The fatigue crack growth of a ship steel in seawater under spectrum loading

Y.W. Cheng

Fatigue crack growth of ABS EH36 steel under spectrum loading intended to simulate sea loading of offshore structures in the North Sea was studied using fracture mechanics. A digital simulation technique was used to generate samples of load/time histories from a power spectrum characteristic of the North Sea environment. In constant load-amplitude tests, the effects of specimen orientation and stress ratio on fatigue crack growth rates were found to be negligible in the range $2 \times 10^{-3}$ to $10^{-3}$ mm/cycle. Fatigue crack growth rates in a 3.5% NaCl solution were two to five times faster than those observed in air in the stress intensity range 25 to 60 MPa$\sqrt{m}$. The average fatigue crack growth rates under spectrum loading and constant-amplitude loading were in excellent agreement when the fatigue crack growth rate was plotted as a function of the appropriately defined equivalent stress intensity range. This procedure is equivalent to applying Miner’s summation rule in fatigue life calculations.

Key words: fatigue; corrosion fatigue; fatigue crack growth; fracture mechanics; seawater environment; spectrum loading; ABS EH36 steel

In recent years the petroleum industry has built offshore drilling and production platforms in deeper waters and more hostile climates. As these offshore platforms encounter more severe weather and rougher seas, fatigue becomes a more important factor in the consideration of structural integrity. In treating the fatigue problem, it is usual to separate the fatigue life into two separate stages: crack initiation and crack growth. For welded structures, such as offshore platforms, crack initiation, during which microcracks form, grow and coalesce to become a macrocrack, is less important because fabrication imperfections are always present. The majority of the fatigue life is spent in the crack growth stage.

Analysis of fatigue crack growth under spectrum loading, which is usually irregular in nature, is complicated because of load-sequence interaction effects. A cycle-by-cycle approach, taking into account overload effects, has been used in the aerospace industry. Other empirical approaches, such as root mean square (RMS) or root mean cube (RMC), were also successfully used to correlate experimental results of spectrum loading of bridges with those of constant-amplitude loading. Use of the latter approaches is empirical and implementation of the former is time-consuming. A more efficient approach which has been proposed will be discussed later. This paper describes work carried out at the National Bureau of Standards over the past two years on the investigation of fatigue crack growth in ABS grade EH36 steel under simulated offshore platform service conditions.

Load spectrum

Service loads acting on offshore structures are random in nature. The main source of cyclic loading is wave action which excites a vibration at approximately the wave frequency. The magnitude of the vibration depends mainly on wave height and direction, size of component and its location in a structure. Besides vibration due to wave action, additional vibrations are induced from structural responses to the wave action. The magnitude and frequency of the structural resonance depend on local structural characteristics. Thus, the precise definition of load/time history is extremely complex and would be expected to vary between different locations on the same structure.

Because of complexity in and lack of information on the precise load/time history experienced by offshore structures, no standard load/time history is available (or exists) for purposes of analysis and experiment. Numerous load/time histories, including Rayleigh peak distribution, Gaussian peak distribution, Gassner blocked program and others, have been used to evaluate the fatigue performance of weldments. The load spectrum selected for the present investigation was realistic for offshore structures in North Sea environments, as shown in Fig. 1. The principal loads in this spectrum, those with a frequency of about 0.1 Hz, are due to wave action. The higher frequency (about 0.35 Hz) loads are due to the structural resonance.

![Characteristic power spectrum of offshore structures in the North Sea](Fig. 1)
Simulation of load/time histories

The power spectral density function, \( S(\omega) \), is not sufficient for experimental purposes; load/time history, \( X(t) \), has to be used. In this investigation, the following expression\textsuperscript{13,14} was used to reconstruct \( X(t) \) from \( S(\omega) \):

\[
X(t) = \sum_{k=1}^{J} [2G(\omega_k)\Delta\omega_k]^{1/2} \cos (\omega_k t + \Phi_k)
\]

(1)

where \( G(\omega) \), as shown in Fig. 1, is the one-sided power spectral density function in terms of frequency, \( \omega(G(\omega) = 2S(\omega) \) for \( \omega > 0 \). Frequency is defined over the interval [0, \( \omega_u \)] with partitions of length such that

\[
\omega_u = \sum_{k=1}^{J} \Delta\omega_k
\]

(2)

\( \Phi \) is a random phase angle uniformly distributed between 0 and \( 2\pi \). \( \omega_k \) is the midpoint of \( \Delta\omega_k \). The number of harmonic functions, \( J \), is arbitrary; in this investigation it was taken to be 50.

An undesired periodic \( X(t) \) with a short period occurs if the minimum common divider for all the \( \Delta\omega_k \) is large. This problem is avoided by using random intervals for \( \Delta\omega_k \). In this investigation, \( \Delta\omega_k \) was taken from a normal distribution with a mean equal to the average of \( \Delta\omega_k \) and a standard deviation equal to one-tenth of the average of \( \Delta\omega_k \).

A computer program written in Fortran IV has been developed to simulate \( X(t) \) using Equation (1). Newton’s method was then used to locate peaks and troughs with respect to time in the simulated load/time history.

Two load spectra were used in this study. One considers only the wave-loading portion of the power spectral density function with frequency up to 0.2 Hz (case I) as shown in Fig. 1. The other considers the whole curve (case II). Typical simulated load/time histories, \( X(t) \), from the power spectral density function are shown in Figs 2a and 2b.

Values of the irregularity factor (number of mean crossings/number of peaks plus troughs) calculated from the power spectra are 0.90 and 0.69 for cases I and II, respectively: they are 0.90 and 0.68, as determined from the simulated load/time histories. The excellent agreement between the values obtained from the power spectra and the simulated load/time histories indicates that use of Equation (1) is satisfactory. Values of the clipping ratio are 3.84 and 3.91 for cases I and II, respectively. The clipping ratio is defined as the ratio of the maximum load amplitude, which is the difference between the maximum peak and the mean load, to the RMS value of load amplitude.*

Table 1. Chemical composition of ABS EH36 steel (weight %)

<table>
<thead>
<tr>
<th>C</th>
<th>Mn</th>
<th>P</th>
<th>S</th>
<th>Si</th>
<th>Cu</th>
<th>Ni</th>
<th>Cr</th>
<th>Mo</th>
<th>Fe</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.12</td>
<td>1.39</td>
<td>0.015</td>
<td>0.006</td>
<td>0.380</td>
<td>0.05</td>
<td>0.03</td>
<td>0.05</td>
<td>0.007</td>
<td>Bal</td>
</tr>
</tbody>
</table>

*This should not be confused with the RMS value of load range which was used in Reference 3.

Experimental procedures

Test material and specimens

The test material was a 25.4 mm thick plate of ABS grade EH36 steel, a C–Mn steel of yield strength 350 MPa. The chemical composition is given in Table 1. The steel was in the normalized condition and had particularly uniform properties due to sulphide-shape control.

Fatigue crack growth rate (FCGR) tests under constant-amplitude loading and spectrum loading were conducted using standard (25.4 mm thick) and modified\textsuperscript{15} compact specimens. The modified compact specimen was a lengthened and side-grooved (with a net thickness of 3.18 mm) version of the standard compact specimen. The deep side grooves determine the plane of crack growth and provide a strip of material that undergoes large cyclic plasticity during fatigue. Specimens were in LT and TL orientations.

Test apparatus and environment

FCGR tests were conducted with a fully automated test system, which was described in a previous paper.\textsuperscript{16} Briefly, the test system consists of a closed-loop, servo-controlled, hydraulic mechanical test machine, a programmable digital
oscilloscope serving as an analogue-to-digital converter, a programmable arbitrary waveform generator and a minicomputer.

Tests were performed in laboratory air and in 3.5% NaCl solution with a free corroding condition (no cathodic protection). Crack lengths were measured by the compliance technique. The crack-length measurement technique is accurate to at least 0.1 mm. In the saltwater tests, the clip-gauge used for displacement measurements was mounted on a scissors-like extension to avoid immersion in the saltwater. The environmental chamber was a 191 capacity plastic container. The saltwater was continuously circulated at a rate of 26 l/min through a diatomaceous-earth filter. The NaCl concentration, the temperature, and the pH of the saltwater was monitored periodically.

**Loading conditions**

In the constant load-amplitude tests, the stress ratio, \( R \) (ie the ratio of minimum to maximum stress), was kept constant at 0.1 or 0.5. Tests in air were conducted at 10 Hz and tests in 3.5% NaCl solution were conducted at 0.1 Hz. A sinusoidal load/time history was used.

In the spectrum-loading tests, the simulated load/time histories were recorded on floppy discs, which were read by a minicomputer. The minicomputer then sent the signals to the hydraulic mechanical test machine through a programmable arbitrary waveform generator. The loads were periodically monitored with an oscilloscope by comparing the input values to the hydraulic mechanical test machine and the output values from the load cell. The input and output values must agree with each other during the test. No modifications, such as truncation, on the simulated load/time histories were done, except on the levels of mean loads. The mean loads were increased so that the minimum loads were slightly above zero. This was done because the apparatus was limited to tension-tension loading. The stress ratio, therefore, varied from about 0 (usually for large load ranges) to about 1 (usually for very small load ranges).

Because of the limited capacity of the floppy disc, the total recorded lengths of load/time histories were 18.0 h for case I and 9.3 h for case II. The recorded lengths correspond to return periods of 15 773 and 11 890 mean-load crossings for cases I and II, respectively. The wave shape was triangular. It has been shown\(^\text{17}\) that there are no differences in FCGR between tests conducted with sinusoidal and triangular waveforms. Both tests in air and in saltwater were conducted at ambient temperature.

**Results and discussion**

**Constant-amplitude tests**

Fatigue crack growth rates were calculated using the linear-elastic fracture mechanics approach; the experimental results are shown in Figs 3–5. As shown in Fig. 3, specimen orientation (TL or LT) had little influence on the FCGR in air and in saltwater. The FCGR in air and in saltwater for the two stress ratios may be compared in Figs 3 and 4. For a stress intensity range, \( \Delta K \), between 30 and 40 MPa \( \sqrt{m} \), the growth rates in saltwater were up to five times faster than those in air. Plotting all the results together (Fig. 5) shows the stress ratio to have a small influence on the FCGR in air. Below \( 4 \times 10^{-5} \) mm/cycle the FCGR in air and in saltwater were about the same.
Fatigue crack growth rates under spectrum loading were analysed using the equivalent stress range approach. For simplicity, the Paris equation, $da/dN = C(\Delta K)^n$, is used for discussion. Here, $da/dN$ is the crack growth increment per load cycle and $C$ and $n$ are constants. $\Delta K$ is defined as:

$$\Delta K = b(\pi a)^{1/2} Y$$

where $b$ is the stress range, $a$ is the crack length and $Y$ is a geometry factor. If $da/dN \ll a$, and there are no load-sequence interaction effects, then:

$$\Delta a_1 = C b_1^1 [(\pi a)^{1/2} Y]^n$$

$$\Delta a_2 = C b_2^1 [(\pi a)^{1/2} Y]^n$$

$$\Delta a_N = C b_N^1 [(\pi a)^{1/2} Y]^n$$

Summing Equations (4)–(6) gives:

$$(\Delta a_1 + \Delta a_2 + \cdots + \Delta a_N)$$

$$= C(b_1^1 + b_2^1 + \cdots + b_N^1) [(\pi a)^{1/2} Y]^n$$

The left-hand side of Equation (7) is the increment of crack growth in $N$ successive cycles; the average FCGR per cycle is then:

$$da/dN = \frac{C(b_1^1 + b_2^1 + \cdots + b_N^1)}{N} [(\pi a)^{1/2} Y]^n$$

$$= C [b_{eq} (\pi a)^{1/2} Y]^n$$

Here $N$ should be large so that the equivalent stress range, $b_{eq}$, is representative of a load spectrum. The definitions of stress range and cycle used in this investigation are given in Fig. 6. The value of $n$ in the test in 3.5% NaCl saltwater obtained from constant-amplitude loading and spectrum loading (case I)


10. Lieurade, H. P., Gerald, J. P. and Putot, C. J. 'Fatigue life prediction of tubular joints' Proc Offshore Technology Conf, Houston, TX, USA, May 1980 OTC paper 3699


Authors

Dr Cheng is with the Fracture and Deformation Division, United States Department of Commerce, National Bureau of Standards, 325 Broadway, Boulder, CO 80303, USA.