Number of Waves') Ļ

epp(j,i)=max(abs(u));

I.

- % figure(3)
- % clf
- % plot(u)
- % figure(4)
- % clf
- % plot(u,f)

disp('epp done')

- % [u,f]=NNL2(m,c,k,sigmay,sigmar2,p,dt);
- % deg(i,j)=max(abs(u));
- % figure(5)
- % clf
- % plot(u)
- % figure(6)
- % clf
- % plot(u,f)
- % disp('deg done')

end

end

time=[0:dt:(length(u)-1)*dt];

figure(2)

subplot(2,1,1) plot(time,u) xlabel('Time (sec)') ylabel('Deck Displ. (in)')

subplot(2,1,2) plot(u,f) ylabel('Force (kips)') xlabel('Deck Displ. (in)')

% mesh(hwave,cyc',epp./16);

function Cais3

global Tw kw H Cd Cm theta Cddeck wide wkf rho D l ld hs fy fr;

. .

Ļ

psi=0.05; w=156.1; k=4; fr=68.1; fy=68.1; g=32.2*12; mu=1; hwave=[31.5]; cyc=[4]; Tw=8; D=48; rho=(64/32.2)*(1/(1000*144*144)); wavenum=length(hwave); cycnum=length(cyc); Cd=1.2; Cm=1.5; Cddeck=2.5; d=48*12; hs=44*12; wkf=0.88; wide=10*12; dt=Tw/100; L=g*Tw*Tw/(2*pi); m=w/g; wn=sqrt(k/m); c=2*m*wn*psi; kw=2*pi/L; for i=1:wavenum H=hwave(i)*12; for j=1:cycnum p=[zeros(1000,1)];for ii=1:cyc(j)*100+1 theta=(2*pi/Tw)*((ii-1)*dt)+(pi/2);eta(ii)=(H/2)*cos(theta);if ((eta(ii)+d)<=hs) l=round(eta(ii)+d); p1=sum(PFD(0:1:1)); p2=sum(PFI(0:1:1)); p3=0; else

```
l=round(eta(ii)+d);
p1=sum(PFD(0:1:1));
p2=sum(PFI(0:1:1));
ld=round((eta(ii)+d)-hs);
  if (ld>10*12) ld=10*12;
   p3=sum(PFDdeck(0:1:ld));
   end
   disp('Deck Inundation')
```

end

end

figure(1)

subplot(2,1,1)plot(time1,eta./12) xlabel('Time (sec)')

subplot(2,1,2)plot(time,p)

Deckmax=max(p3)

figure(1)

plot(eta)

figure(2)

clf

clf

plot(p)

fy=68.1;

fr=68.1;

disp('p assembled')

[u,f]=NNL3(m,c,k,fy,fr,p,dt);

epp(j,i)=max(abs(u));

pause

%

%

%

%

%

%

clf

p(ii)=p1+p2+p3;

time=[0:dt:(length(p)-1)*dt]; time1=[0:dt:(length(eta)-1)*dt];

ylabel('Surface Elevation (ft)')

ylabel('Wave Force (kips)') xlabel('Time (sec)')

Ţ

- % clf
- % plot(u)
- % figure(4)
- % clf
- % plot(u,f)

disp('epp done')

% [u,f]=NNL3(m,c,k,sigmay,sigmar2,p,dt);

Ļ

- % deg(i,j)=max(abs(u));
- % figure(5)
- % clf
- % plot(u)
- % figure(6)
- % clf
- % plot(u,f)
- % disp('deg done')

```
end
```

end

time=[0:dt:(length(u)-1)*dt];

figure(2)

subplot(2,1,1) plot(time,u) xlabel('Time (sec)') ylabel('Deck Displ. (in)')

```
% subplot(2,1,2)
% plot(u,f)
% ylabel('Force (kips)')
% xlabel('Deck Displ. (in)')
```

% mesh(hwave,cyc',epp./16); % title('Ductility Demand on B/EPP Structure') % xlabel('Wave Height (ft)') % ylabel('Number of Waves')

w.,

.