# ASSESSMENT OF DRILLING & WORKOVER RIG STORM SEA FASTENINGS ON OFFSHORE FLOATING PLATFORMS DURING HURRICANE IVAN

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**PHASE 1: Analysis Report** 

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# **Table of Contents**

Table of Contents	i
List of Tables and Figures	ii
Executive Summary	1
Introduction	2
Hurricane Environment	3
Wind Forces on the Drilling Rig & Substructure	4
Hull Accelerations	6
Derrick and Substructure Accelerations	7
Loads on the Footings for the Derrick and Substructure Clamps	7
Clamps	
Clamp Capacity vs. Environmental Loads	
Approximate Estimates of Acceleration (API 4F)	
Discussion	
Conclusions & Recommendations	
Hull Accelerations	
Acknowledgements	
References	

# List of Tables and Figures

# Tables

Table 1. Hurricane Environmental Conditions	4
Table 2. Wind Force Parameters	5
Table 3. Wind Forces on Derrick	6
Table 4. Maximum Hull Accelerations	6
Table 5. Vertical Locations of Centers of Gravity	7
Table 6. Max. Total Accelerations at the Derrick and Substructure CGs	7
Table 7. TLP Derrick Footing Loads & Moments	
Table 8. TLP Substructure Footing Loads & Moments	9
Table 9. Spar Derrick Footing Loads & Moments	9
Table 10. Spar Substructure Footing Load & Moments	9
Table 11. TLP Results - Clamp Capacity/Max Load for Failure Mode, Environment, and L	ocation
	14
Table 12. Spar Results - Clamp Capacity/Max Load for Failure Mode, Environment, and L	ocation
	15
Table 13. Comparison of Max. Total Accelerations at the Derrick and Substructure CGs as	
Calculated from the Time Series Analyses and API 4F Methodology	

# Figures

Figure 1. Drilling Rig, Substructure, and Tie-Down Clamps	3
Figure 2. Drilling Rig and Substructure	4
Figure 3. Upper Derrick & Substructure Footings (Plan View)	5
Figure 4. TLP Derrick Global Moments vs. Max Uplift Force at Footing for Derrick Clamp (Ca	ılm,
10 yr, 100 yr, Ivan )	10
Figure 5. TLP Derrick + Substructure Global Moments vs. Max Uplift Force at Footing for	
Substructure Clamp (Calm, 10 yr, 100 yr, Ivan )	11
Figure 6. Spar Derrick Global Moments vs. Max Uplift Force at Footing for Derrick Clamp (Ca	ılm,
10 yr, 100 yr, Ivan )	11
Figure 7. Spar Derrick + Substructure Global Moments vs. Max Uplift Force at Footing for	
Substructure Clamp (Calm, 10 yr, 100 yr, Ivan )	12
Figure 8. Bolted clamp configuration	13
Figure 9. TLP in 100-year Hurricane Conditions: Clamp Capacity vs. Max Load for Tie-Down	
Clamps for Derrick and Substructure	16
Figure 10. TLP in Hurricane Ivan Conditions: Clamp Capacity vs. Max Load for	16
Tie-Down Clamps for Derrick and Substructure	16
Figure 11. Spar in 100-year Hurricane Conditions: Clamp Capacity vs. Max Load for Tie-Down	n
Clamps for Derrick and Substructure	17
Figure 12. Spar in Hurricane Ivan Conditions: Clamp Capacity vs. Max Load for	17
Tie-Down Clamps for Derrick and Substructure	17

# ASSESSMENT OF DRILLING & WORKOVER RIG STORM SEA FASTENINGS ON OFFSHORE FLOATING PLATFORMS DURING HURRICANE IVAN PHASE 1: Analysis Report by E.G. Ward and M. H. Kim (OTRC) And J.M. Gebara and N. Ghoneim(Technip)

#### **Executive Summary**

Drilling and workover rigs on Floating Production Systems (FPS's) are fastened to the decks of offshore structures sea fastenings to prevent movement during hurricanes. Tie-down systems include bolted clamps, weldments, or other mechanical means. During Hurricane Ivan, a number of drilling or workover rigs shifted. These movements were studied and assessed relative to current design philosophy and installation practices, and onboard storm operational practices to ready FPS's for a hurricane. Results will provide information that can be used to assess any needs to revise tie-down criteria or practices to avoid future damage.

Information was gathered for the FPS's with rig movement during Ivan. Information was obtained for Horn Mountain (BP), Medusa (Murphy), and Ram Powell (Shell). No information was obtained for Devils Tower (Dominion). An interim report to MMS and an OTC paper summarized the observations and learnings from these rig movements. We were also able to work with the API's Hurricane Evaluation & Assessment Team (HEAT) and provide input to API Bulletin 2TD, Guidelines for Tie-Downs on Offshore Production Facilities for Hurricane Season, First Edition that was issued in June 2006.

This report describes the analyses for a hypothetical TLP and Spar to further study the loads and failure modes for rig tie-down clamps for drilling rigs during hurricanes. Results tended to confirm the observation from hurricane Ivan, and illustrate that tie-down clamps should be purpose-designed for the functional requirements and motion characteristics the specific FPS.

#### Introduction

The initial goal for the analysis was to gather sufficient information and data regarding one of the sea fastening failures that occurred during hurricane Ivan and analyze that case to better understand the likely cause of the failure. As discussed in references 1 and 2, there were three cases in which sea fastenings failed to prevent a drilling rig from moving during hurricane Ivan. However, we were not able to gather sufficient data for the specific facilities to allow a detailed forensic study of any of these cases.

Instead, we chose to study two hypothetical structures, a TLP and a Truss Spar during several hurricane environmental conditions. The analyses were used as the basis for studying the loads and failure modes for rig tie-down clamps. The study used a typical clamp design and did not attempt to design a clamp for the specific location or FPS type.

The TLP, Spar, and the drilling rig analyzed were not actual designs, but represented realistic examples of FPS's and a drilling rig. The global loads and deck motions of the FPS's and the wind loads and motions of the drilling rig and its substructure were simulated for hurricane wind, wave, and current environments that represented 10-year and 100-year return period and maximum conditions near the eye during hurricane Ivan. These motions and loads were used to estimate the maximum forces and moments at the locations where tie-down clamps secure (1) the derrick and drill floor to the substructure, and (2) the substructure to the deck. See Figure 1.

A set of tie-down clamps were selected to investigate failure of simple bolted clamps. Three failure modes were considered: (1) slip, (2) bolt failure in tension, and (3) bolt failure in shear. The capacities of the clamps to resist the hurricane forces and loads were computed for several coefficients of friction and bolt pre-tensions, and were compared to the simulated hurricane loads. The same clamps were used for the TLP and the Spar, and at both elevations on each FPS. Results provided a basis for examining and comparing the loads and different failure modes of the clamps. The clamps selected were based on typical designs observed during our visits to four offshore facilities and discussions with operators.



Figure 1. Drilling Rig, Substructure, and Tie-Down Clamps

Appendices A and B contain details of the analyses.

Appendix A (Assessment of the Performance of Tie-Down Clamps for a Drilling Rig on a Spar in Severe Hurricane Environments by J. Gebara and N. Ghoneim of Technip Offshore Inc. focuses on the motions of the spar, wind loads on the derrick, and provides details regarding the clamp design, failure modes, and performance.

Appendix B (Assessment of the Performance of Tie-Down Clamps for a Drilling Rig on a TLP in Severe Hurricane Environments by M.H. Kim and C.K. Yang of Texas A&M University, Civil Engineering Department focuses on the analysis of the TLP motions, wind loads on the derrick, and performance of the clamps.

#### **Hurricane Environment**

The table below summarizes the environmental conditions used in this study. Winds, waves and currents representing 10-year and 100-year hurricane conditions and maximum conditions near the eye of hurricane Ivan are shown in Table 1 below. The JONSWAP spectrum was used to simulate long crested irregular wave generation with the given stiffness parameter. Time varying wind speeds were simulated using the API spectrum. The wind and the current speeds are those associated with and colinear with maximum wave condition.

Return Period	10 y	/ear	100	year	Ivan		
Hs (ft)	24	.9	40	0.0	51.1		
Tp (sec)	11	.9	14	4.0	1:	5.6	
γ*	2.	.4	2	.4	3	.0	
Wind Speed**(kts)	50	).9	81	1.3	8	7.9	
Current Profile	Depth (ft)	Speed (ft/s)	Depth (ft)	Speed (ft/s)	Depth (ft)	Speed (ft/s)	
	0	2.59	0.0	4.9	0	8.2	
	98	1.97	98	3.8	16	8.2	
	197	0.95	197	1.8	82	3.9	
	295	0.33	2957	0.3	164	3.7	
	3000	0.33	3000	0.3	264	2.4	
					328	1.0	
					492	1.0	
					984	0.9	
					3000	0.0	

 Table 1. Hurricane Environmental Conditions

\* JONSWAP spectrum is used for the irregular wave generation with the given  $\gamma$ .

\*\* The wind speed is 1 hour averaged at 10m above MWL, and API wind spectrum is used for the time varying wind speed generation.

#### Wind Forces on the Drilling Rig & Substructure

The derrick and the substructure are schematically shown in Figure 2 and 3 below.



Figure 2. Drilling Rig and Substructure



Figure 3. Upper Derrick & Substructure Footings (Plan View)

Select parameters involved used in calculating the wind forces are shown in Table 2.

Parameter	Derrick	Substructure	Total
Weight (kips)	550	1500	2050
Projected Area (ft^2)	2940	500	3440
Center of Pressure from MWL (ft)	201	130	190
Center of Gravity from MWL (ft)	169	130	140.5
Height Coefficient( $C_h$ )*	1.37	1.19	1.24
Shape Coefficient( $C_s$ )*	1.25	1.25	1.25

**Table 2. Wind Force Parameters** 

Wind forces on the derrick were computed following the recommendations in API 4F. The derrick was assumed to be rigid. The projected area was based on the exposed areas of the two opposite sides of the derrick. Forces at the center of pressure were computed for wind velocities corresponding to 10-year, 100-year, and Ivan conditions. Forces were computed for the winds aligned with the X axis, the Y axis, and at an angle of 45 degrees. The area used for the force in the 45 degree direction was the square root of the sum of the squares of the areas projected areas in the X and Y directions.

The resulting wind loads on the derrick are shown in Table 3.

Tuble 5. Which of ees on Derriek												
Environment	Velocity (kts)	X & Y Wind Force (kips)	45 Degree Wind Force (kips)									
10-year	51	44	62									
100-year	81	112	158									
Ivan	88	131	185									
API 4F	107	195	276									

Table 3. Wind Forces on Derrick

Wind speed measurements near the eye during Ivan are not available, but hindcasts values were 89 knots (1hour average, 10 m elevation). The API 4F wind force of 107 knots is shown for illustrative purposes only, and was not used in our final assessment of the performance of tie-down clamps in this study. Note that the 107 kt wind speed resulted in a wind force on the derrick that was 50 percent greater that the maximum wind speed in Ivan.

#### **Hull Accelerations**

The TLP and the Spar were analyzed to describe the global motions for each environmental condition (see Appendices A and B for details). Due to the symmetry of the TLP and Spar, the motions in the X and Y directions were equal. The hull accelerations were used to determine the inertial loads of the derrick and substructure.

The maximum accelerations at the hull center-of-gravity (CG) in the X and Y directions are shown in Table 4 below.

Environment	Motion	Accelerations @ Hull CG (accel/g)			
		TLP	Spar		
	Horizontal	0.109	0.083		
10-year	Rotational	0.004	0.007		
	Heel (static)	0.001	0.056		
	Horizontal	0.173	0.124		
100-year	Rotational	0.005	0.010		
	Heel (static)	0.002	0.146		
	Horizontal	0.220	0.154		
Ivan	Rotational	0.006	0.013		
	Heel (static)	0.003	0.187		

Table 4. Maximum Hull Accelerations

Note the differences in the accelerations for the TLP and the Spar hull CGs. The TLP has larger horizontal accelerations, whereas the Spar has larger rotational and heel accelerations.

#### **Derrick and Substructure Accelerations**

The accelerations at the CGs of the derrick and substructure are needed to compute the inertial loads of the derrick and substructure on their footings so that the forces on the clamps can be determined. The accelerations at the derrick and substructure CGs were calculated from the hull CG accelerations and the vertical distances from the hull CG to the derrick and substructure CGs (see Figure x above) as shown in the Table 5 below.

Table .	. Vertical Loc	anons of Cent	15 01 Oravity
FPS	CG relative to MWL	CG relative	to Hull CG
	Hull	Derrick	Substructure
TLP	28	141	102
Spar	-177	346	307

 Table 5. Vertical Locations of Centers of Gravity

The maximum total acceleration at the CGs of the derrick and substructure are shown in Table 6 below. Again note the differences in the accelerations for the TLP and the Spar.

Environment	Max. Acceler Derri (acc	Total ations @ ck CG cel/g)	Max. Accelera Substruc (acc	Total ations @ cture CG el/g)
	TLP	Spar	TLP	Spar
10-year	0.130	0.223	0.125	0.207
100-year	0.200	0.200 0.417		0.378
Ivan	0.253	0.503	0.246	0.490

 Table 6. Max. Total Accelerations at the Derrick and Substructure CGs

These differences in accelerations need to be recognized in designing or evaluating tie-down systems for drilling rigs and other equipment placed on the decks.

#### Loads on the Footings for the Derrick and Substructure Clamps

The maximum loads on the footings were determined by combining the gravity, inertial, wind, and static loads for the derrick and substructure.

The derrick and substructure were modeled as rigid structures. The maximum inertial loads for the derrick and substructures were determined a bit differently for the TLP and the Spar. For the TLP, the inertial loads of the derrick and substructure were simulated in a random time series analysis

that included all the acceleration components at their respective phases, and the maximum inertial forces were determined directly. For the Spar, instantaneous values ('snapshots") were determined for the (1) maximum lateral and associated vertical acceleration, (2) maximum positive vertical and the associated lateral acceleration, and (3) maximum negative vertical and the associated lateral acceleration. The method used for the TLP is a more direct approach to determine the maximum forces, but the differences were checked and determined not to be important for this study.

Loads and moments on the footings were computed using the inertial loads in the X and Y directions and wind loads on the derrick and substructure from the X, Y, and 45 degree directions (see Figure 3). Forces at the footings were analyzed assuming both pinned and fixed connections. There was a small difference which was judged to be unimportant given the assumptions in this study. However for detailed design studies, the difference between pinned and fixed footings should be assessed on a case by case basis.

The maximum uplift loads and global moments (acceleration and wind components and the total) on the footings are shown in Tables 7 - 10 below.

Environment	Max per C	UPLIFT I lamp Fo (kips)	Load oting		G	ilobal Mo	ments At I	Derrick Fo	otings Le	evel (kip-ft	)	
						Load	I Directior	า				
	Х	Y	45°		Х			Y			45°	
		Fz		$\mathbf{M}_{accel}$	M <sub>wind</sub>	M <sub>T</sub> *	M <sub>accel</sub>	M <sub>wind</sub>	M <sub>T</sub> *	Maccel	$\mathbf{M}_{wind}$	M <sub>T</sub> *
Calm	-138	6 (dead lo	bad)					0				
10-Year	-48	-48	38	1898	1212	3110	1898	1212	3110	2683	1715	4398
100-Year	42	42	216	2530 3093 5623 2530 3093 5623 3578 4374 795						7952		
Ivan	79	79	290	3289	3616	6905	3289	3616	6905	4651	5114	9765

Table 7. TLP Derrick Footing Loads & Moments

Environment	Max UPLIFT Load per Clamp Footing (kips)			Global Moments At Derrick Footings Level (kip-ft)								
						Load	I Direction	n				
	Х	Y	45°		х			Y			45°	
		Fz		Maccel	$\mathbf{M}_{wind}$	<b>М</b> т*	M <sub>accel</sub>	$\mathbf{M}_{wind}$	<b>М</b> т*	M <sub>accel</sub>	$\mathbf{M}_{wind}$	M <sub>T</sub> *
											•	•
Calm	-513	8 (dead lo	oad)					0				
10-Year	-274	-380	-147	7523	1966	9488	7523	1966	9488	10638	2780	13418
100-Year	-92	-270	131	10030         5015         15045         10030         5015         15045         14185         7092         21277						21277		
Ivan	7	-210	282	13039	5862	18901	13039	5862	18901	18440	8291	26730

# Table 8. TLP Substructure Footing Loads & Moments

# Table 9. Spar Derrick Footing Loads & Moments

Environment	Max per C	UPLIFT lamp Fo (kips)	Load ooting	Global Moments At Derrick Footings Level (kip-ft)								
		Load Direction										
	Х	Y	45°		Х			Y			45°	
		Fz		M <sub>accel</sub>	$\mathbf{M}_{wind}$	M⊤*	M <sub>accel</sub>	$\mathbf{M}_{wind}$	<b>М</b> т*	Maccel	M <sub>wind</sub>	<b>М</b> т*
Calm	-138	3 (dead lo	oad)					0				
10-Year	-34	-34	69	2732	1212	3945	2732	1212	3945	3864	1715	5579
100-Year	86	86	308	4971	3093	8065	4971	3093	8065	7031	4374	11405
Ivan	137	137	410	6426	3616	10042	6426	3616	10042	9088	5114	14202

## Table 10. Spar Substructure Footing Load & Moments

Environment	Max per C	UPLIFT lamp Fo (kips)	Load oting	Global Moments At Derrick Footings Level (kip-ft)								
						Load	I Direction	n				
	Х	Y	45°		х	Y				45°		
		Fz		M <sub>accel</sub>	$\mathbf{M}_{wind}$	<b>М</b> т*	M <sub>accel</sub>	$\mathbf{M}_{wind}$	M <sub>T</sub> *	Maccel	$\mathbf{M}_{wind}$	<b>М</b> т*
Calm	-513	8 (dead lo	oad)					0				
10-Year	-220	-349	-58	10643	1966	12609	10643	1966	12609	15052	2780	17832
100-Year	76	-184	403	19394	5015	24408	19394	5015	24408	27427	7092	34519
Ivan	230	-133	639	25098	5862	30960	25098	5862	30960	35494	8291	43785

The maximum uplift forces  $F_Z$  and total moments  $M_T$  are also shown graphically in Figures 4 – 7 in terms of increasing loads and moments, values are shown for calm, 10-year, 100-year, and Ivan hurricane conditions.

The forces FZ for the "calm" cases are the dead load due only to the weight of the derrick or the derrick plus the substructure, and the corresponding moments are zero. The forces and moments increase with increasingly severe environment as indicated by the increasing total moment  $M_T$ , and the derrick would begin to tip (if not restrained by the clamp) when the maximum uplift force becomes positive.

The maximum uplift forces  $F_Z$  and total moment  $M_T$  for the derrick footings are the same in the X and Y directions since the derrick footings are in a square pattern. The uplift forces  $F_Z$  for the derrick and substructure are larger for the Y direction because of the larger spacing between footings in the Y direction than the X direction for the substructure footings.

The uplift force  $F_Z$  and total moment  $M_T$  in the 45 degree directions is larger than in either X or Y directions in a given environments because of the larger wind force in the 45 degree direction.



Derrick Global Moments (M<sub>T</sub>) (kip-ft)

Figure 4. TLP Derrick Global Moments vs. Max Uplift Force at Footing for Derrick Clamp (Calm, 10 yr, 100 yr, Ivan )



Figure 5. TLP Derrick + Substructure Global Moments vs. Max Uplift Force at Footing for Substructure Clamp (Calm, 10 yr, 100 yr, Ivan )



Derrick Global Moment (M<sub>T</sub>) (kip-ft)

Figure 6. Spar Derrick Global Moments vs. Max Uplift Force at Footing for Derrick Clamp (Calm, 10 yr, 100 yr, Ivan )



Figure 7. Spar Derrick + Substructure Global Moments vs. Max Uplift Force at Footing for Substructure Clamp (Calm, 10 yr, 100 yr, Ivan )

#### Clamps

A simple tie-down clamp was "configured" to investigate failure of clamps. There was no intent to do a detailed design or optimize the clamp for motions of either the TLP or the Spar. The same clamps were used for the TLP and the Spar, and at both elevations, i.e. the derrick-substructure interface and at the substructure-deck interface. The clamp configuration is shown in Figure 8 below.



Figure 8. Bolted clamp configuration

#### **Clamp Capacity vs. Environmental Loads**

Three failure modes were considered: (1) slip, (2) bolt failure in tension, and (3) bolt failure in shear. The capacities of the clamps were computed for three coefficients of friction (0.1, 0.3, and 0.5) and four bolt pre-tensions (75, 137.5, 150, and 225 kips). These capacities were compared to the maximum loads and moments for each hurricane environment and load direction. A Clamp Capacity / Max Load ratio of less than 1 indicates that the configured clamp capacity is exceeded for that failure mode. Note there were no instances where the clamp capacity was exceeded due to bolt shear. This does not imply that this failure mode is not possible, but it is only an indication that the capacity was not exceeded for the particular clamp used.

Values for the ratios of Clamp Capacity / Max Loads for all three failure modes are shown in Table 11 for the TLP and Table 12 for the Spar for 10-year, 100-year, and hurricane Ivan conditions.

Figures 9 and 10 show plots of the ratios of Clamp Capacity / Max Load for the Slip and Tensile Bolt Failure modes for the TLP derrick and substructure clamps in 100-year, and hurricane Ivan conditions. Figures 11 and 12 show similar plots for the Spar. The Clamp Capacity / Max Load ratio value of 1 is emphasized in the figures.

Environment			Derrick						Substructure										
Linnonnent			Failure Modes								Failure Modes								
			S	lip		Bolt Shear		Bolt T	ension			S	lip		Bolt Shear		Bolt T	ension	
	Bolt Pre- Tension (kips)	75	137	150	225		75	137	150	225	75	137	150	225		75	137	150	225
	Coeff of Friction																		
	0.1	1.0	1.6	1.8	2.6						0.7	1.1	1.1	1.5					
Ivan	0.3	2.9	4.9	5.3	7.7	10.9	4.6	2.9	2.6	0.6	2.2	3.2	3.4	4.6	5.5	4.9	3.1	2.7	0.6
-	0.5	4.9	8.2	8.9	12.9						3.7	5.4	5.7	7.7					
	0.1	1.2	1.9	2.1	3.0						0.9	1.2	1.3	1.8					
100 yr	0.3	3.5	5.9	6.4	9.2	13.0	7.4	4.7	4.2	1.0	2.5	3.7	3.9	5.3	6.3	10.4	6.7	5.9	1.4
	0.5	5.8	9.8	10.6	15.3						4.2	6.2	6.5	8.8					
	0.1	2.1	3.5	3.8	5.5						1.6	2.3	2.4	3.3					
10 yr	0.3	6.3	10.6	11.4	16.6	23.2	100.0	100.0	100.0	100.0	4.7	6.9	7.3	9.9	11.2	100.0	100.0	100.0	100.0
-	0.5	10.5	17.6	19.1	27.7						7.9	11.5	12.2	16.4					

 Table 11. TLP Results - Clamp Capacity/Max Load for Failure Mode, Environment, and Location

Environment			Upper Derrick					Substructure											
Environment		Failure Mode							Failure Mode										
			S	Slip		Bolt Shear		Bolt Te	ension			S	lip		Bolt Shear		Bolt Te	ension	
	Bolt Pre- Tension (kips)	75	137	150	225		75	137	150	225	75	137	150	225		75	137	150	225
	Coeff of Friction																		
	0.1	0.7	1.2	1.3	1.9						0.4	0.5	0.6	0.8					
Ivan	0.3	2.1	3.6	3.9	5.6	7.9	3.2	2.0	1.8	0.4	1.1	1.6	1.7	2.3	2.6	1.9	1.2	1.1	0.2
	0.5	3.5	5.9	6.4	9.3						1.8	2.6	2.8	3.8					
	0.1	0.9	1.5	1.6	2.2						0.5	0.7	0.7	1.0					
100 yr	0.3	2.7	4.5	4.8	7.0	9.8	4.2	2.7	2.4	0.6	1.4	2.0	2.1	2.9	3.3	2.9	1.8	1.6	0.4
_	0.5	4.4	7.4	8.0	11.6						2.3	3.4	3.6	4.8					
	·			•					•				•						
	0.1	1.8	3.0	3.2	4.6						0.9	1.3	1.3	1.8					
10 yr	0.3	5.3	8.9	9.6	13.9	19.6	18.7	12.0	10.6	2.4	2.6	3.8	4.0	5.4	6.0	11.9	7.6	6.7	1.5
	0.5	8.8	15.0	16.0	23.2						4.3	6.3	6.7	9.0					

 Table 12. Spar Results - Clamp Capacity/Max Load for Failure Mode, Environment, and Location



Figure 9. TLP in 100-year Hurricane Conditions: Clamp Capacity vs. Max Load for Tie-Down Clamps for Derrick and Substructure



Figure 10. TLP in Hurricane Ivan Conditions: Clamp Capacity vs. Max Load for Tie-Down Clamps for Derrick and Substructure



Figure 11. Spar in 100-year Hurricane Conditions: Clamp Capacity vs. Max Load for Tie-Down Clamps for Derrick and Substructure



Figure 12. Spar in Hurricane Ivan Conditions: Clamp Capacity vs. Max Load for Tie-Down Clamps for Derrick and Substructure

Some basic characteristics of the relationship between the failure modes are apparent in all the Figures 9 - 12. The clamp's capacity to resist sliding increases with the coefficient of friction. As the bolt pre-tension increases the clamp's capacity to resist sliding also increases. But as the bolt pre-tensions increase, tensile failures of bolts can cause the clamp capacity to be exceeded due to uplift forces before sliding would occur. Thus there needs to be a balance between consideration of sliding failures and tensile bolt failures when designing or securing a clamp.

Recall that the same clamp was used in this study for both the TLP and the Spar, and for both the derrick and the substructure. It is instructive to examine the implications of this.

For both the TLP and the Spar, the Clamp Capacity / Max Load ratios were smaller for the substructure clamps than for the derrick clamps for both sliding and bolt tension failures. This is principally due to larger inertial loads on the substructure clamps due to the combined masses of the substructure plus the deck.

The Clamp Capacity / Max Load ratio for the TLP were always higher than corresponding cases for the Spar. This was due to the higher inertial loads on the clamps due to the larger accelerations of the Spar.

## Approximate Estimates of Acceleration (API 4F)

Table 13 below compares acceleration computed from the time series simulations of the structure motions with those estimated from the approximations given in API 4F.

Environment	Max. To	otal Accele CG (a	erations @ ccel/g)	Derrick	Max. Total Accelerations @ Substructure CG (accel/g)					
	Time	Series	AP	API 4F		Series	API 4F			
	TLP	Spar	TLP	Spar	TLP	Spar	TLP	Spar		
10-year	0.130	.216	.096	0.223	0.125	.207	.095	0.220		
100-year	0.200	.393	.197	0.417	0.194	.378	.197	0.405		
Ivan	0.253	.508	.237	0.503	0.246	.490	.236	0.516		

 Table 13. Comparison of Max. Total Accelerations at the Derrick and Substructure CGs as

 Calculated from the Time Series Analyses and API 4F Methodology

The API 4F approximations for accelerations are within about 5 percent of those predicted by the time series analysis. For the TLP, the API 4F underestimates the accelerations by a factor of approximately 25 percent.

#### Discussion

As mentioned in the Introduction, there were three cases in which sea fastenings failed to prevent a drilling rig from moving during hurricane Ivan (reference 1,2). We were able to gather some information on the rig movements on Shell's Ram Powell TLP and Murphy's Medusa Spar. Because we were not able to gather sufficient data to allow a detailed study of any of these cases, we conducted the study of a hypothetical TLP and Spar with a drilling rig to study the performance of a simple bolted clamp tie down system.

While the TLP and Spar studied here were different than Ram Powell and Medusa, it is still interesting to compare the hypothetical TLP with Ram Powell's performance, and the hypothetical Spar with Medusa's performance.

The derrick and drill floor on the Ram Powell TLP were moved during hurricane Ivan, but it was not toppled and remained onboard partially due to the rig impacting process equipment on the deck (reference 4). Ram Powell was located just east of Ivan's track, and the eye of the storm likely passed over Ram Powell. Hindcast values for the maximum hindcast significant wave was 52 ft and the maximum windspeed was 88 kts (30 min average at 10 m elevation). Shell reported that the derrick and drill floor skidded 60 ft along the skid beams until it became wedged against a field gas compressor. Shell concluded that the bolts for the clamps were not properly torqued. Figure x for the TLP and derrick studied here suggests that a combination of low torque and low coefficient of friction could lead to a sliding failure during Ivan conditions.

The Medusa derrick and substructure on Medusa were toppled during Hurricane Ivan. Murphy reported that the measured maximum wave height on Medusa was 72 ft (significant wave height of 41 ft) and the maximum wind speed was73 knots. Their studies indicated that the skid base slid relative to the deck and the rig slid off its skid beams into the sea 1 to 2 hours earlier when the wave

heights and winds were lower. Platform motions were well within design limits throughout the storm. Murphy and Nabors concluded that while the clamp was able to prevent the rig from being blown over, it was not able to prevent sliding. Their findings are not inconsistent with the results of the Spar and drilling rig studied here in that Figure x for the Spar derrick and substructure studied here indicate that sliding of both the derrick and substructure cold occur in 100-year conditions.

#### **Conclusions & Recommendations**

#### Inertial Loads on Tie-Down Clamps

The performance of tie-down clamps for a drilling rig on a TLP and Spar subjected to a in a range of hurricane environments was analyzed. The same tie-down clamps were used to secure the drilling rig to the substructure, and the substructure to the deck for both structures. The loads on the tie-down clamps are due to weight, wind loads and inertial loads due to the motions of the FPS.

The results of this study show that the loads that tie-down clamps must resist can be significantly different for

- the TLP and a Spar
- the derrick and the substructure

The differences in clamp tie-down loads for the TLP and Spar are due to the differences in the inertial loads that result from the different motion characteristics of the two FPSs.

The differences between the clamp tie-down loads for the derrick and the substructure are due to the differences in acceleration of their CGs (due to location, i.e., elevation) and the masses of the derrick and the derrick plus the substructure. The total loads on the clamps for the substructure will always be greater that those for the derrick alone.

These results illustrate that clamps should be purpose-designed for the specific FPS's motions and function. In the case of a different drilling rig being transferred to another structure, the clamps should be assessed to ensure that they can resist the loads imposed by the new combination of different wind and inertial (masses and accelerations) loads.

#### **Bolted Tie-Down Clamps**

Sliding and bolt tensile failures are the most important failure modes for bolted tie-down clamps.

**Sliding** – Clamp failure in slip is resisted by friction, which is dependent upon the coefficient of friction, weight of the derrick and the substructure, and the bolt clamping forces. There is uncertainty in the static and dynamic coefficients of friction that would be effective during hurricane conditions because of the condition of surfaces of the clamp faces and skid beam surfaces, e.g.,

- surface rust and oxidation
- the presence of lubricants used during rig skidding operations
- general cleanliness (presence of drilling mud, lubricants, dirt
- wetness due to rain and spray during a hurricane

This uncertainty in the coefficient of friction should be accounted for in the design of the clamps. Additional clamping forces may be generated by more pre-tension on the bolts (but see discussion below).

Positive stops along the skid beams that could arrest sliding in shear (e.g., shear pins in predrilled regularly spaced holes in the skid beams) might also be considered as a means to arrest movement in the event of clamp slippage.

**Tensile Bolt Failure** – Tensile bolt failures occur when the sum of the bolt's pre-tension and the tension caused by uplift forces on the clamp exceed the bolt's tensile capacity. Tensile bolt failure can lead to the loss of clamp's capacity to prevent slipping or uplift. It is expected that the tensile failure of the first bolt in a clamp would lead to the progressive failure of the remaining bolts in the clamp.

Bolt pre-tension is also the means for increasing the clamp's resistance to sliding. The design of a clamp must balance the bolt pre-tension to provide the necessary amount of friction to prevent sliding and yet leave sufficient tensile capacity to resist the expected uplift forces. This design bolt pre-tension must be carefully and accurately applied when preparing for a hurricane and should not be exceeded. It is important to note that a change in the drilling rig live loads prior to a hurricane can also significantly change the bolt pre-tensions. For example, a reduction in drilling fluids or pipe in the setback can increase the bolt pre-tension and affect the capacity of the clamps.

#### **Hull Accelerations**

API Specification 4F presents an approximate method for estimating accelerations for use in computing the inertia loads for tie-down clamp design. The results of this study indicate that the accelerations may not provide accurate estimates of accelerations for all FPSs or motion components. Vessel motions and acceleration used in the design should be the preferred basis for tie-down clamp design.

#### Acknowledgements

We would like to acknowledge the support of the Minerals Management Service. In addition to MMS funding the project, Mr. Tommy Laurendine arranged for us to visit a number of FPS's to examine rig tie-down systems and discuss operational issues with platform staff, which added great value to this study.

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Appendix A

# Assessment of the Performance of Tie-Down Clamps for a Drilling Rig on a Spar in Severe Hurricane Environments

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To : Joe Gebara

From : Nadia Ghoneim, Michael Szczglowski

Subject : MMS Rig Tie Down Study: Structural Analysis of Clamped Connections for Spar drilling and workover rigs, and a comparison of Spar and TLP rig tie-downs.



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# TABLE OF CONTENTS

1.	INTRODUCTION AND SCOPE OF WORK	6
2.	API-4F ACCELERATION CALCULATIONS	9
3.	SAMPLE CALCULATIONS OF WIND AND DYNAMIC LOADING	13
4.	CLAMPED CONNECTION CAPACITY	17
5.	RIGID MODELS ANALYSIS AND RESULTS	25
6.	CLAMP CONNECTIONS LOADS VS CAPACITY	34
(	6.1       IVAN LOAD CASE         6.1.1       Bolts Shear/Slip Loading         6.1.2       Connection Shear/Slip Check (Ivan Loading)         6.1.3       Bolts Tension Loading & Capacity Check         6.2       100 YEAR HURRICANE LOAD CASE         6.2.1       Bolts Shear/Slip Loading         6.2.2       Connection Shear/Slip Check         6.2.3       Bolts Tension Loading & Capacity Check         6.3       10 YEAR HURRICANE LOAD CASE         6.3.1       Bolts Shear/Slip Loading         6.3.1       Bolts Shear/Slip Loading         6.3.2       Connection Shear/Slip Check         6.3.3       Bolts Shear/Slip Check         6.3.3       Bolts Tension Loading & Capacity Check         6.3.3       Bolts Tension Loading	35 35 36 38 42 42 42 43 43 44 44 47 47 47 47 48 49
7.	SPAR VS TLP ANALYSIS	
•	7.1       GENERAL         7.2       TENSILE, SHEAR & SLIP RESULTS FOR TLP RIG CLAMPS         7.3       STRUCTURE OVERTURNING MOMENTS VS. MAXIMUM UPLIFT FORCES         7.3.1       Results for Spar Rig         7.3.2       Results for TLP Rig	
8.	SUMMARY OF FINDINGS & CONCLUSIONS	59
9.	REFERENCES	63



Our Ref.

303859-IM-0001

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## LIST OF TABLES

TABLE 1	MOTION DETAILS	9
TABLE 2	TRANSLATIONAL (LATERAL) ACCELERATIONS AT SPAR CG.	9
TABLE 3	DISTANCE FROM CENTRE OF MASSES TO SPAR CG.	9
TABLE 4	API-4F CALCULATED ROTATIONAL ACCELERATIONS	10
TABLE 5	ACCELERATIONS DUE TO HEEL (LIST)	10
TABLE 6	API-4F TOTAL TRANSLATIONAL ACCELERATIONS AT UPPER DERRICK CG.	11
TABLE 7	API-4F TOTAL TRANSLATIONAL ACCELERATIONS AT SUBSTRUCTURE CG.	11
TABLE 8	API-4F CALCULATED HEAVE ACCELERATIONS	11
TABLE 9	SUMMARY OF API-4F ACCELERATIONS	12
TABLE 10	TIME DOMAIN ACCELERATIONS	12
TABLE 11	UPPER DERRICK WIND PROJECTED AREA	13
TABLE 12	REACTIONS PER SINGLE CLAMP CONNECTION AT UPPER DERRICK FOOTINGS LEVEL	16
TABLE 13	TORQUE VALUE & CORRESPONDING BOLT PRETENSION LOAD	18
TABLE 14	CONNECTION SLIP CAPACITY VS BOLT PRETENSION LOADING	19
TABLE 15	PRETENSION, COEFFICIENT OF FRICTION & CONNECTION CAPACITY	20
TABLE 16	BOLT TORQUE, COEFFICIENT OF FRICTION, PRETENSION AND SLIP CAPACITY	21
TABLE 17	BOLTS TENSILE CAPACITY PER CLAMP CONNECTION	23
TABLE 18	REACTION FORCES & MOMENTS (IVAN)	28
TABLE 19	REACTION FORCES & MOMENTS (100 YR)	29
TABLE 20	REACTION FORCES & MOMENTS (10YR)	30
TABLE 21	REACTION FORCES & MOMENTS (IVAN), X-DIRECTION LOADING	31
TABLE 22	REACTION FORCES & MOMENTS (100-YR), X-DIRECTION LOADING	31
TABLE 23	REACTION FORCES & MOMENTS (10-YR), X-DIRECTION LOADING	32
TABLE 24	REACTION FORCES & MOMENTS (IVAN), Y-DIRECTION LOADING	32
TABLE 25	REACTION FORCES & MOMENTS (100-YR), Y-DIRECTION LOADING	33
TABLE 26	REACTION FORCES & MOMENTS (10-YR), Y-DIRECTION LOADING	33
TABLE 27	TOTAL LATERAL FORCES PER CONNECTION (IVAN)	35
TABLE 28	BOLTS SHEAR FACTOR OF SAFETY PER CONNECTION (IVAN)	36
TABLE 29	SLIP CHECK & FACTOR OF SAFETY PER CONNECTION (IVAN)	37
TABLE 30	BOLT TENSION CALCULATIONS & FS PER CONNECTION (IVAN) FOR 137.3 KIPS PRETENSION	39
TABLE 31	BOLT TENSION CALCULATIONS & FS PER CONNECTION (IVAN) FOR 75 KIPS PRETENSION	39
TABLE 32	BOLT TENSION CALCULATIONS & FS PER CONNECTION (IVAN) FOR 150 KIPS PRETENSION	40
TABLE 33	BOLT TENSION CALCULATIONS & FS PER CONNECTION (IVAN) FOR 225 KIPS PRETENSION	40
TABLE 34	SUMMARY OF TENSILE FACTORS OF SAFETY: IVAN LOAD CASE	41
TABLE 35	TOTAL SHEAR/SLIP FORCES PER CONNECTION (100 YR)	42
TABLE 36	BOLTS SHEAR FACTOR OF SAFETY PER CONNECTION (100 YR)	43
TABLE 37	SLIP FACTOR OF SAFETY PER CONNECTION (100 YR)	43
TABLE 38	BOLT TENSION CALCULATIONS & FS PER CONNECTION (100 YR) FOR 137.3 KIPS PRETENSION	44



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

TABLE 39	TENSION CALCULATIONS & FS PER CONNECTION (100 YR) FOR 75 KIPS PRETENSION
TABLE 40	BOLT TENSION CALCULATIONS & FS PER CONNECTION (100 YR) FOR 150 KIPS PRETENSION
TABLE 41	BOLT TENSION CALCULATIONS & FS PER CONNECTION (100 YR) FOR 225 KIPS PRETENSION
TABLE 42	SUMMARY OF TENSILE FACTORS OF SAFETY: 100-YEAR HURRICANE LOAD CASE
TABLE 43	TOTAL SHEAR/SLIP FORCES PER CONNECTION (10 YR)
TABLE 44	BOLTS SHEAR FACTOR OF SAFETY PER CONNECTION (10 YR)
TABLE 45	SLIP CHECK & FACTOR OF SAFETY PER CONNECTION (10 YR)
TABLE 46	BOLT TENSION CALCULATIONS & FS PER CONNECTION (10 YR) FOR 137.3 KIPS PRETENSION49
TABLE 47	BOLT TENSION CALCULATIONS & FS PER CONNECTION (10 YR) FOR 75 KIPS PRETENSION
TABLE 48	BOLT TENSION CALCULATIONS & FS PER CONNECTION (10 YR) FOR 150 KIPS PRETENSION
TABLE 49	BOLT TENSION CALCULATIONS & FS PER CONNECTION (10 YR) FOR 225 KIPS PRETENSION
TABLE 50	SUMMARY OF TENSILE FACTORS OF SAFETY: 10-YEAR HURRICANE LOAD CASE
TABLE 51	TLP PLATFORM ACCELERATIONS
TABLE 52	TLP SUBSTRUCTURE CLAMP LOADS PERTAINING TO BOLTS TENSION
TABLE 53	TLP UPPER DERRICK CLAMP LOADS PERTAINING TO BOLTS TENSION
TABLE 54	TLP-CLAMP BOLTS TENSILE FACTORS OF SAFETY FOR 45° LOADING DIRECTION
TABLE 55	TLP-SUBSTRUCTURE CLAMP SHEAR FORCES & FACTORS OF SAFETY
TABLE 56	TLP-UPPER DERRICK CLAMP SHEAR FORCES & FACTORS OF SAFETY
TABLE 57	TLP-SUBSTRUCTURE CLAMP SLIP FORCES & FACTORS OF SAFETY
TABLE 58	TLP-DERRICK CLAMP SLIP FORCES & FACTORS OF SAFETY
TABLE 59	SPAR DERRICK CLAMP MAXIMUM UPLIFT FORCES & GLOBAL OVERTURNING MOMENTS
TABLE 60	SPAR SUBSTRUCTURE CLAMP MAXIMUM UPLIFT FORCES & GLOBAL OVERTURNING MOMENTS55
TABLE 61	TLP DERRICK CLAMP MAXIMUM UPLIFT FORCES & GLOBAL OVERTURNING MOMENTS
TABLE 62	TLP SUBSTRUCTURE CLAMP MAXIMUM UPLIFT FORCES & GLOBAL OVERTURNING MOMENTS



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# LIST OF FIGURES

FIGURE 1	STRUCTURE GENERAL ARRANGEMENT	8
FIGURE 2	UPPER DERRICK FOOTINGS PROJECTION	14
FIGURE 3	CLAMPED CONNECTION DETAIL	17
FIGURE 4	TYPICAL TRANSFER OF LOAD IN PRETENSIONED HIGH STRENGTH BOLTED CONNECTION	18
FIGURE 5	BOLT PRETENSION, COEFFICIENT OF FRICTION & SLIP CAPACITY CHART	20
FIGURE 6	CONNECTION SLIP CAPACITY VS COEFFICIENT OF FRICTION CHART	21
FIGURE 7	UPPER DERRICK CONNECTION SLIP CAPACITY CHART	22
FIGURE 8	SUBSTRUCTURE CONNECTION SLIP CAPACITY CHART	22
FIGURE 9	COMBINED UPPER DERRICK & SUBSTRUCTURE RIGID MODEL	25
FIGURE 10	UPPER DERRICK RIGID MODEL	26
FIGURE 11	REFERENCE NODE NUMBERS AND WIND & ACCELERATIONS LOADING DIRECTIONS FOR UPPER	27
FIGURE 12	BOLT ARRANGEMENTS FOR DERRICK & SUBSTRUCTURE FOOTINGS	34
FIGURE 13	SPAR SUBSTRUCTURE CLAMP UPLIFT FORCES VS GLOBAL OVERTURNING MOMENTS	56
FIGURE 14	SPAR DERRICK CLAMP UPLIFT FORCES VS GLOBAL OVERTURNING MOMENTS	56
FIGURE 15	TLP SUBSTRUCTURE CLAMP UPLIFT FORCES VS GLOBAL OVERTURNING MOMENTS	58
FIGURE 16	TLP DERRICK CLAMP UPLIFT FORCES VS GLOBAL OVERTURNING MOMENTS	58
FIGURE 17	NUMBER OF BOLT SLIP FAILURE CASES IN THE ANALYSIS OF A SPAR RIG	60
FIGURE 18	NUMBER OF BOLT TENSILE FAILURE CASES IN THE ANALYSIS OF A SPAR RIG	61



Dept.



Our Ref.

# 303859-IM-0001

Date : 15/01/2007

## 1. INTRODUCTION AND SCOPE OF WORK

This document pertains to the MMS Study of Rig Tie-Down with particular focus on Spar drilling and workover rigs and on comparing spar and TLP rig tie-downs. It presents a comparative analysis for acceleration calculations based on 2 different approaches and the structural analysis of the capacity of upper derrick and substructure clamped connections.

The scope of the analysis includes:

- 1- Calculating accelerations based on API-4F (Ref. 1) specifications at CG. of upper derrick and CG. of substructure for 10-year, 100-year and Ivan environmental criteria and comparing results with accelerations derived from Time Domain analysis (Ref.2).
- 2- Developing rigid models comprising the upper derrick and substructure masses and extracting the 6 DOF reactions resulting from API-4F loading as well as loading based on Time Domain accelerations for the above load cases.
- 3- Calculating ultimate capacities of clamped connections with respect to lateral loads (taking into account 3 different coefficients of friction) and vertical (tension) loads.
- 4- Comparing connections actual loading to corresponding ultimate capacities and determining factors of safety for all load cases.
- 5- Summarizing the results to provide an overview of the status of the clamped connection with respect to various bolts modes of failure.

The analysis is performed with the aid of STRUCAD\*3D Version 4.3 finite element software One model representing the derrick mass of 550 kips and a second model combining the derrick mass and substructure mass of 1500 kips were developed. The boundary conditions for all the support joints are fixed. The models include wind loading on the structure as well as dynamic loading.

Forces due to wind and dynamics are applied in three directions, Pitch (X) direction; Roll (Y) direction and at 45° angle where Pitch & Roll are combined The importance of the latter case is to determine the maximum tensile forces to which the connection bolts may be subjected. Two cases of wind loading are investigated:

- 1- API-4F recommended 107 knots minimum wind loading, applied to all load cases.
- 2- According to Time Domain analysis: 87.9 knots wind loading for Ivan hurricane, 81.3 knots wind loading for 100-year hurricane and 50.9 knots wind loading for 10-year hurricane.

In addition, this document includes results of a similar analysis performed using Inertia loads derived for TLP rigs. Comparative results of Spar & TLP rig tie-down clamp connections draw attention to the specific sea fastening requirements of rigs on different offshore floating systems.



Dept.

# Our Ref.

## 303859-IM-0001

Date : 15/01/2007

An overview of the structure geometry and dimensions employed in the analysis is shown in Figure 1. Details of the analysis performed are provided and a summary of the analysis findings is also included at the end of this document.

The analysis demonstrates the conservatism of the API-4F approach for dynamic loading calculations for Spar rigs and the vulnerability of the Spar drilling and workover rig clamps to slip and tensile failures compared to the TLP rig tie down.



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007



#### Figure 1 Structure General Arrangement



Dept.

Our Ref.

## 303859-IM-0001

Date : 15/01/2007

## 2. API-4F ACCELERATION CALCULATIONS

Information pertaining to accelerations details required to determine dynamic loading on the structure for three different load cases are obtained from the Spar Motion Analysis Memo (303859-IM-0001, Rev A) and summarised in the following Tables.

		AMPLITUDE	PERIOD	HE	AVE	LIST	
LOAD CASE	MOTION	Φ*	Т	H**	Т	α	
		(degree)	(sec)	(ft)	(sec)	(degree)	
10 vb	ROLL	1.2	11.25	17	17 92	3.2	
i U yii	PITCH	1.2	11.25	1.7	17.02		
100 hww	ROLL	2.2	12.26	БÖ	19.66	0 /	
100 1100	PITCH	2.2	12.26	5.8	10.00	0.4	
lyon	ROLL	3.1	13.02	0.1	10 71	10.9	
ivali	PITCH	3.1	13.02	9.1	10.74	10.0	

\* Single Amplitude

\*\* Double Amplitude

## Table 2 Translational (Lateral) Accelerations at Spar CG.

SURGE & SWAY								
CASE STUDY	SURGE (X) (g)	SWAY (Y) (g)						
10yh	0.0830	0.0830						
100hwv	0.1240	0.1240						
Ivan	0.1540	0.1540						

g= 32.2 ft/sec2

#### Table 3Distance from centre of Masses to Spar CG.

DISTANCE FROM SPAR CG TO						
UPPER DERRICK*	SUBSTRUCTURE**					
CG.	CG.					
(ft)	(ft)					
346	307					

\* Distance=177ft+116ft+53ft=346ft \*\*Distance=177ft+116ft+14ft=307ft

The above motion details are employed to calculate the translational (lateral) and rotational accelerations at the CG. of the upper derrick and CG. of the substructure in accordance with API-4F specifications.


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Our Ref.

# 303859-IM-0001

Date : 15/01/2007

#### ROTATIONAL ACCELERATION DUE TO ROLL OR PITCH:

ACCEL.=  $\frac{4\Pi^2 x \Pi \Phi}{T^2 x 180}$   $\Pi$ = 3.14 **ACCEL= 0.6880**  $\frac{\Phi}{T^2}$  rad/sec<sup>2</sup> .....Eq (1)

#### Table 4 API-4F Calculated Rotational Accelerations

ROTATIONAL	rad/sec <sup>2</sup>	
10yh	ROLL	0.0065
	PITCH	0.0065
100hwa/	ROLL	0.0101
TUUNWV	PITCH	0.0101
lvan	ROLL	0.0126
IVali	PITCH	0.0126

#### ACCELERATIONS DUE TO LIST (HEEL):

α°=	LIST ANGLE	ACCEL= $sin\alpha^{\circ}$	(a)	Eq (2)
u –			(9)	Eq (2)

 Table 5
 Accelerations Due to Heel (List)

LOAD CASE	ACCEL	.ER.=sinα	ACO	CEL. g)
10yh	α°=	3.2	sinα=	0.056
100hwv	α°=	8.4	sinα=	0.146
Ivan	α°=	10.8	sinα=	0.187

In the following Tables (Tables 6 & 7), the "<u>Total Translational</u>" (lateral) accelerations are calculated as follows at derrick and substructure CG. for Pitch & Roll directions respectively,

#### Pitch direction (X):

Total Acceleration= List accel. (Table 5) + (accel. due to weight+ accel. due to Surge+ accel. due to Pitch (Tables 6&7))

Roll direction (Y):

Total Acceleration= List accel. (Table 5) + (accel. due to weight+ accel. due to Sway+ accel. due to Roll (Tables 6&7))



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#### 303859-IM-0001

Date : 15/01/2007

#### TOTAL TRANSLATIONAL ACCELERATIONS UPPER DERRICK

g= 32.2 ft/sec2 Center of Derrick at: L1=

k at: L1= 346 ft from Center of Rotation

Table 6	API-4F Total Translational Ac	celerations at Upper Derrick CG.
---------	-------------------------------	----------------------------------

LOAD	a – WG			ainth	(m)	SWAY=	SURGE=	AT C.G of	DERRICK*	LIST=	TOTAL**
CASE	a <sub>w</sub> = wG		F. ACCEL=	SINΨ	(9)	a <sub>Y</sub> (g)	a <sub>x</sub> (g)	a <sub>R</sub> (g)	a <sub>P</sub> (g)	a <sub>∟</sub> (g)	(g)
10vh	ROLL (Y)	Ф=	1.2	sinΦ=	0.021	0.0830		0.0701		0.056	0.230
royn	PITCH (X)	Ф=	1.2	$sin\Phi=$	0.021		0.0830		0.0701	0.056	0.230
100hway	ROLL (Y)	Ф=	2.2	sinΦ=	0.038	0.1240		0.1082		0.146	0.417
1001100	PITCH (X)	Ф=	2.2	$sin\Phi=$	0.038		0.1240		0.1082	0.146	0.417
lyan	ROLL (Y)	Ф=	3.1	sinΦ=	0.054	0.1540		0.1352		0.187	0.531
ivan	PITCH (X)	Ф=	3.1	$sin\Phi=$	0.054		0.1540		0.1352	0.187	0.531

\* Translational Accel. At CG of Upper Derrick (g)= Rotational Accel (rad/sec<sup>2</sup>)xL1(ft) / g(ft/sec<sup>2</sup>)

\*\* Total Accel. (X)=  $\Sigma$  ( $a_W$  +  $a_X$ +  $a_P$  +  $a_L$ )

Total Accel. (Y)=  $\Sigma$  (a<sub>W</sub> + a<sub>Y</sub> + a<sub>R</sub> + a<sub>L</sub>)

# SUBSTRUCTURE

Center of Substruc. at: L=

from Center of Rotation

# Table 7 API-4F Total Translational Accelerations at Substructure CG.

307 ft

LOAD	a – WG			ainÆ	(a)	SWAY=	SURGE=	AT C.G of	SUBSTR.*	LIST=	TOTAL**
CASE	a <sub>w</sub> = wG		F. ACCEL=	SINΨ	(9)	a <sub>y</sub> (g)	a <sub>x</sub> (g)	a <sub>R</sub> (g)	a <sub>P</sub> (g)	a <sub>∟</sub> (g)	(g)
10vh	ROLL (Y)	Ф=	1.2	sinΦ=	0.021	0.0830		0.0622		0.056	0.222
TOYI	PITCH (X)	Ф=	1.2	$sin\Phi=$	0.021		0.0830		0.0622	0.056	0.222
100hww	ROLL (Y)	Ф=	2.2	sinΦ=	0.038	0.1240		0.0960		0.146	0.404
1001100	PITCH (X)	Ф=	2.2	$sin\Phi=$	0.038		0.1240		0.0960	0.146	0.404
lyon	ROLL (Y)	Ф=	3.1	sinΦ=	0.054	0.1540		0.1199		0.187	0.515
Ivan	PITCH (X)	Ф=	3.1	sinΦ=	0.054		0.1540		0.1199	0.187	0.515

\* Translational Accel. At CG of Sub. (g)= Rotational Accel (rad/sec<sup>2</sup>)xL(ft) / g(ft/sec<sup>2</sup>)

\*\* Total Accel. (X)=  $\Sigma$  (a<sub>W</sub> + a<sub>X</sub>+ a<sub>P</sub> + a<sub>L</sub>)

Total Accel. (Y)=  $\Sigma (a_W + a_Y + a_R + a_L)$ 

#### **ACCELERATIONS DUE TO HEAVE**

g=	32.2 ft/sec <sup>2</sup>			-	
ACCEL=	<u>2∏<sup>2</sup>H</u> gT <sup>2</sup>	ACCEL=	0.6124 <u>H</u> T <sup>2</sup>	(g)	Eq (3)

#### Table 8 API-4F Calculated Heave Accelerations

LOAD CASE	ACCELERATION
10yh	0.0033 g
100hwv	0.0102 g
Ivan	0.0159 g





Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# **ACCELERATIONS COMPARISON**

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Tables 9 & 10 summarise the final results for accelerations at the CG. Of upper derrick and at the CG. of substructure derived from two approaches: API-4F specifications and Time Domain analysis.

API-4F ACCELERATIONS										
	ROTAT	IONAL	LATE	RAL						
LOAD				AT CG.	AT CG.	HEAVE				
CASE	DIRECTION	API-4F	DIRECTION	DERRICK	SUBS.					
		rad/sec2		(g)	(g)	(g)				
10vh	ROLL (Y)	0.0065	(Y)	0.230	0.222	0 0022				
logii	PITCH (X)	0.0065	(X)	0.230	0.222	0.0055				
100bw0/	ROLL (Y)	0.0101	(Y)	0.417	0.404	0.0102				
1001100	PITCH (X)	0.0101	(X)	0.417	0.404	0.0102				
Ivan	ROLL (Y)	0.0126	(Y)	0.531	0.515	0.0150				
	PITCH (X)	0.0126	(X)	0.531	0.515	0.0109				

# Table 9 Summary of API-4F Accelerations

#### Table 10 Time Domain Accelerations

TIME DOMAIN ANALYSIS								
				HEAVE A	AT TIME			
			L.	MAX. LAT	. ACCEL.			
LOAD		AT CG.	AT CG.	AT CG.	AT CG.			
CASE	DIRECTION	DERRICK	SUBS.	DERRICK	SUBS.			
		(g)	(g)	(g)	(g)			
10vb	(Y)	0.2160	0.2070	0.002	0.003			
TOYII	(X)	0.2160	0.2070	0.003				
100bwo/	(Y)	0.3930	0.3780	0.002	0.003			
	(X)	0.3930	0.3780	0.003	0.003			
lyan	(Y)	0.5080	0.4900	0.015	0.015			
Ιναιι	(X)	0.5080	0.4900	0.015	0.015			

The above results indicate that the accelerations calculated based on API-4F specifications are consistently more conservative when compared with those from Time Domain Analysis.

The API-4F lateral accelerations exceed those from Time Domain Analysis by 4.5% to 6.5%. In the case of vertical acceleration, the API-4F 100 YR heave value exceeds that from Time Domain Analysis by nearly 2.5 times when compared to the acceleration associated with the maximum lateral accelerations.



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

#### 3. SAMPLE CALCULATIONS OF WIND AND DYNAMIC LOADING

As described previously, reactions at the footings of the upper derrick & substructure are derived from a combination of wind and dynamic loading on the structure. Loading applied at a 45° angle incorporates all dynamic components & the highest wind surface exposure.

In this section a sample calculation is provided to demonstrate the applicability of the API-4F procedure. This calculation is based on Ivan dynamic loading on the upper derrick and a wind velocity of 107 knots. The derrick supports are assumed to be pinned (rotations allowed) to simplify hand calculations.

Other information pertaining to force and reactions calculations is the wind projected area. The projected area of upper derrick is 1470 ft<sup>2</sup> and CP at 201 ft from MWL.

The analysis in the following sections is based on an estimated wind area for substructure of 500  $ft^2$  and the centre of pressure is assumed to coincide with the centre of gravity.

A summary of wind Area and CP for API-4F force calculations for upper derrick is provided in the following Table:

Α	PROJECTED AREA	(API-4F) <sup>a</sup> PROJECTED AREA	CP <sup>b</sup>	DIRECTION				
UPPER DERRICK								
A <sub>1X</sub>	1470.0 ft2	2940.0 ft2	201 ft	Х				
<b>A</b> <sub>1Y</sub>	1470.0 ft2	2940.0 ft2	201 ft	Y				
<b>A</b> <sup>c</sup> <sup>o</sup> <sub>1-45</sub>		4157.8 ft2	201 ft	45° ANGLE				

#### Table 11 Upper Derrick Wind Projected Area

a: Exposed Areas of two opposite sides (API-4F Section 7.2.1)

b: Distance from MWL to center of wind Area

c:  $A_{1-45}^{o}$  = Square Root of Sum of Squares of Areas in (X) & (Y) Directions



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007





Derrick Reaction Forces D	ue to Wei	ght		
Total Derrick weight=	550	kips		
Total No of Clamped Conne	ctions =N=		4	•
Reaction Force per Con. (du	ue to weigh	t)=	137.5	kips
Derrick Reaction Forces d API-4F Min. Design Wind V	<u>1</u> 107	knots		
Y-DIRECTION				
Wind Velocity= V =	107 kno	ts		
Height* Co.=	C <sub>h</sub> =	1.37		(for Height= 201 ft)
Shape Co.=	C <sub>s</sub> =	1.25		
* Vertical distance from wate	er surface t	o the cent	ter of are	а
P= .00338xV <sup>2</sup> xC <sub>h</sub> xC	C <sub>s</sub> =	66.27 lb	/ft <sup>2</sup>	
Derrick Projected Wind Area	$A = A_{1Y} =$		2940.0	ft <sup>2</sup>
F <sub>1Y</sub> = Wind Loading= ((PxA			194.83	kips
X-DIRECTION				
F <sub>1X</sub> = Wind Loading= ((PxA	( <sub>1x</sub> )/1000)=		194.83	kips
45° ANGLE-DIRECTION				
Wind Loading= F <sub>45</sub> =			275.5	kips

# Wind Loading= $F_{45}$ =



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

Elevation of Centre of pressure of wind area is at 201 ft from MWL					
Elevation of upper derrick footings from MWL is at (116 ft +30 ft) = 146 ft					
Moment Arm for Wind Force= 201ft-146 ft=h= 55.00 ft					
a=	25.00 ft				
b=	25.00 ft				
$d=(a^2+b^2)^{1/2}=$	35.36 ft				

#### SHEAR FORCES

Y-Shear Force/ Connection=F <sub>1V</sub> /N=	48.71	, kips
Shear Force per Connection Due to $45^{\circ}$ -Wind= $F_{45}$ =	68.88	kips

#### **TENSION FORCES**

Tension Force per Connection Due to X-Wind= F <sub>1X</sub> x h/(2a)=	214.32 kips
Tension Force per Connection Due to Y-Wind= F <sub>1Y</sub> x h/(2b)=	214.32 kips
Tension Force per Connection Due to $45^{\circ}$ -Wind= F <sub>45</sub> x h/(d)=	428.63 kips

#### (IVAN) Dynamic Loading on Derrick

L= distance from pitch/roll axis to the center of gravity of the upper derrick W= derrick weight= 550 kips

#### X-DIRECTION (PITCH)

 FP= (WL/g)x(Rotational Accel)+ Wx Transl. Accel(g)= W x (Total Translational Acceleration (g))

 FP= 291.83 kips
 X-Direction

 Y-DIRECTION (ROLL)

 FR= (WL/g)x(Rotational Accel)+ Wx Transl. Accel(g)= W x (Total Translational Acceleration (g))

 FR= 291.83 kips
 Y-Direction

F at  $45^{\circ}$  direction=(FP<sup>2</sup>+FR<sup>2</sup>)<sup>1/2</sup>= 412.7 kips

#### **Derrick Reactions Due to Dynamics**

N= number of Derrick support connections=	4	
a=	25.00 ft	
b=	25.00 ft	
$d=(a^2+b^2)^{1/2}=$	35.36 ft	
Moment Arm for Dynamic Forces=H=53'-30'=		23.00 ft



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

SHEAR FORCE	ES
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X-Shear Force/ Clamp connection= FP/N=	72.96 kips
Y-Shear Force/ Clamp connection= FR/N=	72.96 kips
Shear Force per Clamp connec. Due to 45° Loading=	103.18 kips
TENSION FORCES	
Tension Force per Clamp connection Due to X-Loading= FPx 23/(2a)=	134.24 kips
Tension Force per Clamp connection Due to Y-Loading= FRx 23/(2b)=	134.24 kips
Tens. Force per Clamp connec. Due to 45°-Ldng.=((FR <sup>2</sup> +FP <sup>2</sup> ) <sup>1/2</sup> )x23/d=	268.48 kips

#### HEAVE LOADING

Max. Uplift due to Heave/ Clamp Connection= WxHeave Accel/N=

2.19 kips

The final reactions at the connection are obtained by adding the various loading components. These components are summarised in the following Table.

Number of Bolts per Connection=n=	8.00 bolts
Bolt Diameter= D=	2.00 in
Bolt Area= $\pi$ D <sup>2</sup> /4=	3.14 in <sup>2</sup>

#### Table 12 Reactions per Single Clamp Connection at Upper Derrick Footings Level

DIRECT	TYPE	WIND	DYNAM.	WEIGHT	HEAVE (UP)	TOT. LOAD	BO	LT
	TIFE	(kips)	(kips)	(kips)	(kips)	kips	FORCE (kips)	STRESS (ksi)
Х	SHEAR	48.71	72.96			121.67	15.21	4.84
LOADING	TENSION	214.32	134.24	-137.50	2.19	213.24	26.66	8.49
Y	SHEAR	48.71	72.96			121.67	15.21	4.84
LOADING	TENSION	214.32	134.24	-137.50	2.19	213.24	26.66	8.49
45°	SHEAR	68.88	103.18			172.06	21.51	6.85
LOADING	TENSION	428.63	268.48	-137.50	2.19	561.80	70.23	22.36

From Table 12, the maximum tension force per connection for this case is 561.8 kips and the shear force amounts to 121.67 kips for each direction, X-direction & Y-direction. In addition to demonstrating the applicability of the API-4F specifications and methodology, these numbers validate the results of the STRUCAD analysis (see section 5, Table 18).



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# 4. CLAMPED CONNECTION CAPACITY

A schematic representation for the clamped connections under study is shown in Figure 3.

This section determines the ultimate capacity of the clamped connection with respect to 3 modes of failure for the bolts, namely slip resistance, shear and tension.



Figure 3 Clamped Connection Detail



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

4.1 Connection	Slip Capacit	у				
Coefficient of Friction for the Analysis (µ) 0.1 0.3 0.5						
BOLT PRETENSI	ON CALCUL	ATIONS AS FUNCTION	OF TORQU	<u>E</u>		
MT=0.2 D T	Then:	T=MT/ (0.2 D)		(Ref. 3)		
MT= initial Bolt To	rque (Lb-in)					
D= nominal Bolt D	iameter=	2 in				

T= individal Bolt Load (Pretension) (Lb)

#### Table 13 Torque Value & Corresponding Bolt Pretension Load

TORQUE (MT)	TORQUE (MT)	PRETENSION (T)
(lb-ft)	(lb-in)	(kips)
2500	30000	75
5000	60000	150
7500	90000	225

Bolt pretension creates a slip resistance force P between connected plates as shown below:



Figure 4 Typical Transfer of Load in Pretensioned High Strength Bolted Connection Based on (Ref. 4, Chapter 4).



Dept.

Our Ref.

#### 303859-IM-0001

Date : 15/01/2007

The Frictional resistance can be calcu	lated from the	following e	equation.	
Frictional Resistance= Slip Capacity=	Ρ=μΤ			Eq. 5
	T=	Tensile Fo	rce	
	μ=	Coefficient	of Friction	
n=number of bolts per conc.=	8 bolts			
Upper Derrick weight=W1=	550 kips			
Substructure weight=W2= 1	500 kips			
Total Structure weight carried by substr. for	ootings=	W=550+15	=00	2050 kips
Structure weight carried per upper derrick	clamp connecti	ion=	w1=	137.5 kips
Structure weight carried per substructure	clamp connectio	on=	w2=	512.5 kips
Frictional resistance per connection due to	o weight=	μw <sub>i</sub> =Ρ <sub>i</sub>		

Consequently, the total slip capacity of a single clamp connection is calculated for various pretension bolt load and summarised in Table 14.

BOLT	BOLT	COEFF. OF	BOLT PRET.	TOT. PRET.	SLIP CAPACITY		TOTAL* SLIP CAPACI	
PRETENS.	(TORQUE)	FRICTION	SLIP CAP.	SLIP CAP.	DUE TO WEIGHT (kips)		ps) PER CLAMP CONNEC	
(T)	(MT)	μ	μΤ=Ρ	nxP=P <sub>⊤</sub>	P <sub>D</sub> P <sub>S</sub>		P <sub>s</sub> (kips)	
(kips))	(Lbft		(kips)	(kips)	DERRICK	SUBSTR.	DERRICK	SUBSTR.
		0.1	7.5	60.0	13.8	51.3	73.8	111.3
75	2500	0.3	22.5	180.0	41.3	153.8	221.3	333.8
		0.5	37.5	300.0	68.8	256.3	368.8	556.3
		0.1	15.0	120.0	13.8	51.3	133.8	171.3
150	5000	0.3	45.0	360.0	41.3	153.8	401.3	513.8
		0.5	75.0	600.0	68.8	256.3	668.8	856.3
		0.1	22.5	180.0	13.8	51.3	193.8	231.3
225	7500	0.3	67.5	540.0	41.3	153.8	581.3	693.8
		0.5	112.5	900.0	68.8	256.3	968.8	1156.3
		0.1	13.7	109.8	13.8	51.3	123.6	161.1
137.3	4576.7	0.3	41.2	329.5	41.3	153.8	370.8	483.3
		0.5	68.7	549.2	68.8	256.3	618.0	805.5

#### Table 14 Connection Slip Capacity VS Bolt Pretension Loading

\* TOTAL SLIP CAPACITY FOR: DERRICK= P<sub>T</sub>+P<sub>D</sub>

SUBSTRUCTURE= P<sub>T</sub>+P<sub>S</sub>

NOTE: 137.3 KIPS IS THE RECOMMENDED AISC PRETENSIONFOR 2" BOLTS

CALCULATED AS A LINEAR FUNCTION BASED ON 1-1/2" BOLTS (AISC Table J3.4).



Dept.

Our Ref.

#### 303859-IM-0001

Date : 15/01/2007

The bolt pretension, the coefficients of friction and the resulting slip resistance capacity of the connection are interrelated and can be represented in several ways. This is demonstrated in the following.

 Table 15
 Pretension, Coefficient of Friction & Connection Capacity

COEF. OF F	RICTION (µ)	0.1	0.1 0.3 0.			
Т	МТ	CONNECT. SLIP CAPACITY $P_T$				
(kips)	(Lbs-ft)	(kips)				
75	2500	60	60 180			
150	5000	120	600			
225	7500	180 540 900				



Figure 5 Bolt Pretension, Coefficient of Friction & Slip Capacity Chart



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

The same results can be represented as follows.

Table 16	Bolt Torque,	<b>Coefficient of</b>	Friction,	Pretension	and Slip	o Caj	pacity	
			,					

	MT	MT	MT	
μ	Lb-ft	Lb-ft	Lb-ft	
	2500	5000	7500	
	Т	Т	Т	
	kips	kips	kips	
	75	150	225	
0.1	60	120	180	
0.3	180	360	540	
0.5	300	600	900	

A graphical representation of Table 16 is shown in Figure 6.



Figure 6 Connection Slip Capacity VS Coefficient of Friction Chart



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

Given that the structural weight adds to the slip resistance capacity of the connection, the slip resistance capacity of an upper derrick connection and that of a substructure connection are different. These capacities are graphically represented below.



Figure 7 Upper Derrick Connection Slip Capacity Chart



Figure 8 Substructure Connection Slip Capacity Chart



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# 4.2 Connection Tensile Capacity

Tensile St	rength of Bolt:	
$R_n = F_u^b \times A$	N <sub>n</sub> (Ref. 4, 0	Chapter 4)
R <sub>n</sub> =	Nominal Strength for	one bolt
$F_u^b =$	Tensile strength of b	olt material
A <sub>n=</sub>	Area through the three	eaded portion of bolt= tensile stress area
A <sub>n=</sub>	.75 A <sub>b</sub>	
$A_{b=}$	bolt gross area	
$R_n = F_u^b x .7$	75 A <sub>b</sub>	
D=	2 in	(bolt Diameter)
A <sub>b</sub> =	3.14 in <sup>2</sup>	
$A_{n=}$	2.355 in <sup>2</sup>	
$F_u^b =$	120 ksi	(AISC, Part 4, Table I-C for 1" A325 bolts)
$F_u^b =$	105 ksi	(AISC, Part 4, Table I-C for 1-1/2" A325 bolts)
Take $F_u^b =$	105 ksi	for 2" Bolts

#### TENSILE CAPACITY WITHOUT PRETENTION:

Bolt Tensile Capacity=	R <sub>n</sub> =	247.3 kips
Connection Tensile Capacity=	nxR <sub>n</sub> =	1978.2 kips

#### TENSILE CAPACITY WITH PRETENTION:

Capacity (kips)= Capacity without Pretension (kips)- Bolt Pretension (kips) n= 8 bolts

R <sub>n</sub>	Т	Τ <sub>B</sub> <sup>*</sup>	T <sub>c</sub> **	
kips	kips	kips	kips	
247.3	75.0	172.3	1378.2	
247.3	137.3	109.9	879.6	(Recom. Pretension, based on AISC Table J 3.7 for 1-1/2" bolts)
247.3	150.0	97.3	778.2	(2x103/1.5=137.3 kips)
247.3	225.0	22.3	178.2	
$T_{B}=R_{n}-T$	&	$*T_{C} = nT_{B}$		-

#### Table 17 Bolts Tensile Capacity per Clamp Connection

In fixed type bolted connections where reactions include moments in three directions, the distribution of tensile forces over the connection bolts vary. One bolt will be subject to higher tension force than the rest of the connection bolts.

Therefore, the integrity of the bolted connection relies on the single bolt that carries the highest tensile load.



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

Based on the bolt size (2") and the recommended AISC Pretension load for fully tightened bolts (Table J3.7):

The Tensile Capacity of the Clamped Connection is:

R<sub>n</sub>-137.3 kips= 109.9 kips per bolt

#### 4.3 Connection Shear Capacity

#### Shear Strength of Bolt:

R <sub>n</sub> =m x τ <sub>u</sub>	x A <sub>b</sub> Eq.7
(Ref. 4, Ch	apter 4)
R <sub>n</sub> =	Nominal Strength for one bolt
$\tau_u$ =.62 $F_u^{\ b}$	= Ultimate shear stress across the gross area $A_b$ of Bolt
m=	Number of shear planes
$F_u^b =$	105 ksi
m=	1

#### Shear Capacity per Bolt=

R<sub>n</sub>= 204.4 kips

If Shear occurs: one side (1/2 the number of bolts in the connection) will carry the shear load, as shown in Figure 3.

Total Clamp Connection Shear Capacity =V<sub>c</sub> =

(n/2)xR<sub>n</sub>= 817.7 kips



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# 5. RIGID MODELS ANALYSIS AND RESULTS

The STRUCAD\*3D finite element software is employed to develop rigid models representing the upper derrick mass only and a combined upper derrick and substructure masses for the purpose of applying wind and dynamic loading to the structure and extracting 6 DOF reactions at the footings of the upper derrick and substructure. Those models are shown below.



#### Figure 9 Combined Upper Derrick & Substructure Rigid Model



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007



#### Figure 10 Upper Derrick Rigid Model

Three Load Cases are included in the Analysis:

- 1- IVAN environmental criteria,
- 2- 100 year hurricane environmental criteria,
- 3- 10 year hurricane environmental criteria.

For each load case, three combinations of accelerations and wind loading on the structure are analysed:

- 1- API-4F recommended 107 knots wind velocity and accelerations derived based on API-4F specifications,
- 2- Wind velocities matching those in the Time Domain analysis and accelerations derived based on API-4F specifications,
- 3- Wind velocities and accelerations from the Time Domain analysis.

In addition, for every wind and acceleration combination from the above, wind and accelerations are considered in three directions:

- 1- Pitch direction (X),
- 2- Roll direction (Y),
- 3- 45° angle direction, which combines 100% of wind and dynamic loading on the structure in (X) & (Y) directions simultaneously and provides the highest wind area exposure for the structure.



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

The reaction forces and moments obtained from the STRUCAD models for all the above cases are summarised below.

Figure 9 shows the nodes location and reference number, for upper derrick and substructure, associated with the reactions.

The reactions included in the Tables are shown as absolute values. The numbers highlighted in the FZ columns represent tension loading on the clamp connection bolts.



Figure 11 Reference Node Numbers and Wind & Accelerations Loading Directions for Upper Derrick & substructure Footings



Dept.

Our Ref.

#### 303859-IM-0001

Date : 15/01/2007

# A- WIND & DYNAMIC LOADING AT 45° ANGLE

Table 18	<b>Reaction Forces &amp; Moments (IVAN</b>	1)
UPPER DE	RICK REACTIONS (IVAN)	

API-4F 107	<b>Y KNOTS W</b>	Direction)				
REFERENCE	FX	FY	FZ	MX	MY	MZ
NODE No	kips	kips	kips	kip-in	kip-in	kip-in
6	120.28	121.98	135.31	101.28	38.32	29.14
5	123.04	123.04	831.14	151.90	151.90	0.00
8	121.98	120.28	135.31	38.32	101.28	29.14
9	121.34	121.34	560.51	88.94	88.94	0.00
API-4F 87.	9 KNOTS W	/IND	(45 Degree	Direction)		
6	104.45	106.14	135.31	100.61	37.65	29.14
5	107.20	107.20	691.78	151.23	151.23	0.00
8	106.14	104.45	135.31	37.65	100.61	29.14
9	105.51	105.51	421.15	88.27	88.27	0.00
TIME DOM	IAIN ANALY	′SIS: 87.9 k	<b>(NOTS WIN</b>	1D	(45 Degree D	irection)
6	101.37	103.06	135.44	97.76	34.74	27.91
5	104.08	104.06	680.54	146.23	146.23	0.00
8	103.06	101.37	135.44	34.74	97.76	27.91
9	102.38	102.38	409.67	83.21	83.21	0.00

### SUBSTRUCTURE REACTIONS (IVAN)

API-4F 107	' KNOTS W	Direction)				
REFERENCE	FΧ	FY	FZ	MX	MY	MZ
NODE No	kips	kips	kips	kip-in	kip-in	kip-in
30	324.06	324.53	122.98	172.22	198.27	77.14
29	334.74	312.71	1865.41	364.77	399.47	155.14
31	330.34	346.09	895.97	577.40	265.46	176.61
32	328.47	334.27	846.45	384.86	332.27	55.67
API-4F 87.	9 KNOTS W	/IND	(45 Degree	Direction)		
30	303.51	303.98	173.19	172.56	197.18	77.14
29	314.19	292.15	1689.67	365.10	398.38	155.14
31	309.78	325.54	845.76	577.07	264.38	176.61
32	307.91	313.71	670.72	384.52	331.19	55.67
TIME DOM	AIN ANALY	'SIS: 87.9 k	KNOTS WIN	ID	(45 Degree D	irection)
30	291.05	291.25	179.02	178.17	186.72	71.70
29	301.48	279.91	1648.14	364.27	381.30	150.06
31	297.26	312.62	830.60	564.60	253.30	170.26
32	295.26	301.27	638.52	378.50	314.72	51.50



Dept.

# Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# Table 19 Reaction Forces & Moments (100 YR) DERRICK REACTIONS (100 YR)

API-4F 107 K	NOTS WIND		(45 Degree D	irection)		
NODE	FX	FY	FZ	MX	MY	MZ
No	kips	kips	kips	kip-in	kip-in	kip-in
6	104.72	106.44	137.47	87.24	23.27	22.89
5	107.28	107.28	775.93	126.99	126.99	0.00
8	106.44	104.72	137.47	23.27	87.24	22.89
9	105.56	105.56	500.99	63.03	63.03	0.00
API-4F 81.3 k	<b>KNOTS WIND</b>		(45 Degree D	irection)		
6	84.14	85.86	137.47	86.37	22.40	22.89
5	86.69	86.69	594.77	126.12	126.12	0.00
8	85.86	84.14	137.47	22.40	86.37	22.89
9	84.97	84.97	319.83	62.16	62.16	0.00
TIME DOMAI	N ANALYSIS:	81.3 KNOTS \	WIND	(45 Degree D	irection)	
6	80.91	82.62	137.09	83.26	19.47	21.59
5	83.41	83.41	582.47	120.75	120.75	0.00
8	82.62	80.91	137.09	19.47	83.26	21.59
9	81.69	81.69	308.29	56.97	56.97	0.00

#### SUBSTRUCTURE REACTIONS (100 YR)

API-4F 107 K	NOTS WIND		(45 Degree D	irection)		
CONNECT.	FX	FY	FZ	MX	MY	MZ
No	kips	kips	kips	kip-in	kip-in	kip-in
30	267.28	265.97	175.77	217.68	148.94	49.58
29	277.05	256.68	1693.11	369.02	321.73	132.79
31	273.59	287.65	849.02	536.25	216.52	149.62
32	270.74	278.36	668.32	384.91	254.15	32.75
API-4F 81.3 k	NOTS WIND		(45 Degree D	irection)		
30	240.56	239.25	241.04	218.11	147.53	49.58
29	250.33	229.96	1464.66	369.45	320.32	132.79
31	246.87	260.93	783.75	535.81	215.11	149.62
32	244.02	251.64	439.86	384.47	252.74	32.75
TIME DOMAI	N ANALYSIS:	81.3 KNOTS \	WIND	(45 Degree D	irection)	
30	227.51	225.86	250.59	226.53	136.35	43.56
29	237.06	217.08	1424.62	371.05	302.67	127.80
31	133.80	247.49	771.33	525.29	203.74	143.32
32	130.77	238.71	402.70	380.76	235.28	28.04



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Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# Table 20Reaction Forces & Moments (10YR)UPPER DERRICK REACTIONS (10YR)

API-4F 107 K	NOTS WIND		(45 Degree D	irection)			
REFERENCE	FX	FY	FZ	MX	MY	MZ	
NODE No	kips	kips	kips	kip-in	kip-in	kip-in	
6	79.24	80.95	137.05	63.30	0.47	12.63	
5	81.41	81.41	681.46	85.24	85.24	0.00	
8	80.95	79.24	137.05	0.47	63.30	12.63	
9	79.70	79.70	407.37	21.47	21.47	0.00	
API-4F 50.9 KNOTS WIND (45 Degree Direction)							
6	41.55	43.27	137.05	61.71	2.06	12.63	
5	43.72	43.72	349.84	83.64	83.64	0.00	
8	43.27	41.55	137.05	2.06	61.71	12.63	
9	42.01	42.01	75.75	19.88	19.88	0.00	
TIME DOMAI	N ANALYSIS:	50.9 KNOTS \	WIND	(45 Degree D	irection)		
6	39.65	41.36	137.09	59.94	3.85	11.87	
5	41.80	41.80	342.87	80.55	80.55	0.00	
8	41.36	39.65	137.09	3.85	59.94	11.87	
9	40.08	40.08	68.69	16.76	16.76	0.00	

#### SUBSTRUCTURE REACTIONS (10 YR)

API-4F 107 K	NOTS WIND		(45 Degree D	virection)		
REFERENCE	FX	FY	FZ	MX	MY	MZ
NODE No	kips	kips	kips	kip-in	kip-in	kip-in
30	174.00	169.86	256.05	287.59	68.29	4.93
29	182.20	164.73	1403.87	371.69	193.63	95.49
31	180.29	191.48	765.56	464.00	135.66	104.66
32	175.91	186.35	382.25	379.90	126.25	4.24
API-4F 50.9 KNOTS WIND (45 Degree Direction)						
30	125.09	120.95	375.52	288.39	65.71	4.93
29	133.29	115.82	985.69	372.48	191.04	95.49
31	131.38	142.56	646.09	463.20	133.08	104.66
32	127.00	137.43	35.93	379.11	123.67	4.24
TIME DOMAI	N ANALYSIS:	50.9 KNOTS \	WIND	(45 Degree D	irection)	
30	117.59	113.24	382.05	294.00	59.23	1.36
29	125.67	108.40	963.45	373.83	180.92	92.67
31	123.88	134.86	639.87	457.81	126.62	101.12
32	119.38	130.03	58.48	377.98	113.53	7.09



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Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# **B- WIND & DYNAMIC LOADING IN (X) DIRECTION**

The upper derrick and substructure reaction forces and moments pertaining to tension loading on the clamped connections are summarised in the following tables.

Table 21 Reaction Forces & Moments (WAN), X-Direction Loading								
UPPER DE	RRICK RE	ACTIONS (	<u>IVAN)</u>	SUBSTRUCTURE REACTIONS (IVAN)				
	API-4F 107 K	NOTS WIND			(0 Degree Dir	ection)		
REFERENCE	FZ	MX	MY	REFERENCE	FZ	MX	MY	
NODE No	kips	kip-in	kip-in	NODE No	kips	kip-in	kip-in	
6	212.60	6.17	63.63	30	361.73	278.54	265.26	
5	483.23	56.79	126.59	29	1380.69	471.09	332.46	
8	483.23	56.79	126.59	31	1380.68	471.08	332.46	
9	212.60	6.17	63.63	32	361.73	278.54	265.27	
API-4F 87.9 KNOTS WIND (0 Degree Direction)								
6	142.92	62.96	62.96	30	248.76	278.54	264.20	
5	413.54	125.92	125.92	29	1267.70	471.08	331.38	
8	413.55	125.92	125.92	31	1267.70	471.08	331.37	
9	142.92	62.96	62.96	32	248.76	278.54	264.18	
	TIME DOMAIN	ANALYSIS:	87.9 KNOTS \	WIND	(0 Degree Dir	ection)		
6	137.12	7.28	58.97	30	229.75	278.33	250.72	
5	407.99	55.74	121.99	29	1239.37	464.40	317.30	
8	407.99	55.74	121.99	31	1239.37	464.40	317.30	
9	137.12	7.28	58.97	32	229.74	278.33	250.70	

### Table 21 Reaction Forces & Moments (IVAN), X-Direction Loading

Table 22 Reaction Forces & Moments (100-YR), X-Direction Loading

				· · · · ·			•	
UPPER DE	UPPER DERRICK REACTIONS (100 YR) SUBSTRUCTURE REACTIONS (100 YR)							
	API-4F 107 K	NOTS WIND		(0 Degree Direction)				
REFERENCE	FZ	MX	MY	REFERENCE	FZ	MX	MY	
NODE No	kips	kip-in	kip-in	NODE No	kips	kip-in	kip-in	
6	181.75	12.10	43.15	30	246.27	301.29	201.54	
5	456.70	51.86	107.12	29	1271.06	452.63	269.13	
8	456.70	51.86	107.12	31	1271.06	452.63	269.13	
9	181.76	12.11	43.15	32	246.27	301.29	201.54	
	<b>NOTS WIND</b>	(0 Degree Di	ection)					
6	91.18	12.11	42.28	30	99.40	301.29	200.13	
5	366.12	51.86	106.25	29	1124.20	452.60	267.71	
8	366.12	51.86	106.25	31	1124.20	452.60	267.71	
9	91.18	12.11	42.28	32	99.40	301.29	200.13	
	TIME DOMAI	N ANALYSIS:	81.3 KNOTS	WIND	(0 Degree Di	ection)		
6	85.60	13.15	38.22	30	76.05	303.64	185.82	
5	359.78	50.64	102.01	29	1097.98	448.18	253.21	
8	359.78	50.64	102.01	31	1097.98	448.18	253.21	
9	85.60	13.15	38.22	32	76.05	303.64	185.82	



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Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# Table 23 Reaction Forces & Moments (10-YR), X-Direction Loading

UPPER DE	UPPER DERRICK REACTIONS (10-YR)				SUBSTRUCTURE REACTIONS (10-YR)			
	API-4F 107 K	NOTS WIND		(0 Degree Direction)				
REFERENCE	FZ	MX	MY	REFERENCE	FZ	MX	MY	
NODE No	kips	kip-in	kip-in	NODE No	kips	kip-in	kip-in	
6	135.16	20.92	10.49	30	63.10	333.75	97.27	
5	409.25	42.85	74.27	29	1084.70	417.84	164.64	
8	409.25	42.85	74.27	31	1084.70	417.84	164.64	
9	135.16	20.92	10.49	32	63.10	333.75	97.27	
	API-4F 50.9 k	NOTS WIND		(0 Degree Dir	rection)			
6	30.65	20.92	8.90	30	205.73	333.74	94.69	
5	243.45	42.85	72.67	29	815.89	417.84	162.06	
8	243.45	42.85	72.67	31	815.89	417.84	162.06	
9	30.65	20.92	8.90	32	205.73	333.74	94.69	
	TIME DOMAI	N ANALYSIS:	50.9 KNOTS	WIND	(0 Degree Dir	rection)		
6	34.20	21.59	6.45	30	220.26	335.99	86.38	
5	239.98	42.20	70.24	29	801.66	415.82	153.77	
8	239.98	42.20	70.24	31	801.66	415.82	153.77	
9	34.20	21.59	6.45	32	220.26	335.99	86.38	

# C- WIND & DYNAMIC LOADING IN (Y) DIRECTION

#### Table 24 Reaction Forces & Moments (IVAN), Y-Direction Loading

UPPER DE	UPPER DERRICK REACTIONS (IVAN)				SUBSTRUCTURE REACTIONS (IVAN)			
	API-4F 107 K	NOTS WIND		(90 Degree Direction)				
REFERENCE	FZ	MX	MY	REFERENCE	FZ	MX	MY	
NODE No	kips	kip-in	kip-in	NODE No	kips	kip-in	kip-in	
6	483.23	126.59	56.79	30	994.20	268.50	100.60	
5	483.23	126.59	56.79	29	994.20	268.50	100.60	
8	212.60	63.63	6.17	31	24.76	481.13	33.41	
9	212.60	63.63	6.17	32	24.76	481.13	33.41	
	API-4F 87.9 K	NOTS WIND			(90 Degree D	irection)		
6	413.55	125.92	56.79	30	931.43	268.83	100.60	
5	413.55	125.92	56.79	29	931.43	268.83	100.60	
8	142.92	62.96	6.17	31	87.52	480.80	33.41	
9	142.92	62.96	6.17	32	87.52	480.80	33.41	
	TIME DOMAIN	NANALYSIS:	87.9 KNOTS \	WIND	(90 Degree D	irection)		
6	407.99	121.99	55.74	30	876.26	249.53	87.82	
5	407.99	121.99	55.74	29	876.26	249.53	87.82	
8	137.12	58.97	7.28	31	133.37	493.24	21.24	
9	137.12	58.97	7.28	32	133.37	493.24	21.24	



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Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# Table 25 Reaction Forces & Moments (100-YR), Y-Direction Loading

UPPER DE	JPPER DERRICK REACTIONS (100 YR)				SUBSTRUCTURE REACTIONS (100 YR)			
	API-4F 107 K	NOTS WIND		(90 Degree Direction)				
REFERENCE	FZ	MX	MY	REFERENCE	FZ	MX	MY	
NODE No	kips	kip-in	kip-in	NODE No	kips	kip-in	kip-in	
6	456.70	107.12	51.86	30	934.44	293.35	86.40	
5	456.70	107.12	51.86	29	934.44	293.35	86.40	
8	181.76	43.15	12.11	31	90.35	460.58	18.82	
9	181.76	43.15	12.10	32	90.35	460.58	18.82	
	API-4F 81.3 k	<b>NOTS WIND</b>			(90 Degree D	irection)		
6	366.12	106.25	51.86	30	852.85	293.78	86.40	
5	366.12	106.25	51.86	29	852.85	293.78	86.40	
8	91.18	42.28	12.10	31	171.95	460.14	18.82	
9	91.18	42.28	12.10	32	171.95	460.14	18.82	
	TIME DOMAI	N ANALYSIS:	81.3 KNOTS	WIND	(90 Degree D	irection)		
6	359.77	102.01	50.64	30	837.60	298.79	83.16	
5	359.77	102.01	50.64	29	837.60	298.79	83.16	
8	85.60	38.22	13.15	31	184.32	453.02	15.77	
9	85.60	38.22	13.15	32	184.32	453.02	15.77	

#### Table 26 Reaction Forces & Moments (10-YR), Y-Direction Loading

UPPER DE	JPPER DERRICK REACTIONS (10-YR)				SUBSTRUCTURE REACTIONS (10-YR)			
	API-4F 107 K	NOTS WIND		(90 Degree Direction)				
REFERENCE	EFERENCE FZ MX MY			REFERENCE	FZ	MX	MY	
NODE No	kips	kip-in	kip-in	NODE No	kips	kip-in	kip-in	
6	409.25	74.27	42.85	30	829.96	329.64	62.67	
5	409.25	74.27	42.85	29	829.96	329.64	62.67	
8	135.16	10.45	20.92	31	191.66	421.95	4.70	
9	135.16	10.45	20.92	32	191.66	421.95	4.70	
	API-4F 50.9 M	NOTS WIND			(90 Degree D	irection)		
6	243.45	72.68	42.85	30	680.61	330.43	62.67	
5	243.45	72.68	42.85	29	680.61	330.43	62.67	
8	30.65	8.90	20.92	31	341.01	421.00	4.70	
9	30.65	8.90	20.92	32	341.01	421.00	4.70	
	TIME DOMAI	N ANALYSIS:	50.9 KNOTS	WIND	(90 Degree D	irection)		
6	239.98	70.24	42.20	30	672.75	333.92	60.85	
5	239.98	70.24	42.20	29	672.75	333.92	60.85	
8	34.20	6.46	21.59	31	349.18	417.89	6.54	
9	34.20	6.46	21.59	32	349.18	417.89	6.54	



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

#### 6. CLAMP CONNECTIONS LOADS VS CAPACITY

Depending on the connection orientation, FX & FY forces will cause a shearing effect on the bolts (once slipping resistance is exceeded) or slipping effect only. The connections orientation for upper derrick and substructure are shown in Figure 12.The force FZ causes tension or compression loading on the bolts

The reaction moments will add to the above loading. MX & MY will affect the tension/compression loading while MZ adds to the bolts shear load. Due to the special configuration of the clamped connections, it is most likely that only the two outer bolts will be affected by the torsion moment MZ. This is depicted in Figure 12.



(Note: The above sketches do not reflect dimensions to scale)

Details pertaining to bolt loading calculations are presented in Tables format for the different environmental criteria.



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

#### 6.1 **IVAN Load Case**

#### **Bolts Shear/Slip Loading** 6.1.1

d=	28.4 in	(diagonal distance between outer bolts)				
p=	6 in	(bolt Spaci	ng)			
α=	39.29	sinα=	0.633	cosα=	0.774	
β=	50.71	sinβ=	0.774	cosβ=	0.633	

#### Table 27 **Total Lateral Forces per Connection (IVAN)**

	CONNEC	S (IVAN)	TOTAL	FORCE*			
		UPI	PER DERR	ICK		$\Sigma X$ -FORCES	ΣY-FORCES
NODE	MZ	MZ/d=F	Fsinα= Fx	Fcosα= Fy	WIND & ACCELERATION	kips	kips
No	kin	kips	kips	kips	COMBINATION	SHEAR	SLIP
6	29.14	1.03	0.65	0.79	(I)	120.93	122.77
5	0.00	0.00	0.00	0.00	API-4F ACCEL. &	123.04	123.04
8	29.14	1.03	0.65	0.79	107 KNOTS WIND	122.63	121.07
9	0.00	0.00	0.00	0.00		121.34	121.34
6	29.14	1.03	0.65	0.79	(II)	105.10	106.93
5	0.00	0.00	0.00	0.00	API-4F ACCEL. &	107.20	107.20
8	29.14	1.03	0.65	0.79	87.9 KNOTS WIND	106.79	105.24
9	0.00	0.00	0.00	0.00		105.51	105.51
6	27.91	0.98	0.62	0.76	(III)	101.99	103.82
5	0.00	0.00	0.00	0.00	TIME DOMAIN ACCEL.&	104.08	104.06
8	27.91	0.98	0.62	0.76	87.9 KNOTS WIND	103.68	102.13
9	0.00	0.00	0.00	0.00		102.38	102.38
	SUBSTRUCTURE				$\Sigma X$ -FORCES	$\Sigma Y$ -FORCES	
NODE	MZ	MZ/d=F	Fsinβ= Fx	Fcosβ=Fy	WIND & ACCELERATION	kips	kips
No	kip-in	kips	kips	kips	COMBINATION	SLIP	SHEAR
30	77.14	2.71	2.10	1.72	(I)	326.16	326.25
29	155.14	5.46	4.22	3.46	API-4F ACCEL. &	338.96	316.17
31	176.61	6.21	4.81	3.93	107 KNOTS WIND	335.15	350.02
32	55.67	1.96	1.52	1.24		329.99	335.51
30	77.14	2.71	2.10	1.72	(II)	305.61	305.70
29	155.14	5.46	4.22	3.46	API-4F ACCEL. &	318.41	295.61
31	176.61	6.21	4.81	3.93	87.9 KNOTS WIND	314.59	329.47
32	55.67	1.96	1.52	1.24		309.43	314.95
30	71.70	2.52	1.95	1.60	(111)	293.00	292.85
29	150.06	5.28	4.09	3.34	TIME DOMAIN ACCEL.&	305.57	283.25
31	170.26	5.99	4.64	3.79	87.9 KNOTS WIND	301.90	316.41
32	51.50	1.81	1.40	1.15		296.66	302.42

\*TOTAL FORCE (X) = FX (from Table 18) + Fx (from Table 27) TOTAL FORCE (Y) = FY (from Table 18) + Fy (from Table 27)

The numbers highlighted in Table 27 are the maximum shear (V<sub>max</sub>) and maximum slip (P<sub>max</sub>) loads per clamp connection for this case.



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# 6.1.2 Connection Shear/Slip Check (Ivan Loading)

From section 4.3, it was determined that the ultimate shear capacity per connection is 817.7 kips.

By dividing that number by the highest shear load per connection, the factors of safety are determined and included in Table 28 for Ivan load case.

(IVAN) REACTIONS FROM:	UPPER DERRICK (FS <sub>V1</sub> )	SUBSTRUCTURE (FSv2)
API-4F ACC. + 107 KNOTS WIND	6.65	2.34
API-4F ACC. + 87.9 KNOTS WIND	7.63	2.48
TIME DM. ACC. + 87.9 KNOTS WIND	7.86	2.58

Table 28	Bolts Shear Factor of Safety	per Connection (IVAN)
----------	------------------------------	-----------------------

Where  $FSv_i = Factor of Safety = V_C / V_{max}$ .

Similar to the above procedure, the highest force in slip direction per connection for upper derrick and substructure are compared with the various connection slip capacities resulting from varying the coefficient of friction & pretension (Section 4.1). The factors of safety are calculated. The connections having a factor of safety less than one (i.e. loading exceeds the capacity) indicate failure of the connection.



Dept.

# Our Ref.

### 303859-IM-0001

Date : 15/01/2007

Table 29 Slip Check & Factor of Safety per Connection (IVAN)										
	UP	PER DERR	ICK	SU	BSTRUCTU	JRE				
	AISC PR	ETENSION=1	37.3 kips	-						
COEFFICIENT OF FRICTION	0.1	0.3	0.5	0.1	0.3	0.5				
SLIP CAPACITY (kips)	123.6	370.8	618.0	161.1	483.3	805.5				
(IVAN) REACTIONS FROM:	FACTO	R OF SAFET	( (FS <sub>PD</sub> )	FACTO	R OF SAFET	Y (FS <sub>PS</sub> )				
API-4F ACC.+ 107 KNOTS WIND	1.0	3.0	5.0	0.5	1.4	2.4				
API-4F ACC.+ 87.9 KNOTS WIND	1.2	3.5	5.8	0.5	1.5	2.5				
TIME DM Ac+ 87.9 KNOTS WIND	1.2	3.6	5.9	0.5	1.6	2.6				
PRETENSION=75.0 kips										
COEFFICIENT OF FRICTION	0.1	0.3	0.5	0.1	0.3	0.5				
SLIP CAPACITY (kips)	73.8	221.3	368.8	111.3	333.8	556.3				
(IVAN) REACTIONS FROM:	FACTO	R OF SAFET	イ (FS <sub>PD</sub> )	FACTOR OF SAFETY (FS <sub>PS</sub> )						
API-4F ACC.+ 107 KNOTS WIND	0.60	1.80	3.00	0.33	0.98	1.64				
API-4F ACC.+ 87.9 KNOTS WIND	0.69	2.06	3.44	0.35	1.05	1.75				
TIME DM Ac+ 87.9 KNOTS WIND	0.71	2.13	3.54	0.36	1.05	1.82				
	PRET	ENSION= 150	) kips							
COEFFICIENT OF FRICTION	0.1	0.3	0.5	0.1	0.3	0.5				
SLIP CAPACITY (kips)	133.8	401.3	668.8	171.3	513.8	856.3				
(IVAN) REACTIONS FROM:	FACTO	R OF SAFET	(FS <sub>PD</sub> )	FACTO	R OF SAFET	Ү (FS <sub>PS</sub> )				
API-4F ACC.+ 107 KNOTS WIND	1.09	3.26	5.44	0.51	1.52	2.53				
API-4F ACC.+ 87.9 KNOTS WIND	1.25	3.74	6.24	0.54	1.61	2.69				
TIME DM Ac+ 87.9 KNOTS WIND	1.29	3.86	6.43	0.56	1.68	2.80				
	PRET	ENSION= 225	i kips							
COEFFICIENT OF FRICTION	0.1	0.3	0.5	0.1	0.3	0.5				
SLIP CAPACITY (kips)	193.8	581.3	968.8	231.3	693.8	1156.3				
(IVAN) REACTIONS FROM:	FACTO	R OF SAFET	(FS <sub>PD</sub> )	FACTO	R OF SAFET	Y (FS <sub>PS</sub> )				
API-4F ACC.+ 107 KNOTS WIND	1.57	4.72	7.87	0.68	2.05	3.41				
API-4F ACC.+ 87.9 KNOTS WIND	1.81	5.42	9.04	0.73	2.18	3.63				
TIME DM Ac+ 87.9 KNOTS WIND	1.86	5.59	9.31	0.76	2.27	3.78				

Where: FS<sub>PD</sub>= Slip Factor of Safety for Derrick connection =  $P_D / P_{max}$ , & FS<sub>PS</sub>= Slip Factor of Safety for Substructure connection =  $P_S / P_{max}$ .

The same procedure is adopted to calculate the factors of safety for the cases of 100 year and 10 year hurricanes.



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# 6.1.3 Bolts Tension Loading & Capacity Check

#### Maximum tension force per bolt= Sum of tension forces (T1+T2+T3) Where: T1-Tension force per bolt due to FZ

11=	Tension for	ce per boil d	лие ю г	-2				
T2=	Tension for	ce per bolt o	due to M	ЛХ				
Т3=	Tension for	ce per bolt o	due to M	ЛY				
FOR UPPE	ER DERRICI	<b>CONNEC</b>	TION					
T1=	FZ/n=	connection	tensior	n reaction/ numb	per of bolts			
T2=	MX x $y_{max}/\Sigma y_i^2$							
T3=	MY / ((n/2)H	l)						
Where:	n=	8	bolts					
	y <sub>max</sub> =	9	in					
	H=	22	in					
	y <sub>i</sub> (in)	$y_i^2$ (in <sup>2</sup> )						
	3	9						
	9	81						
	$\Sigma y_i^2 = 4x(9+8)$	31)=	-	360 in <sup>2</sup>	(for 8 bolts)			
FOR SUBS	STRUCTUR	E CONNEC	TION					
T1=	FZ/n=	connection	tensior	n reaction/ num	per of bolts			
T2=	MY x x <sub>max</sub> / X	$\Sigma x_i^2$						
Т3=	MX / ((n/2)H	H)						
Where:	x <sub>max</sub> =	9	in					
	H=	22	in					
	$\Sigma x_i^2 = 4x(9+8)$	81)=		360 in <sup>2</sup>	(for 8 bolts)			

Connection total tensile forces are calculated as the sum of forces due to tension force and moments. Three directions for the wind and dynamic loading on the structures are considered. These directions include Pitch ( $0^\circ$ ) direction, Roll ( $90^\circ$ ) direction and  $45^\circ$  direction which include a combination of Pitch and Roll. The later case is the most critical for tension loading on the clamps bolts

The results of those calculations are summarised in the following Tables of this Section. These Tables also include the factors of safety resulting from comparing actual tension forces on the bolts to the ultimate tensile capacities of the connection derived for the various bolt pretension cases discussed in section 4.2.



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# A- WIND & DYNAMIC LOADING AT 45° ANGLE

# Table 30Bolt Tension Calculations & FS per Connection (IVAN) for 137.3 kips PretensionBOLT TENSILE CAPACITY=109.9 kips

	IVA	N REACTIC	ONS		TENSION	FORCES		FACTOR			
LOAD COMBIN.	FZ	MX	MY	T1	T2	Т3	Т	OF			
	kips	kip-in	kip-in	kips	kips	kips	kips	SAFETY			
UPPER DERRICK											
API-4F ACCEL. &											
107 KNOTS WIND	560.51	88.94	88.94	70.06	2.22	1.01	73.30	1.50			
API-4F ACCEL. &											
87.9 KNOTS WIND	421.15	88.27	88.27	52.64	2.21	1.00	55.85	1.97			
TIME-DM ACCEL. &											
87.9 KNOTS WIND	409.67	83.21	83.21	51.21	2.08	0.95	54.23	2.03			
		รเ	JBSTRUCT	URE							
API-4F ACCEL. &											
107 KNOTS WIND	846.45	384.86	332.27	105.81	8.31	4.37	118.49	0.93			
API-4F ACCEL. &											
87.9 KNOTS WIND	670.72	384.52	331.19	83.84	8.28	4.37	96.49	1.14			
TIME-DM ACCEL. &											
87.9 KNOTS WIND	638.52	378.50	314.72	79.82	7.87	4.30	91.98	1.20			

# Table 31Bolt Tension Calculations & FS per Connection (IVAN) for 75 kips PretensionBOLT TENSILE CAPACITY=172.3 kips

	IVAN REACTIONS TENSION FORCES F/					FACTOR		
LOAD COMBIN.	FZ	MX	MY	T1	T2	Т3	Т	OF
	kips	kip-in	kip-in	kips	kips	kips	kips	SAFETY
		U	PPER DER	RICK				
API-4F ACCEL. &								
107 KNOTS WIND	560.51	88.94	88.94	70.06	2.22	1.01	73.30	2.35
API-4F ACCEL. &								
87.9 KNOTS WIND	421.15	88.27	88.27	52.64	2.21	1.00	55.85	3.08
TIME-DM ACCEL. &								
87.9 KNOTS WIND	409.67	83.21	83.21	51.21	2.08	0.95	54.23	3.18
		SI	JBSTRUCT	URE				
API-4F ACCEL. &								
107 KNOTS WIND	846.45	384.86	332.27	105.81	8.31	4.37	118.49	1.45
API-4F ACCEL. &								
87.9 KNOTS WIND	670.72	384.52	331.19	83.84	8.28	4.37	96.49	1.79
TIME-DM ACCEL. &								
87.9 KNOTS WIND	638.52	378.50	314.72	79.82	7.87	4.30	91.98	1.87



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# Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# Table 32Bolt Tension Calculations & FS per Connection (IVAN) for 150 kips PretensionBOLT TENSILE CAPACITY=97.3 kips

	IVAN REACTIONS TENSION FORCES							FACTOR			
LOAD COMBIN.	FZ	MX	MY	T1	T2	Т3	Т	OF			
	kips	kip-in	kip-in	kips	kips	kips	kips	SAFETY			
UPPER DERRICK											
API-4F ACCEL. &											
107 KNOTS WIND	560.51	88.94	88.94	70.06	2.22	1.01	73.30	1.33			
API-4F ACCEL. &											
87.9 KNOTS WIND	421.15	88.27	88.27	52.64	2.21	1.00	55.85	1.74			
TIME-DM ACCEL. &											
87.9 KNOTS WIND	409.67	83.21	83.21	51.21	2.08	0.95	54.23	1.79			
		Sl	JBSTRUCT	URE							
API-4F ACCEL. &											
107 KNOTS WIND	846.45	384.86	332.27	105.81	8.31	4.37	118.49	0.82			
API-4F ACCEL. &											
87.9 KNOTS WIND	670.72	384.52	331.19	83.84	8.28	4.37	96.49	1.01			
TIME-DM ACCEL. &											
87.9 KNOTS WIND	638.52	378.50	314.72	79.82	7.87	4.30	91.98	1.06			

Table 33	<b>Bolt Tension Calculations &amp; F</b>	S per Connection (IVAN) for 225 kips Pretension
BOLT TENS	ILE CAPACITY=	22.3 kips

	IVA	N REACTIO	IONS TENSION FORCES					FACTOR			
LOAD COMBIN.	FZ	MX	MY	T1	T2	Т3	Т	OF			
	kips	kip-in	kip-in	kips	kips	kips	kips	SAFETY			
UPPER DERRICK											
API-4F ACCEL. &											
107 KNOTS WIND	560.51	88.94	88.94	70.06	2.22	1.01	73.30	0.30			
API-4F ACCEL. &											
87.9 KNOTS WIND	421.15	88.27	88.27	52.64	2.21	1.00	55.85	0.40			
TIME-DM ACCEL. &											
87.9 KNOTS WIND	409.67	83.21	83.21	51.21	2.08	0.95	54.23	0.41			
		รเ	JBSTRUCT	URE							
API-4F ACCEL. &											
107 KNOTS WIND	846.45	384.86	332.27	105.81	8.31	4.37	118.49	0.19			
API-4F ACCEL. &											
87.9 KNOTS WIND	670.72	384.52	331.19	83.84	8.28	4.37	96.49	0.23			
TIME-DM ACCEL. &											
87.9 KNOTS WIND	638.52	378.50	314.72	79.82	7.87	4.30	91.98	0.24			



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

Calculations for the tensile loading of upper derrick and substructure clamps bolts are performed in the same fashion as detailed above for the cases of wind and dynamic loading on the structure in the (X) and (Y) directions A summary of the resulting factors of safety for the three loading directions is given below.

# 1- IVAN LOAD CASE

LOADING DIR	ECTION		45-DEGR	EE LOADIN	IG		D-DEGREE	LOADING			90-DEGRE	E LOADING	ì
BOLT TE	ENSILE	109.9	172.3	97.3	22.3	109.9	172.3	97.3	22.3	109.9	172.3	97.3	22.3
CAPA	CITY	kips	kips	kips	kips	kips	kips	kips	kips	kips	kips	kips	kips
LOA	Ó		FACTOR	OF SAFET	Ý	F	ACTOR OI	F SAFETY	-		FACTOR C	F SAFETY	-
COMBIN	ATION	UPPER DERRICK FOOTINGS			UPP	ER DERRIC	CK FOOTIN	GS	UPI	PER DERR	ICK FOOTII	NGS	
API-4F	ACCEL. &	1.50	2.35	1.33	0.30	4.00	6.28	3.54	0.81	3.89	6.10	3.45	0.79
107 KNOTS	WIND												
API-4F	ACCEL. &	1.97	3.08	1.74	0.40	5.87	9.20	5.19	1.19	5.64	8.83	4.99	1.14
87.9 KNOTS	WIND												
TIME-DM	ACCEL. &	2.03	3.18	1.79	0.41	6.11	9.58	5.41	1.24	5.88	9.21	5.20	1.19
87.9 KNOTS	WIND												
		SL	JBSTRUCT	URE FOOT	INGS	SUB	STRUCTUR	RE FOOTIN	GS	SUBSTRUCTURE FOOTINGS			
API-4F	ACCEL. &	0.93	1.45	0.82	0.19	2.00	3.13	1.77	0.41	17.44	27.33	15.43	3.53
107 KNOTS	WIND												
API-4F	ACCEL. &	1.14	1.79	1.01	0.23	2.69	4.22	2.38	0.55	17.46	27.35	15.44	3.54
87.9 KNOTS	WIND												
TIME-DM	ACCEL. &	1.20	1.87	1.06	0.24	2.88	4.52	2.55	0.58	17.92	28.08	15.85	3.63
87.9 KNOTS	WIND												

#### Table 34 Summary of Tensile Factors of Safety: IVAN Load Case

In Table 34 and similar Tables of the following Sections, the highlighted numbers with a numeric value less than one indicate bolt failure due to tension forces exceeding the ultimate tensile strength of the bolts.



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# 6.2 100 Year Hurricane Load Case

In a similar fashion to that described in Section 6.1, the connections loadings and factor of safety calculations for the 100 Year hurricane load case are determined and included in this Section.

# 6.2.1 Bolts Shear/Slip Loading

Table 35 Total Shear/Slip Forces per Connection (100 YF	!)
---	----

	CONNECTION TOTAL LATERAL FORCES (100 YR)										
		UP	PER DERR	ICK		ΣX-FORCES	ΣY-FORCES				
NODE REF.	MZ	MZ/d=F	Fsinα= Fx	Fcosα= Fy	WIND & ACCELERATION	kips	kips				
No	kin	kips	kips	kips	COMBINATION	SHEAR	SLIP				
6	22.89	0.81	0.51	0.62	(I)	105.23	107.06				
5	0.00	0.00	0.00	0.00	API-4F ACCEL. &	107.28	107.28				
8	22.89	0.81	0.51	0.62	107 KNOTS WIND	106.95	105.34				
9	0.00	0.00	0.00	0.00		105.56	105.56				
6	22.89	0.81	0.51	0.62	(II)	84.65	86.48				
5	0.00	0.00	0.00	0.00	API-4F ACCEL. &	86.69	86.69				
8	22.89	0.81	0.51	0.62	81.3 KNOTS WIND	86.37	84.76				
9	0.00	0.00	0.00	0.00		84.97	84.97				
6	21.59	0.76	0.48	0.59	(III)	81.39	83.21				
5	0.00	0.00	0.00	0.00	TIME DOMAIN ACCEL.&	83.41	83.41				
8	21.59	0.76	0.48	0.59	81.3 KNOTS WIND	83.10	81.50				
9	0.00	0.00	0.00	0.00		81.69	81.69				
		SU	BSTRUCTL	JRE		ΣX-FORCES	$\Sigma Y$ -FORCES				
NODE REF.	MZ	MZ/d=F	Fsinβ= Fx	Fcosβ= Fy	WIND & ACCELERATION	kips	kips				
No	kin	kips	kips	kips	COMBINATION	SLIP	SHEAR				
30	49.58	1.74	1.35	1.10	(I)	268.63	267.07				
29	132.79	4.67	3.62	2.96	API-4F ACCEL. &	280.67	259.64				
31	149.62	5.26	4.07	3.33	107 KNOTS WIND	277.66	290.98				
32	32.75	1.15	0.89	0.73		271.63	279.09				
30	49.58	1.74	1.35	1.10	(II)	241.91	240.35				
29	132.79	4.67	3.62	2.96	API-4F ACCEL. &	253.95	232.92				
31	149.62	5.26	4.07	3.33	81.3 KNOTS WIND	250.94	264.26				
32	32.75	1.15	0.89	0.73		244.91	252.37				
30	43.56	1.53	1.19	0.97	(III)	228.70	226.83				
29	127.80	4.50	3.48	2.85	TIME DOMAIN ACCEL.&	240.54	219.93				
31	143.32	5.04	3.90	3.19	81.3 KNOTS WIND	137.70	250.68				
32	28.04	0.99	0.76	0.62		131.53	239.33				



Dept.

Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# 6.2.2 Connection Shear/Slip Check

Table 36 I	Bolts Shear Factor of Safety	per Connection (100	YR)	
(100 YR) REAC	TIONS FROM:	UPPER DERRICK (FS <sub>V1</sub> )	SUBSTRUCTURE (FS <sub>V2</sub> )	
API-4F ACCL. +	107 KNOTS WIND	7.62	2.81	
API-4F ACCL. +	81.3 KNOTS WIND	9.43	3.09	
TIME DOM. AC	CL. + 81.3 KNOTS WIND	9.80	3.26	

# Table 37 Slip Factor of Safety per Connection (100 YR)

	UPPER DERRICK			SUBSTRUCTURE			
	AISC PR	ETENSION=1	37.3 kips				
COEFFICIENT OF FRICTION	0.1	0.3	0.5	0.1	0.3	0.5	
SLIP CAPACITY (kips)	123.6	370.8	618.0	161.1	483.3	805.5	
(100 YR) REACTIONS FROM:	FAC	TOR OF SAF	ETY	FAC	TOR OF SAF	ETY	
API-4F ACC+ 107 KNOTS WIND	1.15	3.46	5.76	0.57	1.72	2.87	
API-4F ACC+ 81.3 KNOTS WIND	1.43	4.28	7.13	0.63	1.90	3.17	
TIME DM.Ac + 81.3 KNOTS WIND	1.48	4.45	7.41	0.67	2.01	3.35	
	PRE	TENSION=75	kips				
COEFFICIENT OF FRICTION	0.1	0.3	0.5	0.1	0.3	0.5	
SLIP CAPACITY (kips)	73.8	221.3	368.8	111.3	333.8	556.3	
(100 YR) REACTIONS FROM:	FAC	TOR OF SAF	ETY	FAC	CTOR OF SAF	ETY	
API-4F ACC+ 107 KNOTS WIND	0.69	2.06	3.44	0.40	1.19	1.98	
API-4F ACC+ 81.3 KNOTS WIND	0.85	2.55	4.25	0.44	1.31	2.19	
TIME DM.Ac + 81.3 KNOTS WIND	0.88	2.65	4.42	0.46	1.39	2.31	
	PRET	ENSION=150	kips				
COEFFICIENT OF FRICTION	0.1	0.3	0.5	0.1	0.3	0.5	
SLIP CAPACITY (kips)	133.8	401.3	668.8	171.3	513.8	856.3	
(100 YR) REACTIONS FROM:	FAC	TOR OF SAF	ETY	FAC	CTOR OF SAF	ETY	
API-4F ACC+ 107 KNOTS WIND	1.25	3.74	6.23	0.61	1.83	3.05	
API-4F ACC+ 81.3 KNOTS WIND	1.54	4.63	7.71	0.67	2.02	3.37	
TIME DM.Ac + 81.3 KNOTS WIND	1.60	4.81	8.02	0.71	2.14	3.56	
	PRET	ENSION=225	kips				
COEFFICIENT OF FRICTION	0.1	0.3	0.5	0.1	0.3	0.5	
SLIP CAPACITY (kips)	193.8	581.3	968.8	231.3	693.8	1156.3	
(100 YR) REACTIONS FROM:	FAC	TOR OF SAF	ETY	FAC	CTOR OF SAF	ETY	
API-4F ACC+ 107 KNOTS WIND	1.81	5.42	9.03	0.82	2.47	4.12	
API-4F ACC+ 81.3 KNOTS WIND	2.23	6.70	11.17	0.91	2.73	4.55	
TIME DM.Ac + 81.3 KNOTS WIND	2.32	6.97	11.61	0.96	2.88	4.81	



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Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# 6.2.3 Bolts Tension Loading & Capacity Check

Table 38	<b>Bolt Tension</b>	Calculations & FS	per Connection (100	YR) for	137.3 kij	os Preten	sion
BOLT TENSI	LE CAPACITY:	109.9	kips	-			

	(100 YR) REACTIONS				FACTOR			
LOAD COMBIN.	FZ	MX	MY	T1	T2	Т3	Т	OF
	kips	kip-in	kip-in	kips	kips	kips	kips	SAFETY
UPPER DERRICK								
API-4F ACCEL. &								
107 KNOTS WIND	500.99	63.03	63.03	62.62	1.58	0.72	64.92	1.69
API-4F ACCEL. &								
81.3 KNOTS WIND	319.83	62.16	62.16	39.98	1.55	0.71	42.24	2.60
TIME-DM ACCEL. &								
81.3 KNOTS WIND	308.29	56.97	56.97	38.54	1.42	0.65	40.61	2.71
			SUBST	RUCTURE				
API-4F ACCEL. &								
107 KNOTS WIND	668.32	384.91	254.15	83.54	6.35	4.37	94.27	1.17
API-4F ACCEL. &								
81.3 KNOTS WIND	439.86	384.47	252.74	54.98	6.32	4.37	65.67	1.67
TIME-DM ACCEL. &								
81.3 KNOTS WIND	402.70	380.76	235.28	50.34	5.88	4.33	60.55	1.82

# Table 39Tension Calculations & FS per Connection (100 YR) for 75 kips PretensionBOLT TENSILE CAPACITY:172.3 kips

	(100 YR) REACTIONS				FACTOR				
LOAD COMBIN.	FZ	MX	MY	T1	T2	T3	Т	OF	
	kips	kip-in	kip-in	kips	kips	kips	kips	SAFETY	
UPPER DERRICK									
API-4F ACCEL. &									
107 KNOTS WIND	500.99	63.03	63.03	62.62	1.58	0.72	64.92	2.65	
API-4F ACCEL. &									
81.3 KNOTS WIND	319.83	62.16	62.16	39.98	1.55	0.71	42.24	4.08	
TIME-DM ACCEL. &									
81.3 KNOTS WIND	308.29	56.97	56.97	38.54	1.42	0.65	40.61	4.24	
			SUBST	RUCTURE					
API-4F ACCEL. &									
107 KNOTS WIND	668.32	384.91	254.15	83.54	6.35	4.37	94.27	1.83	
API-4F ACCEL. &									
81.3 KNOTS WIND	439.86	384.47	252.74	54.98	6.32	4.37	65.67	2.62	
TIME-DM ACCEL. &									
81.3 KNOTS WIND	402.70	380.76	235.28	50.34	5.88	4.33	60.55	2.85	



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# Our Ref.

# 303859-IM-0001

Date : 15/01/2007

# Table 40Bolt Tension Calculations & FS per Connection (100 YR) for 150 kips PretensionBOLT TENSILE CAPACITY:97.3 kips

	(100 YR) REACTIONS				FACTOR				
LOAD COMBIN.	FZ	MX	MY	T1	T2	Т3	Т	OF	
	kips	kip-in	kip-in	kips	kips	kips	kips	SAFETY	
UPPER DERRICK									
API-4F ACCEL. &									
107 KNOTS WIND	500.99	63.03	63.03	62.62	1.58	0.72	64.92	1.50	
API-4F ACCEL. &									
81.3 KNOTS WIND	319.83	62.16	62.16	39.98	1.55	0.71	42.24	2.30	
TIME-DM ACCEL. &									
81.3 KNOTS WIND	308.29	56.97	56.97	38.54	1.42	0.65	40.61	2.40	
			SUBST	RUCTURE					
API-4F ACCEL. &									
107 KNOTS WIND	668.32	384.91	254.15	83.54	6.35	4.37	94.27	1.03	
API-4F ACCEL. &									
81.3 KNOTS WIND	439.86	384.47	252.74	54.98	6.32	4.37	65.67	1.48	
TIME-DM ACCEL. &									
81.3 KNOTS WIND	402.70	380.76	235.28	50.34	5.88	4.33	60.55	1.61	

# Table 41Bolt Tension Calculations & FS per Connection (100 YR) for 225 kips PretensionBOLT TENSILE CAPACITY:22.3 kips

	(100 YR) REACTIONS TENSION FORCES						FACTOR	
LOAD COMBIN.	FZ	MX	MY	T1	T2	Т3	Т	OF
	kips	kip-in	kip-in	kips	kips	kips	kips	SAFETY
			UPPER	DERRICK				
API-4F ACCEL. &								
107 KNOTS WIND	500.99	63.03	63.03	62.62	1.58	0.72	64.92	0.34
API-4F ACCEL. &								
81.3 KNOTS WIND	319.83	62.16	62.16	39.98	1.55	0.71	42.24	0.53
TIME-DM ACCEL. &								
81.3 KNOTS WIND	308.29	56.97	56.97	38.54	1.42	0.65	40.61	0.55
SUBSTRUCTURE								
API-4F ACCEL. &								
107 KNOTS WIND	668.32	384.91	254.15	83.54	6.35	4.37	94.27	0.24
API-4F ACCEL. &								
81.3 KNOTS WIND	439.86	384.47	252.74	54.98	6.32	4.37	65.67	0.34
TIME-DM ACCEL. &								
81.3 KNOTS WIND	402.70	380.76	235.28	50.34	5.88	4.33	60.55	0.37


Dept.

Our Ref.

## 303859-IM-0001

Date : 15/01/2007

A summary of the factors of safety associated with the three wind and dynamic loading directions for the 100 Year hurricane case is given below.

#### Table 42 Summary of Tensile Factors of Safety: 100-Year Hurricane Load Case

LOADING DIRECTION	45-DEGREE LOADING				0-DEGREE	E LOADING		90-DEGREE LOADING				
BOLT TENSILE	109.9	172.3	97.3	22.3	109.9	172.3	97.3	22.3	109.9	172.3	97.3	22.3
CAPACITY	kips	kips	kips	kips	kips	kips	kips	kips	kips	kips	kips	kips
LOAD		FACTOR OF SAFETY				FACTOR C	F SAFETY		FACTOR OF SAFETY			
COMBINATION	UPF	PER DERRI	CK FOOTII	NGS	UPI	PER DERRI	CK FOOTI	NGS	UPI	UPPER DERRICK FOOTINGS		
API-4F ACCEL. &	1.69	2.65	1.50	0.34	4.68	7.33	4.14	0.95	4.59	7.20	4.06	0.93
107 KNOTS WIND												
API-4F ACCEL. &	2.60	4.08	2.30	0.53	9.03	14.14	7.99	1.83	8.73	13.68	7.73	1.77
81.3 KNOTS WIND												
TIME-DM ACCEL. &	2.71	4.24	2.40	0.55	9.59	15.03	8.49	1.94	9.31	14.59	8.24	1.89
81.3 KNOTS WIND												
	SUE	BSTRUCTU	RE FOOTI	NGS	SUI	BSTRUCTURE FOOTINGS			SUBSTRUCTURE FOOTINGS			
API-4F ACCEL. &	1.17	1.83	1.03	0.24	2.80	4.39	2.48	0.57	19.27	30.20	17.05	3.90
107 KNOTS WIND												
API-4F ACCEL. &	1.67	2.62	1.48	0.34	5.27	8.26	4.66	1.07	19.29	30.23	17.07	3.91
81.3 KNOTS WIND												
TIME-DM ACCEL. &	1.82	2.85	1.61	0.37	6.25	9.79	5.53	1.27	19.84	31.08	17.55	4.02
81.3 KNOTS WIND												



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## 303859-IM-0001

Date : 15/01/2007

## 6.3 10 Year Hurricane Load Case

#### 6.3.1 Bolts Shear/Slip Loading

## Table 43 Total Shear/Slip Forces per Connection (10 YR) CONNECTION TOTAL LATERAL EOPCES (10 YR)

	CONNECTION TOTAL LATERAL FORCES (101R)										
		UP	PER DERR	ICK		ΣX-FORCES	$\Sigma Y$ -FORCES				
REFERENCE	MZ	MZ/d=F	Fsinα= Fx	Fcosα= Fy	LOAD	kips	kips				
NODE No	kip-in	kips	kips	kips	COMBINATION	SHEAR	SLIP				
6	12.63	0.44	0.28	0.34	(I)	79.52	81.29				
5	0.00	0.00	0.00	0.00	API-4F ACCEL. &	81.41	81.41				
8	12.63	0.44	0.28	0.34	107 KNOTS WIND	81.23	79.58				
9	0.00	0.00	0.00	0.00		79.70	79.70				
6	12.63	0.44	0.28	0.34	(II)	41.83	43.61				
5	0.00	0.00	0.00	0.00	API-4F ACCEL. &	43.72	43.72				
8	12.63	0.44	0.28	0.34	50.9 KNOTS WIND	43.55	41.89				
9	0.00	0.00	0.00	0.00		42.01	42.01				
6	11.87	0.42	0.26	0.32	(III)	39.91	41.68				
5	0.00	0.00	0.00	0.00	TIME DOMAIN ACCEL.&	41.80	41.80				
8	11.87	0.42	0.26	0.32	50.9 KNOTS WIND	41.62	39.97				
9	0.00	0.00	0.00	0.00		40.08	40.08				
		SU	BSTRUCTU	JRE		ΣX-FORCES	ΣY-FORCES				
REFERENCE	MZ	MZ/d=F	Fsinβ= Fx	Fcosβ= Fy	LOAD	kips	kips				
NODE No	kip-in	kips	kips	kips	COMBINATION	SLIP	SHEAR				
30	4.93	0.17	0.13	0.11	(I)	174.13	169.97				
29	95.49	3.36	2.60	2.13	API-4F ACCEL. &	184.80	166.86				
31	104.66	3.68	2.85	2.33	107 KNOTS WIND	183.14	193.81				
32	4.24	0.15	0.12	0.09		176.03	186.44				
30	4.93	0.17	0.13	0.11	(II)	125.22	121.06				
29	95.49	3.36	2.60	2.13	API-4F ACCEL. &	135.89	117.95				
31	104.66	3.68	2.85	2.33	50.9 KNOTS WIND	134.23	144.89				
32	4.24	0.15	0.12	0.09		127.12	137.52				
30	1.36	0.05	0.04	0.03	(III)	117.63	113.27				
29	92.67	3.26	2.52	2.06	TIME DOMAIN ACCEL.&	128.19	110.46				
31	101.12	3.56	2.75	2.25	50.9 KNOTS WIND	126.63	137.11				
32	7.09	0.25	0.19	0.16		119.57	130.19				



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Our Ref.

## 303859-IM-0001

Date : 15/01/2007

## 6.3.2 Connection Shear/Slip Check

Table 44	Bolts Shear Factor of S	afety per Connection	(10 YR)	)

(10 YR) REACTIONS FROM:	UPPER DERRICK (FS <sub>V1</sub> )	SUBSTRUCTURE (FS <sub>V2</sub> )
API-4F ACC. + 107 KNOTS WIND	10.04	4.22
API-4F ACC.+ 50.9 KNOTS WIND	18.70	5.64
TIME DM. ACC.+ 50.9 KNOTS WIND	19.56	5.96

#### Table 45 Slip Check & Factor of Safety per Connection (10 YR)

	UP	PER DERR	ICK	SUBSTRUCTURE			
	AISC PRET	ENSION=137	3 kips				
COEFFICIENT OF FRICTION	0.1	0.3	0.5	0.1	0.3	0.5	
SLIP CAPACITY (kips)	123.6	370.8	618.0	161.1	483.3	805.5	
(10 YR) REACTIONS FROM:	FAC	TOR OF SAF	ETY	FAC	TOR OF SAF	ETY	
API-4F ACCL. + 107 KNOTS WIND	1.52	4.55	7.59	0.87	2.62	4.36	
API-4F ACCL. + 50.9 KNOTS WIND	2.83	8.48	14.13	1.19	3.56	5.93	
TIME DOM.ACC.+ 50.9.9 KNOTS WIND	2.96	8.87	14.78	1.26	3.77	6.28	
	PRETE	NSION= 75 ki	ps				
COEFFICIENT OF FRICTION	0.1	0.3	0.5	0.1	0.3	0.5	
SLIP CAPACITY (kips)	73.8	221.3	368.8	111.3	333.8	556.3	
(10 YR) REACTIONS FROM:	FAC	TOR OF SAF	ETY	FAC	FACTOR OF SAFETY		
API-4F ACCL. + 107 KNOTS WIND	0.91	2.72	4.53	0.60	1.81	3.01	
API-4F ACCL. + 50.9 KNOTS WIND	1.69	5.06	8.43	0.82	2.46	4.09	
TIME DOM.ACC.+ 50.9.9 KNOTS WIND	1.76	5.29	8.82	0.87	2.60	4.34	
	PRETE	NSION=150 ki	ps				
COEFFICIENT OF FRICTION	0.1	0.3	0.5	0.1	0.3	0.5	
SLIP CAPACITY (kips)	133.8	401.3	668.8	171.3	513.8	856.3	
(10 YR) REACTIONS FROM:	FAC	TOR OF SAF	ETY	FAC	TOR OF SAF	ETY	
API-4F ACCL. + 107 KNOTS WIND	1.64	4.93	8.21	0.93	2.78	4.63	
API-4F ACCL. + 50.9 KNOTS WIND	3.06	9.18	15.30	1.26	3.78	6.30	
TIME DOM.ACC.+ 50.9.9 KNOTS WIND	3.20	9.60	16.00	1.34	4.01	6.68	
	PRETE	NSION=225 ki	ps				
COEFFICIENT OF FRICTION	0.1	0.3	0.5	0.1	0.3	0.5	
SLIP CAPACITY (kips)	193.8	581.3	968.8	231.3	693.8	1156.3	
(10 YR) REACTIONS FROM:	FACTOR OF SAFETY			FAC	TOR OF SAF	ETY	
API-4F ACCL. + 107 KNOTS WIND	2.38	7.14	11.90	1.25	3.75	6.26	
API-4F ACCL. + 50.9 KNOTS WIND	4.43	13.29	22.16	1.70	5.11	8.51	
TIME DOM.ACC.+ 50.9.9 KNOTS WIND	4.64	13.91	23.18	1.80	5.41	9.02	



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Our Ref.

#### 303859-IM-0001

Date : 15/01/2007

#### 6.3.3 Bolts Tension Loading & Capacity Check

Table 46Bolt Tension Calculations & FS per Connection (10 YR) for 137.3 kips PretensionBOLT TENSILE CAPACITY:109.9 kips

		(10 YR) RE	ACTIONS		TEN	ISION FOR	CES	FACTOR	
LOAD COMBIN.	FZ	MX	MY	T1	T2	T3	Т	FACTOR	
	kips	kip-in	kip-in	kips	kips	kips	kips	OF SAFETY	
UPPER DERRICK									
API-4F ACCEL. &									
107 KNOTS WIND	407.37	21.47	21.47	50.92	0.54	0.24	51.70	2.13	
API-4F ACCEL. &									
50.9 KNOTS WIND	75.75	19.88	19.88	9.47	0.50	0.23	10.19	10.79	
TIME-DM ACCEL. &									
50.9 KNOTS WIND	68.69	16.76	16.76	8.59	0.42	0.19	9.20	11.96	
			SUBST	RUCTURE					
API-4F ACCEL. &									
107 KNOTS WIND	382.25	379.90	126.25	47.78	3.16	4.32	55.25	1.99	
API-4F ACCEL. &									
50.9 KNOTS WIND	35.93	379.11	123.67	4.49	3.09	4.31	11.89	9.25	
TIME-DM ACCEL. &									
50.9 KNOTS WIND	58.48	377.98	113.53	7.31	2.84	4.30	14.44	7.61	

Table 47	<b>Bolt Tension Cal</b>	lations & FS per Connection (10 YR) for 75 kips Pretension
BOLT TENS	LE CAPACITY:	172.3 kips

		(10 YR) REACTIONS				TENSION FORCES			
LOAD COMBIN.	FZ	MX	MY	T1	T2	T3	Т	FACTOR	
	kips	kip-in	kip-in	kips	kips	kips	kips	OF SAFETY	
UPPER DERRICK									
API-4F ACCEL. &									
107 KNOTS WIND	407.37	21.47	21.47	50.92	0.54	0.24	51.70	3.33	
API-4F ACCEL. &									
50.9 KNOTS WIND	75.75	19.88	19.88	9.47	0.50	0.23	10.19	16.90	
TIME-DM ACCEL. &									
50.9 KNOTS WIND	68.69	16.76	16.76	8.59	0.42	0.19	9.20	18.73	
			SUBST	RUCTURE					
API-4F ACCEL. &									
107 KNOTS WIND	382.25	379.90	126.25	47.78	3.16	4.32	55.25	3.12	
API-4F ACCEL. &									
50.9 KNOTS WIND	35.93	379.11	123.67	4.49	3.09	4.31	11.89	14.49	
TIME-DM ACCEL. &									
50.9 KNOTS WIND	58.48	377.98	113.53	7.31	2.84	4.30	14.44	11.93	



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Our Ref.

## 303859-IM-0001

Date : 15/01/2007

# Table 48Bolt Tension Calculations & FS per Connection (10 YR) for 150 kips PretensionBOLT TENSILE CAPACITY:97.3 kips

		(10 YR) RE	EACTIONS		TEN	CES	FACTOR		
LOAD COMBIN.	FZ	MX	MY	T1	T2	Т3	Т	FACTOR	
	kips	kip-in	kip-in	kips	kips	kips	kips	OF SAFETY	
	UPPER DERRICK								
API-4F ACCEL. &									
107 KNOTS WIND	407.37	21.47	21.47	50.92	0.54	0.24	51.70	1.88	
API-4F ACCEL. &									
50.9 KNOTS WIND	75.75	19.88	19.88	9.47	0.50	0.23	10.19	9.54	
TIME-DM ACCEL. &									
50.9 KNOTS WIND	68.69	16.76	16.76	8.59	0.42	0.19	9.20	10.58	
			SUBST	RUCTURE					
API-4F ACCEL. &									
107 KNOTS WIND	382.25	379.90	126.25	47.78	3.16	4.32	55.25	1.76	
API-4F ACCEL. &									
50.9 KNOTS WIND	35.93	379.11	123.67	4.49	3.09	4.31	11.89	8.18	
TIME-DM ACCEL. &									
50.9 KNOTS WIND	58.48	377.98	113.53	7.31	2.84	4.30	14.44	6.73	

# Table 49Bolt Tension Calculations & FS per Connection (10 YR) for 225 kips PretensionBOLT TENSILE CAPACITY:22.3 kips

		(10 YR) RE	EACTIONS		TEN	ISION FOR	CES	FACTOR
LOAD COMBIN.	FZ	MX	MY	T1	T2	Т3	Т	FACTOR
	kips	kip-in	kip-in	kips	kips	kips	kips	OF SAFETY
UPPER DERRICK								
API-4F ACCEL. &								
107 KNOTS WIND	407.37	21.47	21.47	50.92	0.54	0.24	51.70	0.43
API-4F ACCEL. &								
50.9 KNOTS WIND	75.75	19.88	19.88	9.47	0.50	0.23	10.19	2.19
TIME-DM ACCEL. &								
50.9 KNOTS WIND	68.69	16.76	16.76	8.59	0.42	0.19	9.20	2.42
			SUBST	RUCTURE				
API-4F ACCEL. &								
107 KNOTS WIND	382.25	379.90	126.25	47.78	3.16	4.32	55.25	0.40
API-4F ACCEL. &								
50.9 KNOTS WIND	35.93	379.11	123.67	4.49	3.09	4.31	11.89	1.87
TIME-DM ACCEL. &								
50.9 KNOTS WIND	58.48	377.98	113.53	7.31	2.84	4.30	14.44	1.54



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Our Ref.

#### 303859-IM-0001

Date : 15/01/2007

A summary of the factors of safety associated with the three wind and dynamic loading directions for the 10 Year hurricane case is given below.

	Jummu		CHOIC			Cly. 10	i cui i	lannou					
LOADING DIRECTION		45-DEGRE	E LOADIN	G		0-DEGREE	LOADING			90-DEGRE	E LOADING	j	
BOLT TENSILE	109.9	172.3	97.3	22.3	109.9	172.3	97.3	22.3	109.9	172.3	97.3	22.3	
CAPACITY	kips	kips	kips	kips	kips	kips	kips	kips	kips	kips	kips	kips	
LOAD		FACTOR 0	OF SAFETY	i		FACTOR O	F SAFETY			FACTOR OF SAFETY			
COMBINATION	UP	PER DERR	ICK FOOTI	NGS	UP	PER DERRI	CK FOOTIN	NGS	UP	UPPER DERRICK FOOTINGS			
API-4F ACCEL. &	2.13	3.33	1.88	0.43	6.27	9.82	5.55	1.27	6.32	9.90	5.59	1.28	
107 KNOTS WIND													
API-4F ACCEL. &	10.79	16.90	9.54	2.19	176.19	276.08	155.89	35.70	238.92	374.37	211.39	48.41	
50.9 KNOTS WIND													
TIME-DM ACCEL. &	11.96	18.73	10.58	2.42	179.34	281.02	158.68	36.33	270.33	423.59	239.18	54.77	
50.9 KNOTS WIND													
	SU	BSTRUCTU	JRE FOOTI	NGS	SU	SUBSTRUCTURE FOOTINGS			SUBSTRUCTURE FOOTINGS				
API-4F ACCEL. &	1.99	3.12	1.76	0.40	7.79	12.21	6.89	1.58	22.38	35.07	19.80	4.53	
107 KNOTS WIND													
API-4F ACCEL. &	9.25	14.49	8.18	1.87	17.85	27.97	15.79	3.62	22.43	35.15	19.85	4.54	
50.9 KNOTS WIND													
TIME-DM ACCEL. &	7.61	11.93	6.73	1.54	18.39	28.82	16.27	3.73	22.38	35.07	19.80	4.53	
50.9 KNOTS WIND													

#### Table 50 Summary of Tensile Factors of Safety: 10-Year Hurricane Load Case



Dept.

Our Ref.

## 303859-IM-0001

Date : 15/01/2007

#### 7. SPAR VS TLP ANALYSIS

#### 7.1 General

An analysis, similar to that outlined in the previous sections for Spar rigs, is performed with the aid of the STRUCAD software using the TLP motions presented in the following Table.

ENVIRONMENTAL	MAXIMUM ACCELERATION (g)					
CONDITION	LATERAL	VERTICAL				
10 YEAR	0.15	0.02				
100 YEAR	0.2	0.04				
IVAN	0.26	0.05				

#### Table 51 TLP Platform Accelerations

The structure (derrick & substructure) geometry, wind areas and masses remain the same. The clamp connections are assumed to be fixed (as opposed to pinned).

#### 7.2 Tensile, Shear & Slip Results for TLP Rig Clamps

The TLP rig clamp reaction forces and moments and associated factors of safety are calculated in a similar fashion to that described previously. The results are summarised in the following Tables.

EN	VIRONMENTAL	2			G	45°- DIRECTION LOADING					
CONDITION		MAX. FZ kips	MIN. FZ** kips	MX kip-in	MY kip-in	MAX. FZ kips	MIN. FZ** kips	MX kip-in	MY kip-in		
10 YEAR		730.757	273.743	395.599 343.396	118.976 52.734	857.906	146.594	363.877 375.118	138.115 71.873		
	100 YEAR	892.430	91.570	396.750 327.155	147.838 82.948	1115.161	-131.161	354.179 369.735	173.356 108.466		
1000 YEAR		981.148	-7.398	403.429 312.944	181.866 117.651	1256.093	-282.300	348.153 368.220	215.039 150.824		

#### Table 52 TLP Substructure Clamp Loads Pertaining to Bolts Tension

\*\* POSITIVE NUMBER= COMPRESSION FORCE ON BOLTS



Dept.

Our Ref.

#### 303859-IM-0001

Date : 15/01/2007

#### Table 53 TLP Upper Derrick Clamp Loads Pertaining to Bolts Tension

ENVIRONMENTAL	хс	R Y DIREC	TION LOAD	DING	45°- DIRECTION LOADING				
CONDITION	MAX. FZ kips	MIN. FZ** kips	MX kip-in	MY kip-in	MAX. FZ kips	MIN. FZ** kips	MX kip-in	MY kip-in	
	221.019		38.500	58.120	307.300		65.278	65.278	
IU TEAR		48.480	24.194	4.577		-37.789	2.579	2.579	
	306.060		40.250	66.974	480.173		76.515	76.515	
		-42.086	21.169	5.554		-216.173	15.095	15.095	
	340.724		77.377	42.793	550.823		89.780	89.780	
TUUUTLAN		-79.474	17.987	16.598		-289.573	29.001	29.001	

\*\* POSITIVE NUMBER= COMPRESSION FORCE ON BOLTS

Given that the most critical direction for wind & Inertia loading on the structure is at 45° angle, the related clamps factors of safety are calculated and provided below.

	BC	OLT PRETE	NSION (kij	os)						
ENVIRONMENT	75.0	225.0								
	CLAM	CLAMP TENSILE FACTOR OF SAFETY								
	UPPE									
IVAN	4.62	2.95	2.61	0.60						
100 YR	6.25	3.99	3.53	0.81						
10 YR	35.75	22.82	20.19	4.62						
	SUBS	FRUCTURE								
IVAN	3.98	2.54	2.25	0.52						
100 YR	7.39	4.72	4.17	0.96						
10 YR	28.43	18.14	16.05	3.68						

## Table 54 TLP-Clamp Bolts Tensile Factors of Safety for 45° Loading Direction

Clamps slip and bolts shear factors of safety are also calculated as follows.

Table 55	TLP-Substructure Clam	p Shear Forces & F	Factors of Safety
----------	-----------------------	--------------------	-------------------

	SUBSTRUCTURE	
		FACTOR
ENVIRONMENT	CEAMP SHEARTORCE	OF
	(kips)	SAFETY
IVAN	189.1	4.32
100-YEAR	151.6	5.39
10-YEAR	103.5	7.9



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Our Ref.

## 303859-IM-0001

Date : 15/01/2007

# Table 56 TLP-Upper Derrick Clamp Shear Forces & Factors of Safety UPPER DERRICK

	CLAMP SHEAR FORCE	FACTOR
	CEAM SHEARTORCE	OF
	(kips)	SAFETY
IVAN	69.70	11.73
100-YEAR	56.65	14.43
10-YEAR	32.64	25.0

#### Table 57 TLP-Substructure Clamp Slip Forces & Factors of Safety

	SUBSTRUCTURE											
BOLT PF	RETENSION: (ki	ps)	75	137.3	150	225						
ENVIRONMENT	SLIP LOAD (kips)	COF	FACTOR OF SAFETY									
IVAN	177.8	0.1	0.63	0.91	0.96	1.30						
		0.3	1.88	2.72	2.89	3.88						
		0.5	3.13	4.53	4.82	6.50						
100-YEAR	141.2	0.1	0.79	1.14	1.21	1.64						
		0.3	2.36	3.42	3.64	4.89						
		0.5	3.94	5.70	6.06	8.19						
10-YEAR	93.65	0.1	1.19	1.72	1.83	2.47						
		0.3	3.56	5.16	5.49	7.37						
		0.5	5.94	8.60	9.14	12.35						

#### Table 58 TLP-Derrick Clamp Slip Forces & Factors of Safety

	DERRICK												
BOLT PR	ETENSION: (ki	ips)	75	137.3	150	225							
ENVIRONMENT	SLIP LOAD (kips)	COF	FACTOR OF SAFETY										
IVAN	69.698	0.1	1.06	1.77	1.92	2.78							
		0.3	3.18	5.32	5.76	8.34							
		0.5	5.29	8.87	9.60	13.90							
100-YEAR	56.646	0.1	1.30	2.18	2.36	3.42							
		0.3	3.91	6.55	7.08	10.26							
		0.5	6.51	10.91	11.81	17.10							
10-YEAR	32.64	0.1	2.26	3.79	4.10	5.94							
		0.3	6.78	11.36	12.29	17.81							
		0.5	11.30	18.93	20.49	29.68							



Dept.

Our Ref.

## 303859-IM-0001

Date : 15/01/2007

#### 7.3 Structure Overturning Moments Vs. Maximum Uplift Forces

As demonstrated in the previous Sections, Inertia & wind loading generate moments at the upper derrick and substructure footings, which result in uplift forces that can exceed the compression forces exerted by the dead weight of the structure.

When this happens, the clamp bolts are subject to tensile loading. This section depicts the relationship between clamp max. uplift forces and the structure global overturning moments. The results for Spar rigs are derived using Time Domain accelerations.

#### 7.3.1 Results for Spar Rig

## Table 59Spar Derrick Clamp Maximum Uplift Forces & Global Overturning Moments

	LOAD-DIRECTION				LOAD DIRECTION									
ENVIRONMENT	X-DIRECT.	Y-DIRECT.	45 deg	х	X-DIRECTION Y-DIRECTION 45°-DIRECTION									
	MAX. UP	<u>LIFT</u> CLAMP I	OAD (FZ)		DERRICK GLOBAL MOMENTS (AT DERRICK FOOTINGS LEVEL) (kip-ft)									
		(kips)		M <sub>accel</sub>	M <sub>wind</sub>	М <sub>т</sub> *	M <sub>accel</sub>	M <sub>wind</sub>	М <sub>т</sub> *	M <sub>accel</sub>	M <sub>wind</sub>	М <sub>т</sub> *		
NONE (STATIC)	U DEAD LO	IPLIFT=0.0 kip AD/CLAMP= -	<b>os</b> 137.5 kips		0.00									
10 YEAR	-34.20	-34.20	68.69	2732.40	1212.42	3944.82	2732.40	1212.42	3944.82	3864.20	1714.62	5578.82		
100 YEAR	85.60	85.60	308.29	4971.45	3093.20	8064.65	4971.45	3093.20	8064.65	7030.69	4374.45	11405.14		
IVAN	137.12	137.12	409.67	6426.20	3615.81	10042.01	6426.20	3615.81	10042.01	9088.02	5113.53	14201.55		

\* M<sub>T</sub>= M<sub>accel</sub>+M<sub>wind</sub>

#### Table 60 Spar Substructure Clamp Maximum Uplift Forces & Global Overturning Moments

	LC	DAD-DIRECTIO	ON		LOAD DIRECTION								
ENVIRONMENT	X-DIRECT.	Y-DIRECT.	45 deg	X-DIRECTION Y-DIRECTION					N	45°-DIRECTION			
	MAX. UPI	<u>LIFT</u> CLAMP I	OAD (FZ)	(DERF	(DERRICK+SUB.) GLOBAL MOMENTS (AT SUBSTRUCTURE F					FOOTINGS LEVEL) (kip-ft)			
		(kips)		Maccel	Mwind	M <sub>T</sub> *	Maccel	Mwind	М <sub>т</sub> *	Maccel	Mwind	M <sub>T</sub> *	
NONE (STATIC)	U DEAD LO	PLIFT=0.0 kip AD/CLAMP= -	<b>os</b> 512.5 kips		0.00								
10 YEAR	-220.26	-349.18	-58.48	10643.40	1965.73	12609.13	10643.40	1965.73	12609.13	15052.04	2779.96	17832.00	
100 YEAR	76.05	-184.32	402.70	19393.95	5014.98	24408.93	19393.95	5014.98	24408.93	27427.19	7092.26	34519.44	
IVAN	229.75	-133.37	638.52	25098.20	5862.27	30960.47	25098.20	5862.27	30960.47	35494.21	8290.50	43784.72	

#### \* M<sub>T</sub>= M<sub>accel</sub>+M<sub>wind</sub>

These results are shown in the following Figures.



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Figure 13 Spar Substructure Clamp Uplift Forces VS Global Overturning Moments



Figure 14 Spar Derrick Clamp Uplift Forces VS Global Overturning Moments



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## 303859-IM-0001

Date : 15/01/2007

#### 7.3.2 Results for TLP Rig

#### Table 61 TLP Derrick Clamp Maximum Uplift Forces & Global Overturning Moments

	LC	DAD-DIRECTIO	ON		LOAD DIRECTION								
ENVIRONMENT	X-DIRECT.	Y-DIRECT.	45 deg	X-DIRECTION Y-DIRECTION					45°-DIRECTION				
	MAX. UPL	LIFT CLAMP L	.OAD (FZ)		DERRICK GLOBAL MOMENTS (AT DERRICK FOOTINGS LEVEL) (kip-ft)								
		(kips)		M <sub>accel</sub>	Mwind	M <sub>T</sub> *	M <sub>accel</sub>	Mwind	M <sub>T</sub> *	M <sub>accel</sub>	Mwind	M <sub>T</sub> *	
NONE (STATIC)	U DEAD LO	PLIFT=0.0 kip AD/CLAMP= -	<b>is</b> 137.5 kips		0.00								
10 YEAR	-48.48	-48.48	37.79	1897.50	1212.42	3109.92	1897.50	1212.42	3109.92	2683.47	1714.62	4398.09	
100 YEAR	42.09	42.09	216.17	2530.00	3093.20	5623.20	2530.00	3093.20	5623.20	3577.96	4374.45	7952.41	
IVAN	79.47	79.47	289.57	3289.00	9.00 3615.81 <b>6904.81</b> 3289.00 3615.81 <b>6904.81</b> 4651.35 5113.53								

\*  $M_T = M_{accel} + M_{wind}$ 

#### Table 62 TLP Substructure Clamp Maximum Uplift Forces & Global Overturning Moments

	LC	DAD-DIRECTI	ON		LOAD DIRECTION								
ENVIRONMENT	X-DIRECT.	Y-DIRECT.	45 deg	х	-DIRECTIO	N	Y-DIRECTION			45°-DIRECTION			
	MAX. UPI	<u>LIFT</u> CLAMP I	OAD (FZ)	(DERF	RICK+SUB.	) GLOBAL	MOMENTS	(AT SUBS	TRUCTUR	E FOOTING	S LEVEL)	(kip-ft)	
		Maccel	M <sub>wind</sub>	М <sub>т</sub> *	M <sub>accel</sub>	M <sub>wind</sub>	M <sub>T</sub> *	M <sub>accel</sub>	Mwind	M <sub>T</sub> *			
NONE (STATIC)	U DEAD LO	PLIFT=0.0 kip AD/CLAMP= -	<b>os</b> 512.5 kips		0.00								
10 YEAR	-273.74	-379.50	-146.59	7522.50	1965.73	9488.23	7522.50	1965.73	9488.23	10638.42	2779.96	13418.38	
100 YEAR	-91.57	-269.70	131.16	10030.00	5014.98	15044.98	10030.00	5014.98	15044.98	14184.56	7092.25	21276.82	
IVAN	7.40	-209.90	282.30	13039.00	5862.27	18901.27	13039.00	5862.27	18901.27	18439.93	8290.50	26730.43	

\* M<sub>T</sub>= M<sub>accel</sub>+M<sub>wind</sub>

These results are illustrated in the following Figures.



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## 303859-IM-0001

Date : 15/01/2007



Figure 15 TLP Substructure Clamp Uplift Forces VS Global Overturning Moments



Figure 16 TLP Derrick Clamp Uplift Forces VS Global Overturning Moments





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#### 303859-IM-0001

Date : 15/01/2007

#### 8. SUMMARY OF FINDINGS & CONCLUSIONS

Technid

**TECHNIP OFFSHORE, INC.** 

The analysis included in this document focuses on the Tie-Down clamps of a drilling rig mounted on a Spar. The analysis has two main objectives. The first objective is to compare the accelerations calculated based on API-4F specifications to those resulting from Time Domain analysis. The second objective is to analyse the capability of the clamped connections at the upper derrick and substructure footings levels to withstand various environmental loading conditions, namely those associated with Ivan, 100 year and 10 year hurricanes.

**Detailed calculations included in Section 2 of this document proved that for a Spar Rig the accelerations derived according to API-4F specifications are consistently more conservative than those obtained from the Time Domain analysis.** The latter was exceeded by 4.5% to 6.5% for the case of lateral accelerations. For vertical accelerations, API-4F gives a range of values that reach 2.5 times the corresponding value from Time Domain analysis specifically for the 100 year hurricane case. It is important to note that the vertical accelerations employed for the comparison from Time Domain Analysis, are those associated with maximum lateral accelerations.

To address the second objective of this analysis, several steps were undertaken.

- 1- Rigid models simulating the upper derrick and substructure masses were developed and subjected to the three different environmental conditions. Reaction forces and moments at the upper derrick and substructure footings were extracted from those models.
- 2- The clamped connections ultimate strength with respect to bolt shear, slip resistance and tension were determined with respect to corresponding varying parameters.
- 3- Connections actual shear, slip and tension loads were calculated from the reactions for the three environmental load cases.
- 4- The ratio of connection ultimate strength to actual loading were determined and documented as the connection factor of safety with respect to each mode of bolt failure.

The analysis demonstrates that the integrity of the clamped connections is highly specific and varies due to the many varying parameters involved. These parameters vary with respect to the mode of failure under consideration. Moreover, for the same mode of failure a second set of parameters affect the outcome of the analysis. As an example, the slip resistance of a connection depends on bolts pretension and coefficient of friction for a given load case.

The specifics of the bolts failure analysis are included in details in this document. A general overview of the results suggests that within the limits of this study:

#### 1- Shear failure does not occur for bolts.



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#### 303859-IM-0001

Date : 15/01/2007

2- Slip resistance failure occurs in several occasions. Out of a total number of 36 varying combinations of loading conditions and parameters, the number of reported failure cases for a Spar rig are shown in the following graph:



Figure 17 Number of Bolt Slip Failure cases in the analysis of a Spar Rig

3- Similarly, the number of connection tensile failure cases, reported in this study for a Spar rig, is graphically represented below. These are cases where the actual load exceeds the corresponding ultimate capacity of the clamp (factors of safety less than one).



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Our Ref.

## 303859-IM-0001

Date : 15/01/2007



Figure 18 Number of Bolt Tensile Failure cases in the analysis of a Spar Rig

A comparative analysis performed between Spar and TLP rig tie-down clamps, where the only varying parameter is the dynamic loading on the structure, demonstrates the higher vulnerability of the Spar rigs for clamp slip and bolt tensile failures.

In conclusion, the analysis demonstrates that:

- 1. The clamp connections, particularly at the substructure footings level and during severe environmental conditions, such as Ivan hurricane, are more likely to fail due to inadequate slip resistance and/or bolt tensile failure than due to shear failure of the bolts.
- 2. There is a need to address the clamp design issue while taking into consideration the particulars of the offshore floating structures on which the drilling rigs are mounted.

It is important to finally note that the analyses in this document address the clamp actual load VS the ultimate strength of the connections and not VS the allowable design loads (or stresses) for shear, slip and tension.



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## 303859-IM-0001

Date : 15/01/2007

Comparing actual loads to the latter would show a higher number of cases designated as "not acceptable" due to exceeding the allowable design forces and stresses defined by the AISC. and other industry standards and specifications.



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## 303859-IM-0001

Date : 15/01/2007

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Appendix B

## Assessment of the Performance of Tie-Down Clamps for a Drilling Rig on a TLP in Severe Hurricane Environments

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## Global Motion of Deep Star TLP and the Corresponding Load at the Connection of Derrick and Substructure in Extreme Survival Condition

Prepared

by

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August, 2006

## **Table of Contents**

1.0	SUMMARY	. 1
1.1	SCOPE	. 1
2.0	INTRODUCTION	. 2
3.0	SPECIFICATION OF DEEP STAR TLP	. 3
4.0	NUMERICAL MODELING OF HULL, TENDONS AND RISERS	. 6
4.1	HYDRODYNAMIC MODELING WITH WAMIT	. 6
4.2	FULLY COUPLED ANALYSIS MODELING WITH HARP	. 7
5.0	ENVIRONMENTAL CONDITION	10
6.0	REACTION FORCE ON THE DERRICK BASE	11
7.0	RESULTS	15
7.1	DERRICK MOTION	19
7.2	DYNAMIC FORCES ON DERRICK AND SUBSTRUCTURE	22
7.3	REACTION FORCES ON THE FOOTINGS	25
7.4	CONNECTION CAPACITY AND SAFETY FACTORS	26
8.0	INTERPRETATION AND DISCUSSION OF THE RESULTS	29
8.1	PLATFORM ACCELERATION RESULTS	34
8.2	RECOMMENDATION BASED ON THE PRESENT STUDY	34
9.0	REFERENCES	35
10.0	APPENDIX A: FIGURES FOR THE 180 DEGREE CASE	36
11.0	APPENDIX B: 135 DEGREE CASE	90
12.0	APPENDIX C: SPRING CONNECTION MODEL	94
13.0	APPENDIX D: COMPARISON OF HORIZONTAL ACCELERATION BETWEEN	
EXAC	T SIMULATION METHOD AND API FORMULA	95
14.0	APPENDIX E: COMPARISON BETWEEN MHKIM AND TECHNIP FOR TLP	
MAXI	MUM BOLT TENSION	96

## List of Tables

Table 1. Principal Dimensions   3
Table 2. Hull Load Condition at In-Place Draft4
Table 3. Configuration of the Mooring Line
Table 4. Environmental Conditions    10
Table 5. Specifications of Upper Derrick    18
Table 6. Statistics of Dynamic Forces on the Derrick for 10 Year Hurricane    22
Surge(kips)
Table 7. Statistics of Dynamic Forces on the Derrick for 100 Year Hurricane    22
Table 8. Statistics of Dynamic Forces on the Derrick for 1000 Year Hurricane    23
Table 9. Statistics of Dynamic Forces on the Derrick and the Substructure for 10 Year Hurricane23
Table 10. Statistics of Dynamic Forces on the Derrick and the Substructure for 100 Year Hurricane24
Table 11. Statistics of Dynamic Forces on the Derrick and the Substructure for 1000 Year Hurricane 24
Table 12. Reaction Forces on Upper Derrick Footing for 10 Year Hurricane
Table 13. Reaction Forces on Upper Derrick Footing for 100 Year Hurricane
Table 14. Reaction Forces on Upper Derrick Footing for 1000 Year Hurricane
Table 15. Reaction Forces on Substructure Footing for 10 Year Hurricane
Table 16. Reaction Forces on Substructure Footing for 100 Year Hurricane
Table 17. Reaction Forces on Substructure Footing for 1000 Year Hurricane
Table 18. Friction Resistance Capacity (Slip Capacity)    26
Table 19. Tensile Capacity with Pretension
Table 20. Shear Capacity of bolts    26
Table 21. Shear and Slip Safety Factor of the Upper Derrick Footing for 10 year Hurricane Load
Condition
Table 22. Shear and Slip Safety Factor of the Substructure Footing for 10 year Hurricane Load Condition
(Evaluated for 4 different pretension condition and 3 friction coeff.)
Table 23. Minimum Tension Safety Factor for 10 year Hurricane Load Condition (- means no tensile
loading)
Table 24. Shear and Slip Safety Factor of the Upper Derrick Footing for 100 year Hurricane Load
Condition
Table 25. Shear and Slip Safety Factor of the Substructure Footing for 100 year Hurricane Load
Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)
Table 26. Minimum Tension Safety Factor for 100 year Hurricane Load Condition

Table 27. Shear and Slip Safety Factor of the Upper Derrick Footing for 1000 year Hurricane Load
Condition
Table 28. Shear and Slip Safety Factor of the Substructure Footing for 1000 year Hurricane Load
Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)
Table 29. Minimum Tension Safety Factor for 1000 year Hurricane Load Condition
Table B-1. Reaction Forces at the Upper Derrick Footings (10 Year Hurricane)       90
Table B-2. Reaction Forces at the Substructure Footings (10 Year Hurricane)    91
Table B-3. Reaction Forces at the Upper Derrick Footings (100 Year Hurricane)       91
Table B-4. Reaction Forces at the Substructure Footings (100 Year Hurricane)    91
Table B-5. Reaction Forces at the Upper Derrick Footings (1000 Year Hurricane)91
Table B-6. Reaction Forces at the Substructure Footings (1000 Year Hurricane)
Table B-7. Shear and Slip Safety Factor of the Upper Derrick Footing for 10 year Hurricane Load
Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)91
Table B-8. Shear and Slip Safety Factor of the Substructure Footing for 10 year Hurricane Load
Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)92
Table B-9. Shear and Slip Safety Factor of the Upper Derrick and the Substructure Footing for 10 year
Hurricane Load Condition (Evaluated for 4 different pretension condition)
Table B-10. Shear and Slip Safety Factor of the Upper Derrick Footing for 100 year Hurricane Load
Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)
Table B-11. Shear and Slip Safety Factor of the Substructure Footing for 100 year Hurricane Load
Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)
Table B-12. Shear and Slip Safety Factor of the Upper Derrick and the Substructure Footing for 100 year
Hurricane Load Condition (Evaluated for 4 different pretension condition)
Table B-13. Shear and Slip Safety Factor of the Upper Derrick Footing for 1000 year Hurricane Load
Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)
Table B-14 . Shear and Slip Safety Factor of the Substructure Footing for 1000 year Hurricane Load
Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)
Table B-15.         Shear and Slip Safety Factor of the Upper Derrick and the Substructure Footing for 1000
year Hurricane Load Condition (Evaluated for 4 different pretension condition)
Table E1. Maximum bolt tension on upper derrick (0-degree heading unit: kips, negative sign=tension on
bolt)96
Table E2. Maximum bolt tension on upper derrick (45-degree heading unit: kips, negative sign=tension
on bolt)

Table E3. Maximum bolt tension on sub-structure footing (0-degree heading unit: kips, negative	
sign=tension on bolt)	.96
Table E4. Maximum bolt tension on sub-structure footing (45-degree heading unit: kips, negative	
sign=tension on bolt)	.96

## List of Figures

Figure 1. Configuration of the TLP Hull
Figure 2. Panel for Hydrodynamic Computation by WAMIT and Body Fixed Coordinate System
Figure 3. Global Configuration of the Hull/Mooring Line/Riser
Figure 4. Zoom in of the Global Configuration of the System9
Figure 5. Definition Sketch of the Coordinate System and Free Body Diagram of the Derrick14
Figure 6. The Configuration of Derrick and Substructure
Figure 7. Configuration of the Upper Derrick and the Substructure Footings
Figure 8. A Typical Connection at Derrick Base & at Substructure base
Figure 9. Statistics of Derrick COG Motion - Three Main Modes for 180 Degree Incident Angle
Figure 10. Statistics of Derrick COG Acceleration - Three Main Modes for 180 Degree Incident Angle 21
Figure A-1. Incident Wave Time History and Power Spectrum (10 Year Hurricane; Hs=24.9ft, Tp=11.9,
γ =2.4)
Figure A-2. Motion Time Series and Spectrum at the Upper Derrick CG for 10 Year Hurricane
Figure A-3. Velocity Time Series and Spectrum at the Upper Derrick CG for 10 Year Hurricane
Figure A-4. Acceleration Time Series and Spectrum at the Upper Derrick CG for 10 Year Hurricane42
Figure A-5. Incident Wave Time History and Power Spectrum (100 Year Hurricane; Hs=24.9ft, Tp=14.0,
γ=2.4)
Figure A-6. Motion Time Series and Spectrum at the Upper Derrick CG for 100 Year Hurricane
Figure A-7. Velocity Time Series and Spectrum at the Upper Derrick CG for 100 Year Hurricane
Figure A-8. Acceleration Time Series and Spectrum at the Upper Derrick CG for 100 Year Hurricane49
Figure A-9. Incident Wave Time History and Power Spectrum (1000 Year Hurricane; Hs=51.9ft,
Tp=15.6, $\gamma = 3.0$ )
Figure A-10. Motion Time Series and Spectrum at the Upper Derrick CG for 1000 Year Hurricane 52
Figure A-11. Velocity Time Series and Spectrum at the Upper Derrick CG for 1000 Year Hurricane 54
Figure A-12. Acceleration Time Series and Spectrum at the Upper Derrick CG for 1000 Year Hurricane
Figure A-13. Resultant Inertia, Gravitational and Wind Forces and Moments Acting on the Upper
Derrick for 10 Year Hurricane Condition (Moment is with respect to the Derrick Footing Level)
Figure A-14. Resultant Inertia, Gravitational and Wind Forces and Moments Acting on the Upper
Derrick for 100 Year Hurricane Condition (Moment is with respect to the Derrick Footing Level)

Figure A-15. Resultant Inertia, Gravitational and Wind Forces and Moments Acting on the Upper
Derrick for 1000 Year Hurricane Condition (Moment is with respect to the Derrick Footing Level) 65
Figure A-16. Reaction Forces at Derrick Point (Positive sign means upward and negative downward
direction in the normal reaction force) for 10 Year Hurricane Condition67
Figure A-17. Reaction Forces at Derrick Footing Point (Positive sign means upward and negative
downward direction in the normal reaction force) for 100 Year Hurricane Condition
Figure A-18. Reaction Forces at Derrick Footing Point (Positive sign means upward and negative
downward direction in the normal reaction force) for 1000 Year Hurricane Condition
Figure A-19. Resultant Inertia, Gravitational and Wind Forces and Moments Acting on the Upper
Derrick and Substructure for 10 Year Hurricane Condition (Moment is with respect to the Substructure
Footing Level)74
Figure A-20. Resultant Inertia, Gravitational and Wind Forces and Moments Acting on the Upper
Derrick and Substructure for 100 Year Hurricane Condition (Moment is with respect to the Substructure
Footing Level)
Figure A-21. Resultant Inertia, Gravitational and Wind Forces and Moments Acting on the Upper
Derrick and Substructure for 1000 Year Hurricane Condition (Moment is with respect to the Substructure
Footing Level)
Figure A-22. Reaction Forces at Substructure Footing Point (Positive sign means upward and negative
downward direction in the normal reaction force) for 10 Year Hurricane Condition
Figure A-23. Reaction Forces at Substructure Footing Point (Positive sign means upward and negative
downward direction in the normal reaction force) for 100 Year Hurricane Condition
Figure A-24. Reaction Forces at Substructure Footing Point (Positive sign means upward and negative
downward direction in the normal reaction force) for 1000 Year Hurricane Condition

#### 1.0 SUMMARY

#### 1.1 Scope

This report summarizes the results of the global motion analysis of the Deep Star TLP in 1000 year hurricane condition as well as in 10 year and 100 year hurricane. WAMIT, a second order diffraction/radiation program, was utilized to calculate the frequency dependent hydrodynamic coefficients and the first-order and the second-order sum and difference frequency wave excitation forces. Due to the stiff tendon system of TLP, the heave, roll and pitch natural periods are around 3-4 seconds and the surge and sway natural periods are about 100-160 seconds, which are out of the wave frequency range. Thus, the second order wave loads of sum and difference frequencies are so important that they may not be ignored. Three hour time domain simulation were carried out by a TAMU hull/mooring/riser coupled dynamics analysis program, in the 10 year, 100 year and 1000 year hurricane condition. The force components, such as wind, gravitational and inertia forces, acting on a derrick are obtained through the global motion of the hull to calculate the shear and axial reaction forces at the derrick footing. The calculation is to evaluate the maximum load on the tie-down equipment in the extreme survival condition.

#### 2.0 INTRODUCTION

Many platforms have been designed and installed in GOM (Gulf of Mexico) since the offshore oil and gas industry was born off in 1940's. Most of them have been designed for 100 year return hurricane as the environmental criteria according to API RP2A[1], while the others are designed to survive in 1000 year return hurricane. Recently, there were several severe hurricanes, such as Ivan, Katrina and Rita, which caused the minor and major damages of the platforms. The recent successive severe hurricane events raised the question whether the current design criteria is suitable or not. This study is based on such demands to investigate the robustness of the design criteria in GOM.

A global motion analysis of a typical TLP in GOM, the Deep Star TLP, is performed in severe environmental condition using Charm3D, a computer program of hull and mooring/riser coupled analysis in frequency and time domain[2]. Ten year, 100 year and 1000 year return hurricanes are considered as environmental conditions.

WAMIT[3] is used to calculate the hydrodynamic coefficients such as added mass and hydrodynamic damping and the first and second wave excitation forces. The external stiffness due to tendon and riser is calculated and included in addition to the hydrostatic stiffness due to hull geometry in WAMIT computation so that more accurate motions are obtained in frequency domain because the second order wave excitation force in frequency domain is motion-dependent. The Charm3D is based on the hybrid model of Morison members and a panelized body. The potential forces on column and pontoon are obtained from WAMIT while the viscous effects are considered through the Morison equation.

To calculate the reaction shear and axial forces at a derrick base, equations of force and moment equilibrium of derrick are set up and solved. The results are examined and discussed in the view point of the safety of a top side component in the severe hurricane condition.

#### 3.0 SPECIFICATION OF DEEP STAR TLP

The principal dimensions of the platform are tabulated in Table 1, which are based on Ref. [4]. The TLP consists of four circular columns of 54 ft. outer diameter which are connected at the keel by rectangular pontoons of 27 ft. width and 24 ft. height. The center to center distance is 200 ft. The hull is attached to eight tendons (two tendons at each column), and one drilling TTR and seven production. TTRs are connected to the hull by hydraulic pneumatic tensioners at 120.08 ft. above the mean water level (MWL). The detailed configurations are shown in Figure 1 by the side and the plan views of it.

The In-Place draft, 80 ft., is selected as a base case to estimate the hydrostatic and mass properties. The load condition and corresponding values are shown in Table 2. The total weight is 53,256 kips, the total tendon pretension at the top (porch) is 15,500 kips, and the riser total pretension at the top is 3,500 kips. Vertical center of gravity (COG) is at 28.1 ft. above MWL and vertical center of buoyancy (COB) is at 49.8 ft. below MWL. The roll and pitch radii of gyration are 108.9 ft. and the yaw radius of gyration is 106.3 ft.

The wind load coefficient is  $C_{eff} = F_w / V_{10}^2 = 0.0665$  kips/(ft/sec)^2 at the center of pressure 125 ft. from MWL, where  $F_w$  is total wind force on the hull above MWL and  $V_{10}$  is the 1 hour averaged wind speed at 10m level above MWL.

12 spread mooring lines, 6 SCRs and 8 TTRs are modeled. The 8 TTRs are modeled as an equivalent one. The tensioner stiffness of a TTR is assumed to be 25 kips/ft. The mooring and riser configuration is shown in Table 3.

3000					
4					
54					
200					
67					
27					
24					
75					
40					

Table 1. Principal Dimensions

Draft (ft)	80.0
Total weight (kips)	53,256
Tendon Pretension at the top (kips)	15,500
Riser Pretension at the top (kips)	3,500
Displacements (kips)	72,256
Vertical Center of Gravity from MWL(ft)	28.1
Vertical Center of Buoyancy from MWL(ft)	-49.8
Roll Radius of Gyration (ft)	108.9
Pitch Radius of Gyration (ft)	108.9
Yaw Radius of Gyration (ft)	106.3
Wind Load Coefficient(kips/(ft/sec)^2)	0.0665
Center of Pressure from MWL (ft)	125.0

Table 2. Hull Load Condition at In-Place Draft

 Table 3. Configuration of the Mooring Line.

	#	X (ft)	Y (ft)	Z (ft)	X (ft)	Y (ft)	Z (ft)	To(kips)
Tendon	1	108.29	130.92	-72.51	108.29	130.92	-3000.15	1.94E+03
	2	130.92	108.29	-72.51	130.92	108.29	-3000.15	1.94E+03
	3	130.92	-108.29	-72.51	130.92	-108.29	-3000.15	1.94E+03
	4	108.29	-130.92	-72.51	108.29	-130.92	-3000.15	1.94E+03
	5	-108.29	-130.92	-72.51	-108.29	-130.92	-3000.15	1.94E+03
	6	-130.92	-108.29	-72.51	-130.92	-108.29	-3000.15	1.94E+03
	7	-130.92	108.29	-72.51	-130.92	108.29	-3000.15	1.94E+03
	8	-108.29	130.92	-72.51	-108.29	130.92	-3000.15	1.94E+03
Drill Riser	1	-7.5	-7.5	120.08	-7.5	-7.5	-3000.15	4.54E+02
Production	1	7.5	7.5	120.08	7.5	7.5	-3000.15	2.30E+02
Riser	2	22.5	7.5	120.08	22.5	7.5	-3000.15	2.30E+02
	3	22.5	-7.5	120.08	22.5	-7.5	-3000.15	2.30E+02
	4	7.5	-7.5	120.08	7.5	-7.5	-3000.15	2.30E+02
	5	-22.5	-7.5	120.08	-22.5	-7.5	-3000.15	2.30E+02
	6	-22.5	7.5	120.08	-22.5	7.5	-3000.15	2.30E+02
	7	-7.5	7.5	120.08	-7.5	7.5	-3000.15	2.30E+02



Figure 1. Configuration of the TLP Hull

#### 4.0 NUMERICAL MODELING OF HULL, TENDONS AND RISERS

#### 4.1 Hydrodynamic Modeling with WAMIT

The added mass and radiation damping coefficients, first-order wave excitation forces, and second order sum and difference frequency forces are calculated by the second-order diffraction/radiation program, WAMIT[2]. The tendons and the TTRs are considered as an external stiffness in the frequency domain calculation. The stiffness is added to the hydrostatic stiffness due to the hull geometry, which increases the accuracy of the motion response and the second order forces as well. All the hydrodynamic coefficients are calculated in the frequency domain, and the corresponding forces are converted to the time domain using two-term Volterra series expansion [3]. The frequency-dependent radiation damping was included in the form of convolution integral in the time domain simulation. In Figure 2, the panel configuration for the WAMIT is shown. The body fixed coordinate reference is on the free surface at the centroid of water plane area of the columns. The x-axis is parallel to the pontoon and the z-axis is upward positive. The TLP hull is discretized by 1420 panels and the free surface is discretized by 1070 panels inside a truncation radius.



Figure 2. Panel for Hydrodynamic Computation by WAMIT and Body Fixed Coordinate System

#### 4.2 Fully Coupled Analysis Modeling with HARP

Figure 3 shows the global configuration of the platform and tendon/riser coupled system. The water depth is 3000 ft., and the tendons and the risers are all attached down to the sea bed with linear spring. The tendons are also coupled with the hull by the linear spring, while the TTRs are couple with it by numerical pneumatic tensioner model. The relation between tension and the stroke of the tensioner model is obtained through the following nonlinear relation.

$$T = \frac{T_0}{\left(1 + z/z_0\right)^n} \tag{1}$$

, where

z : stroke of the piston with upward direction positive,

- $z_0$ : effective length of gas in the associated accumulator,
- $T_0$ : Initial top tension at stroke z=0.
- n: gas constant.

Figure 3 shows the zoom-in feature near the platform. The centerlines of the columns and the pontoons represent the Morrison tubular members to model the drag force of the columns and the pontoons.



Figure 3. Global Configuration of the Hull/Mooring Line/Riser



Figure 4. Zoom in of the Global Configuration of the System

#### 5.0 ENVIRONMENTAL CONDITION

Ten year, 100 year and 1000 year return hurricane events are selected as environmental conditions. Table 4. shows the typical wave, wind and current characteristics of each environmental condition. JONSWAP spectrum is used for the long crested irregular wave generation with the given stiffness parameter,  $\gamma$ . Time varying wind speed is generated by using the API spectrum. Wave incident angle is 180 degrees, and the wind and the current are associated with the wave in the direction.

Return Period	10 year		100 year		Ivan	
Hs (ft)	24.9		40.0		51.1	
Tp (sec)	11.9		14.0		15.6	
γ*	2.4			2.4		3.0
Wind Speed** (knot)	50.9		81.3		87.9	
Current Profile	Depth(ft)	Speed(ft/s)	Depth(ft)	Speed(ft/s)	Depth(ft)	Speed(ft/s)
	0.0	2.59	0.0	4.92	0.0	8.19
	98.4	1.97	98.4	3.77	16.4	8.19
	196.9	0.95	196.9	1.84	82.0	3.92
	295.3	0.33	295.3	0.33	164.1	3.69
	3000.0	0.33	3000.0	0.33	264.1	2.44
					328.1	1.02
					492.2	0.95
					984.3	0.88
					3000.0	0.00

 Table 4.
 Environmental Conditions

\* JONSWAP spectrum is used for the irregular wave generation with the given  $\gamma$ 

\*\* The wind speed is 1 hour averaged one at 10m above MWL, and API wind spectrum is used for the time varying wind speed generation.
#### 6.0 REACTION FORCE ON THE DERRICK BASE

Let the inertia coordinate system  $(\underline{x}_1, \underline{x}_2, \underline{x}_3)$ , then the body fixed coordinate system  $(\underline{b}_1, \underline{b}_2, \underline{b}_3)$  experience the translational motion  ${}^{N}\underline{x}_t$  and the rotational motion  $\underline{\theta}_{B/N}$  with respect to the inertia coordinate system (Refer to Figure 5.), where superscript *N* means "with respect to the inertia frame" and superscript B means "with respect to the body fixed coordinate system". Assume the derrick is on the deck by the four point support at  $\underline{p}^1$ ,  $\underline{p}^2$ ,  $\underline{p}^3$  and  $\underline{p}^4$ , and that each support has the substructure tied-down by bolts as in Figure 6.

The velocity of the point,  ${}^{B}\underline{r}$  or  ${}^{N}\underline{R}$ , on the platform is obtained by the time derivative in the inertia frame as :

$$\frac{d\underline{R}}{dt} = \underline{\dot{x}}_t + \underline{\dot{\theta}}_{B/N} \times {}^B \underline{r}$$
<sup>(2)</sup>

The inertial acceleration is found by taking the inertial derivative of velocity as:

$$\frac{d^{2}\underline{R}}{dt^{2}} = \underline{\ddot{x}}_{t} + \underline{\ddot{\theta}}_{B/N} \times {}^{B}\underline{r} + \underline{\dot{\theta}}_{B/N} \times \left(\underline{\dot{\theta}}_{B/N} \times {}^{B}\underline{r}\right)$$
(3)

Integrating the infinitesimal linear inertial force contributions over the entire body, the total linear inertia force is given by:

$$\int_{B}^{N} \frac{d^{2}\underline{R}}{dt^{2}} dm = [M] \underline{\ddot{x}}_{t} - [\underline{r}_{g}^{\times}] \{\underline{\ddot{\theta}}_{B/N}\} - [\underline{\dot{\theta}}_{B/N}^{\times}] ([\underline{r}_{g}^{\times}] \{\underline{\dot{\theta}}_{B/N}\})$$
(4)

where

$$\begin{bmatrix} M \end{bmatrix} = \begin{bmatrix} m & 0 & 0 \\ 0 & m & 0 \\ 0 & 0 & m \end{bmatrix},$$
$$\begin{bmatrix} \underline{mr}_{g}^{\times} \end{bmatrix} = \int_{M} \begin{bmatrix} \underline{r}^{\times} \end{bmatrix} dm,$$

The angular momentum is obtained by integrating the infinitesimal angular momentum contributions over the entire body.

$$\underline{H} = \int_{M} \underline{r} \times \int_{M}^{N} \frac{d\underline{R}}{dt} dm = \int_{M} \underline{r} dm \times \underline{\dot{x}}_{t} + \int_{M} - \left[\underline{r}^{\times}\right] \left[\underline{r}^{\times}\right] dm \left\{\underline{\dot{\theta}}_{B/N}\right\}$$
(5)

Taking the time derivative of angular momentum gives

$$\frac{d\underline{L}}{dt} = \left[\underline{m}\underline{r}_{g}^{\times}\right] \{\underline{\ddot{x}}_{t}\} + [I]\{\underline{\ddot{\theta}}_{B/N}\}$$
(6)  
, where  

$$\left[I\right] = \int_{M} -\left[\underline{r}^{\times}\right] [\underline{r}^{\times}] dm.$$

Thus, the force equilibrium from the free body diagram at Figure 5. is written as:

$$\begin{bmatrix} M \end{bmatrix} \ddot{\underline{x}}_{t} - \begin{bmatrix} \underline{mr}_{g}^{\times} \end{bmatrix} \left\{ \ddot{\underline{\theta}}_{B/N} \right\} - \begin{bmatrix} \dot{\underline{\theta}}_{B/N}^{\times} \end{bmatrix} \left( \begin{bmatrix} \underline{r}_{g}^{\times} \end{bmatrix} \left\{ \dot{\underline{\theta}}_{B/N} \right\} \right) = \left\{ \underline{f}_{g} \right\} + \left\{ \underline{f}_{wind} \right\} + \sum_{i=1}^{4} \left\{ \underline{f}_{r}^{i} \right\}$$
(7)

where

 $\underline{f}_{g} = \text{gravitational force,}$   $\underline{f}_{wind} = \text{wind force,}$   $\underline{f}_{r}^{i} = \text{reaction force at the bolting point } \underline{p}^{i}.$ 

The moment equilibrium around the body reference point goes to

$$\left[\underline{mr}_{g}^{\times}\right]\left\{\underline{\ddot{x}}_{t}\right\} + \left[I\right]\left\{\underline{\ddot{\theta}}_{B/N}\right\} = \left[\underline{r}_{g}^{\times}\right]\left\{\underline{f}_{g}\right\} + \left[\underline{r}_{wind}^{\times}\right]\left\{\underline{f}_{wind}\right\} + \sum_{i=1}^{4}\left[\underline{p}^{i\times}\right]\left\{\underline{f}_{r}^{i}\right\}$$
(8)

The wind force and the gravitational force are expressed in global coordinate. Thus, coordinate transformation is necessary to express them in the body fixed coordinate. The Euler angle representation of the transformation is used.

The standard yaw-pitch-roll angles are selected as a sequence of rotational angles. Then, resultant transform matrix is obtained in Equation (12).

$$\left\{\underline{b}\right\} = \left\{\underline{b}_{1}\\\underline{b}_{2}\\\underline{b}_{3}\right\} = \begin{bmatrix}c\theta_{3} & s\theta_{3} & 0\\-s\theta_{3} & c\theta_{3} & 0\\0 & 0 & 1\end{bmatrix} \left\{\underline{x}_{1}\\\underline{x}_{2}\\\underline{x}_{3}\right\} = \begin{bmatrix}E(\theta_{3})]\{\underline{x}\}$$
(9)

$$\left\{\underline{b}\right\} = \left\{\underline{b}_{1}\\\underline{b}_{2}\\\underline{b}_{3}\right\} = \begin{bmatrix}c\theta_{2} & 0 & -s\theta_{2}\\0 & 1 & 0\\s\theta_{2} & 0 & c\theta_{2}\end{bmatrix} \left\{\underline{x}_{1}\\\underline{x}_{2}\\\underline{x}_{3}\right\} = \begin{bmatrix}E(\theta_{2})\end{bmatrix}\left\{\underline{x}\right\}$$
(10)

$$\left\{\underline{b}\right\} = \left\{\begin{array}{ccc}\underline{b}_{1}\\\underline{b}_{2}\\\underline{b}_{3}\end{array}\right\} = \begin{bmatrix}1 & 0 & 0\\0 & c\theta_{1} & s\theta_{1}\\0 & -s\theta_{1} & c\theta_{1}\end{bmatrix}\left\{\underline{x}_{2}\\\underline{x}_{3}\end{array}\right\} = \begin{bmatrix}E\left(\theta_{1}\right)\end{bmatrix}\left\{\underline{x}\right\}$$
(11)

$$\{\underline{b}\} = \left[E(\theta_1)\right] \left[E(\theta_2)\right] \left[E(\theta_3)\right] \{\underline{x}\} = \left[E(\underline{\theta})\right] \{\underline{x}\}$$
(12)

where

$$\begin{bmatrix} E(\underline{\theta}) \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & c\theta_1 & s\theta_1 \\ 0 & -s\theta_1 & c\theta_1 \end{bmatrix} \begin{bmatrix} c\theta_2 & 0 & -s\theta_2 \\ 0 & 1 & 0 \\ s\theta_2 & 0 & c\theta_2 \end{bmatrix} \begin{bmatrix} c\theta_3 & s\theta_3 & 0 \\ -s\theta_3 & c\theta_3 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} c\theta_2 c\theta_3 & c\theta_2 s\theta_3 & -s\theta_2 \\ s\theta_1 s\theta_2 c\theta_3 - c\theta_1 s\theta_3 & s\theta_1 s\theta_2 s\theta_3 + c\theta_1 c\theta_3 & s\theta_1 c\theta_2 \\ c\theta_1 s\theta_2 c\theta_3 + s\theta_1 s\theta_3 & c\theta_1 s\theta_2 s\theta_3 - s\theta_1 c\theta_3 & c\theta_1 c\theta_2 \end{bmatrix}$$

The body force is gravitational force acting on the center of gravity represented in the body fixed coordinate system is

$$\left\{ \underline{f}_{g} \right\} = \begin{bmatrix} E(\underline{\theta}) \end{bmatrix} \begin{cases} 0\\ 0\\ -mg \end{cases} \quad \text{at } \left\{ \overline{p}_{g} \right\} = \begin{cases} x_{g}\\ y_{g}\\ z_{g} \end{cases}$$
(13)

The environmental forces on the derrick is the wind which is only in horizontal plane in the global coordinate system. Transforming the wind force to the body fixed coordinate system is

$$\left\{ \underline{f}_{w} \right\} = \begin{bmatrix} E(\underline{\theta}) \end{bmatrix} \begin{cases} f_{wx} \\ f_{wy} \\ 0 \end{cases} \quad \text{at } \left\{ \underline{P}_{w} \right\} = \begin{cases} x_{w} \\ y_{w} \\ z_{w} \end{cases}$$
(14)

The reaction forces are at the four corners and they consist of normal force and the shear forces.



Figure 5. Definition Sketch of the Coordinate System and Free Body Diagram of the Derrick

#### 7.0 RESULTS

The reaction forces and the moments on the derrick and the substructure footing points are calculated with the formula given at the previous section. The corresponding slip force and the shear and the tensile forces acting on each bolt are calculated to give the safety factor of the footing against the environmental loadings.

The configuration of the derrick and the substructure is shown in Figure 6. The derrick is connected to the deck through the substructure. The footings of derrick connect the derrick and the substructure, and the substructure footings support the derrick and the substructure. A plan view of the footing layout is in Figure 7. The upper derrick footings are on the rail which is parallel to the y-axis to allow the slip only in y-direction. The shear force in x-direction is transferred to the bolt directly and the bolts need to resist the shear force. On the contrary, the substructure footings are laid on the rail parallel to x-direction to allow the slip in x-direction. Thus, the y-directional shear forces are totally transferred to the bolts.

Each footing has the eight bolts to give the pretension for the slip capacity as in Figure 8. Due to the layout of the bolts, the shear force is applied only to 4 bolts, while the tensile force is uniformly applied to 8 bolts. Therefore, the capacity of the shear force for a footing is determined by the those of 4 bolts and the tensile capacity is by 8 bolts. 1-1/2 inch bolts are used to tie down the structure and the corresponding shear and the tensile capacities for each bolt are estimated through the material property(Refer to Ref.3).

The derrick and the substructure are assumed to be positioned at the center of the deck, i.e. at the CG of the TLP, and the vertical CGs of the derrick and the substructure are shown in Table 5. The center of pressure of the wind force and the wind area of derrick and the substructure are also shown in the table. For the derrick, the projected area in x-direction is  $1470 \text{ ft.}^2$ , but the front part does not shade the area at the down stream. Thus, the double of the projected area(=2940 ft.<sup>2</sup>) is used. The resultant total wind area and the center of wind pressure at the last column are used to calculated the reaction forces on the substructure footings. The radius of gyrations are assumed and given in the table.



Figure 6. The Configuration of Derrick and Substructure



Figure 7. Configuration of the Upper Derrick and the Substructure Footings



Figure 8. A Typical Connection at Derrick Base & at Substructure base

······································	···· · · · · · · · · · · · · · · · · ·		
	Upper Derrick	Substructure	Total
Weight (kips)	550	1500	2050
Projected Area (ft <sup>2</sup> )	2940	500	3440
Center of Pressure from MWL (ft)	201	130	190
Center of Gravity from MWL (ft)	169	130	140.5
Height Coefficient( $C_h$ )*	1.37	1.19	1.24
Shape Coefficient( $C_s$ )*	1.25	1.25	1.25
Radius of Gyration around CG** (ft)	15/15/10	15/15/10	20/20/10

		-	
Table 5.	<b>Specifications</b>	of Upper	Derrick

\* Wind force is calculated by  $F_{wind} = 1/2\rho_{air}A_{project}C_hC_sV_{10m}^2$  (Refer to Technip Report) \*\* Assumed for the exact inertia force calculation through motion.

# 7.1 Derrick Motion

Derrick Motions are shown in Figure A-1 through A-12 in Appendix A. The Statistics of surge, heave and pitch are in figure 8, and the statistics of the accelerations in the directions are in figure 9.



(a) Surge Motion



(b) Heave Motion



(c) Pitch Motion

Figure 9. Statistics of Derrick COG Motion - Three Main Modes for 180 Degree Incident Angle



(a) Surge Acceleration



(b) Heave Acceleration



(c) Pitch Acceleration

Figure 10. Statistics of Derrick COG Acceleration - Three Main Modes for 180 Degree Incident Angle

# 7.2 Dynamic Forces on Derrick and Substructure

Surge(Kips)				
	Inertia	Gravitational	Wind	Total
Max	61.73	0.65	-18.50	21.80
Min	-61.22	-1.94	-97.31	-141.27
Mean	0.00	-0.54	-52.20	-52.75
Heave(kips)				
	Inertia	Gravitational	Wind	Total
Max	10.95	-554.00	0.26	-540.75
Min	-13.25	-554.00	-0.08	-564.95
Mean	0.01	-554.00	0.05	-553.96
Pitch	(kips-ft)			
	Inertia	Gravitational	Wind	Total
Max	1423.30	15.10	-1017.70	-265.30
Min	-1425.90	-44.50	-5351.80	-6184.80
Mean	0.00	-12.50	-2871.20	-2883.60

**Table 6. Statistics of Dynamic Forces on the Derrick for 10 Year Hurricane** Surge(kips)

 Table 7. Statistics of Dynamic Forces on the Derrick for 100 Year Hurricane

 Surge(kips)

	Inertia	Gravitational	Wind	Total	
Max	98.98	0.88	-46.74	32.36	
Min	-112.08	-3.11	-199.69	-252.01	
Mean	0.00	-1.19	-113.91	-115.11	
Heave(kips)	•				
	Inertia	Gravitational	Wind	Total	
Max	22.34	-553.99	0.91	-533.38	
Min	-20.55	-554.00	-0.19	-576.16	
Mean	-0.04	-554.00	0.25	-553.71	
Pitch (kips-ft)					
	Inertia	Gravitational	Wind	Total	
Max	2287.00	20.00	-2571.00	-1489.00	
Min	-2606.00	-72.00	-10983.00	-11543.00	
Mean	0.00	-27.00	-6265.00	-6293.00	

	Inertia	Gravitational	Wind	Total
Max	122.46	0.44	-47.20	17.72
Min	-144.24	-4.53	-248.25	-299.01
Mean	0.08	-1.53	-133.22	-134.83
Heave(kips)				
	Inertia	Gravitational	Wind	Total
Max	27.06	-553.98	1.41	-529.89
Min	-23.86	-554.00	-0.09	-580.60
Mean	0.44	-554.00	0.37	-554.06
Pitch	(kips-ft)			
	Inertia	Gravitational	Wind	Total
Max	2818.00	10.00	-2596.00	-1446.00
Min	-3343.00	-104.00	-13654.00	-14388.00
Mean	2.00	-35.00	-7327.00	-7364.00

**Table 8. Statistics of Dynamic Forces on the Derrick for 1000 Year Hurricane** Surge(kips)

 Table 9. Statistics of Dynamic Forces on the Derrick and the Substructure for 10 Year Hurricane

 Surge(kips)

	Inertia	Gravitational	Wind	Total
Max	227.24	2.42	-19.60	174.34
Min	-220.77	-7.16	-103.05	-281.35
Mean	0.00	-2.01	-55.29	-57.29
Heave(kips)				
	Inertia	Gravitational	Wind	Total
Max	40.50	-2050.00	0.30	-2001.00
Min	-49.00	-2050.00	-0.10	-2090.50
Mean	0.00	-2050.00	0.10	-2050.00
Pitch(kips-ft)				
	Inertia	Gravitational	Wind	Total
Max	5588.00	59.00	-1450.00	2277.00
Min	-5510.00	-176.00	-7626.00	-11660.00
Mean	0.00	-49.00	-4091.00	-4140.00

	Inertia	Gravitational	Wind	Total
Max	362.78	3.24	-49.50	318.81
Min	-405.48	-11.52	-211.48	-523.80
Mean	0.01	-4.42	-120.64	-125.07
Heave(kips)				
	Inertia	Gravitational	Wind	Total
Max	82.60	-2050.00	1.00	-1973.90
Min	-76.10	-2050.00	-0.20	-2132.50
Mean	-0.10	-2050.00	0.30	-2049.60
Pitch(kips-ft)				
	Inertia	Gravitational	Wind	Total
Max	8949.00	79.00	-3663.00	3839.00
Min	-10097.00	-282.00	-15649.00	-20945.00
Mean	0.00	-108.00	-8927.00	-9036.00

 Table 10. Statistics of Dynamic Forces on the Derrick and the Substructure for 100 Year Hurricane

 Surge(kips)

Table 11. St	atistics of Dyna	amic Forces on t	the Derrick and th	ne Substructure	for 1000 Yea	r Hurricane
Surge(kip	os)					
						1

	Inertia	Gravitational	Wind	Total
Max	452.75	1.63	-49.99	362.90
Min	-525.36	-16.77	-262.90	-597.29
Mean	0.25	-5.65	-141.08	-146.98
Heave(kips)				
	Inertia	Gravitational	Wind	Total
Max	100.10	-2049.90	1.50	-1961.40
Min	-88.30	-2050.00	-0.10	-2149.60
Mean	1.60	-2050.00	0.40	-2051.20
Pitch(kips-ft)				
	Inertia	Gravitational	Wind	Total
Max	11099.00	40.00	-3699.00	2293.00
Min	-13018.00	-411.00	-19455.00	-24482.00
Mean	7.00	-138.00	-10440.00	-10586.00

# 7.3 Reaction Forces on the Footings

	Fx	N1,N4	N2,N3
Max	35.32	132.31	263.11
Min	-5.45	15.23	142.92
Mean	13.19	80.82	196.16

Table 12. Reaction Forces on Upper Derrick Footing for 10 Year Hurricane

Table 13.	Reac	tion For	ces on Up	per	Derrick	Footi	ng for	100	Year	Hurricane
			1	,				-		

	Fx	N1,N4	N2,N3
Max	63.00	107.50	368.51
Min	-8.09	-93.19	167.08
Mean	28.78	12.57	264.28

Table 14. Reaction Forces on Upper Derrick Footing for 1000 Year Hurricane

	Fx	N1,N4	N2,N3
Max	74.75	109.10	425.18
Min	-4.43	-150.36	166.94
Mean	33.71	-8.77	285.80

 Table 15. Reaction Forces on Substructure Footing for 10 Year Hurricane

	Fx	N1,N4	N2,N3
Max	73.23	553.40	754.49
Min	-41.96	275.46	465.11
Mean	16.33	426.66	598.33

Table 16.	Reaction 1	Forces on	Substructure	Footing	for 1	00 Ye	ar Hurricane

	Fx	N1,N4	N2,N3
Max	130.95	581.38	939.28
Min	-79.70	101.50	427.82
Mean	31.27	331.68	693.11

Table 17. Reaction Forces on Substructure Footing for 1000 Year Hurricane

	Fx	N1,N4	N2,N3
Max	149.30	556.80	1009.20
Min	-90.70	29.90	463.60
Mean	36.70	301.10	724.50

# 7.4 Connection Capacity and Safety Factors

Torq (lb-ft)	T0 (kips)	Friction Coeff	P <sub>0</sub> (kips)	Ptot	Pder	Pder_tot	Psub	Psub_tot
2500	75	0.1	7.50	60.00	13.75	73.75	51.25	111.25
		0.3	22.50	180.00	41.25	221.25	153.75	333.75
		0.5	37.50	300.00	68.75	368.75	256.25	556.25
4576.7	137.301	0.1	13.73	109.84	13.75	123.59	51.25	161.09
		0.3	41.19	329.52	41.25	370.77	153.75	483.27
		0.5	68.65	549.20	68.75	617.95	256.25	805.45
5000	150	0.1	15.00	120.00	13.75	133.75	51.25	171.25
		0.3	45.00	360.00	41.25	401.25	153.75	513.75
		0.5	75.00	600.00	68.75	668.75	256.25	856.25
7500	225	0.1	22.50	180.00	13.75	193.75	51.25	231.25
		0.3	67.50	540.00	41.25	581.25	153.75	693.75
		0.5	112.50	900.00	68.75	968.75	256.25	1156.25

 Table 18. Friction Resistance Capacity (Slip Capacity)

#### Table 19. Tensile Capacity with Pretension

Rn	Bolt	Ten. Cap.	Total	
	Pretension	per Bolt	Capacity	
(kips)	(kips)	(kips)	(kips)	
247.4004	75.000	172.400	1379.203	
247.4004	137.301	110.099	880.795	
247.4004	150.000	97.400	779.203	
247.4004	225.000	22.400	179.203	

#### Table 20. Shear Capacity of bolts

Shear Capacity per Bolt =	Rn =	204.518	kips
Total Connection Shear Capacity =	(N/2)*Rn=	818.071	kips

Table 21.	Shear and Sli	p Safety	Factor of the	e Upper l	Derrick Footing	g for 10	year Hurricane	Load Conditi	on
							•		

Pretension	Fx (kips)	Fy(kips)	Bolt Shear Fact.	Bolt Slip Fact.	Of Safety (w	hen Fy=Fx)
(kips)	SHEAR	SLIP	of Safety	0.1	0.3	0.5
137.3	35.318	0.000	23.163	3.5	10.6	17.6
75	35.318	0.000	23.163	2.1	6.3	10.5
150	35.318	0.000	23.163	3.8	11.4	19.1
225	35.318	0.000	23.163	5.5	16.6	27.7

(2)	alantea loi .	anner ente pr	eremotom eomantion a		om eoem)	
Pretension	Fx (kips)	Fy(kips)	Bolt Shear Fact.	Bolt Slip	Fact. Of S	Safety
			of Safety(when			
(kips)	SLIP	SHEAR	Fy=Fx)	0.1	0.3	0.5
137.3	70.339	0.000	11.2	2.290	6.871	11.451
75	70.339	0.000	11.2	1.582	4.745	7.908
150	70.339	0.000	11.2	2.435	7.304	12.173
225	70.339	0.000	11.2	3.288	9.863	16.438

 

 Table 22. Shear and Slip Safety Factor of the Substructure Footing for 10 year Hurricane Load Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)

Table 23. Minimum Tension Safety Factor for 10 year Hurricane Load Condition (- means no tensil
loading)

	Fz	Т	Torque(lb-ft)	4576.7	2500	5000	7500
	(kips)	(kips)	T0(in kips) =	137.3	75	150	225
Upper Der	15.231	1.904	Safety Factors	-	-	-	-
Substruct	280.734	35.092	-	-	-	-	-

\*Positive Fz is compression with the view point of the bolt, and does not add the tensile force to it. Only negative reaction force adds the tensile force to the bolt.

 Table 24. Shear and Slip Safety Factor of the Upper Derrick Footing for 100 year Hurricane Load Condition

Pretension	Fx (kips)	Fy (kips)	Bolt Shear Fact.	Bolt Slip Fact. Of Safety(when Fy=		hen Fy=Fx)
			of Safety(when			
(kips)	SHEAR	SLIP	Fy=Fx)	0.1	0.3	0.5
137.3	63.001	0.000	12.985	1.9	5.9	9.8
75	63.001	0.000	12.985	1.2	3.5	5.8
150	63.001	0.000	12.985	2.1	6.4	10.6
225	63.001	0.000	12.985	3.0	9.2	15.3

 Table 25. Shear and Slip Safety Factor of the Substructure Footing for 100 year Hurricane Load Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)

Pretension	Fx (kips)	Fy(kips)	Bolt Shear Fact.	Bolt S	lip Fact. Of	Safety
			of Safety(when			
(kips)	SLIP	SHEAR	Fy=Fx)	0.1	0.3	0.5
137.3	130.950	0.000	6.3	1.230	3.691	6.151
75	130.950	0.000	6.3	0.850	2.549	4.248
150	130.950	0.000	6.3	1.308	3.923	6.539
225	130.950	0.000	6.3	1.766	5.298	8.830

	Fz	Т	Torque (lb-ft)	4576.7	2500	5000	7500
	(kips)	(kips)	T0 (in kips) =	137.3	75	150	225
Upper Der	-93.189	-11.649	Safety Factors	9.452	14.800	8.362	1.923
Substruct	101.501	12.688		-	-	-	-

Table 26. Minimum Tension Safety Factor for 100 year Hurricane Load Condition

\*Positive Fz is compression with the view point of the bolt, and does not add the tensile force to it. Only negative reaction force adds the tensile force to the bolt.

 Table 27. Shear and Slip Safety Factor of the Upper Derrick Footing for 1000 year Hurricane Load

 Condition

				Bolt Slip Fact. Of Safety (when		
Pretension	Fx (kips)	Fy (kips)	Bolt Shear Fact.	Fy=Fx)		
(kips)	SHEAR	SLIP	of Safety	0.1	0.3	0.5
137.3	74.753	0.000	10.944	1.6	4.9	8.2
75	74.753	0.000	10.944	0.98	2.9	4.9
150	74.753	0.000	10.944	1.8	5.3	8.9
225	74.753	0.000	10.944	2.6	7.7	12.9

Table 28.	Shear and Slip Safety Factor of the Substructure Footing for 1000 year Hurricane Load Condition
	(Evaluated for 4 different pretension condition and 3 friction coeff.)

Pretension	Fx (kips)	Fy (kips)	Bolt Shear Fact.	Bolt	Slip Fact. Of S	afety
			of Safety (when			
(kips)	SLIP	SHEAR	Fy=Fx)	0.1	0.3	0.5
137.3	149.300	0.000	5.5	1.079	3.237	5.395
75	149.300	0.000	5.5	0.745	2.235	3.726
150	149.300	0.000	5.5	1.147	3.441	5.735
225	149.300	0.000	5.5	1.549	4.647	7.744

	Fz	Т	Torque (lb-ft)	4576.7	2500	5000	7500	
	(kips)	(kips)	T0 (in kips) =	137.3	75	150	225	
Upper Der	-150.356	-18.795	Safety Factors	5.858	9.173	5.182	1.192	
Substruct	29.900	3.738	-	-	-	-	-	

Table 29. Minimum Tension Safety Factor for 1000 year Hurricane Load Condition

\*Positive Fz is compression with the view point of the bolt, and does not add the tensile force to it. Only negative reaction force adds the tensile force to the bolt.

### 8.0 INTERPRETATION AND DISCUSSION OF THE RESULTS

This case study is for a Deepstar TLP (3000 ft.) with the collinear wind, wave, and current from X direction. Three different environmental conditions, 10yr, 1000yr, 1000yr (IVAN), are considered. We check the possibility of slip and tensile failure at upper-derrick and substructure footings.

We first simulated the global motion of the TLP by using hull-mooring-riser coupled dynamic time-domain analysis program, WINPOST. Then, the platform motion and acceleration time series are inputted to the exact dynamic equations for a derrick to obtain the maximum shear force causing slip and maximum separation force causing additional tensile loading on bolts.

The exact results are compared with the current industry methodology based on API-4F.

API-4F recommendation for the dynamic loading estimation is based on a simple formula neglecting phase differences between accelerations and forces hoping that it will lead to conservative results. Furthermore, API formula neglects the effects of rotational inertia and centrifugal forces, which turned out to be insignificant in the present example.

One of the drawbacks of the current API-4F recommendation is the calculation methodology of the maximum acceleration, which is to be calculated by maximum motion amplitude multiplied by peak frequency (of input spectrum) squared. In the case of TLP, the actual peak frequency of pitch acceleration is quite different from the input-spectrum peak frequency. Therefore, in this kind of case, the maximum acceleration values read directly from the acceleration time series had better to be used.

Example spectrum peak frequency=0.4 rad/s, pitch acceleration peak frequency=2 rad/s, surge acceleration peak frequency= 0.4 rad/s (see attached figures)

In the following, we summarize the results only for the case of IVAN.

# (1) At Upper Derrick Footing

We follow the same procedure as Technip for the slip and tensile capacity of the derrick connection by bolts. In reality, the actual normal force causing frictional resistance can be smaller than the pretension of the bolts, so the slip capacity is actually smaller than the given numbers by Technip. In tensile and slip capability, the flexibility of the plates can play a role but in the present case, it is assumed that they are all rigid.

In calculating the exact dynamic equation of the upper derrick, the pitch-roll radius of gyration of the upper derrick is assumed to be 15 ft.

In all cases, the shear loading is much smaller than the bolt shear capacity (per connection=818 kips), therefore there is no chance of bolt shear failure at upper-derrick footing.

### [Dynamic Loading by simple(API4F) formulas]

Shear

- 1. API with accel time series: m(r x pit accel + hor accel)= 17080 x (0.006 x 169+8)=17080 x 9=154 kips (38 kips per connection)
- 2. API4F original : hor accel=0.16x20=3.2 ; 17080 x (0.001 x 169 + 3) = 51 kips (13 kips per connection)

It is clearly seen that the original API 4F formula underestimates the dynamic X loading by factor of 3 in the case of TLP.

Then using API4F with accel time series:

Shear per connection: by wind = 62kips, by dynamics=36kips, by grav=1 kips : total=**99** kips

Tensile per connection: by wind = 272kips, by dynamics=66kips, by grav=-137 kips : total=**201 kips** 

This simple formula does not consider phase differences between constituent forces.

# [Exact Method]

By using the exact dynamic equation of upper derrick and acceleration time series of platform, we obtain the following results (see attached table and time series).

Shear per connection = **75 kips** 

Tensile per connection=150 kips

Using the same Shear and Tensile Capacity of Technip (per connection)

Slip failure occurs when bolt pretension=75 kips and friction coef=0.1(capacity=74 kips)

Tensile failure does not occur even for the smallest tensile capacity case (capacity=178 kips)

## [Possible Increase by 45-deg heading]

We can do/repeat the same simulation and analysis for 45-deg heading. Here, we use simple estimation based on the load and arm increase.

It is likely that the wind and dynamic loading are increased by factor of 1.414. Similarly, the maximum tensile force is increased by factor of  $1.414 \times 1.43=2$  $(1.43=25 \times 2/35:1$  bolt resists instead of 2 bolts and the new arm is 35 ft. instead of 25 ft.)

(for 45-deg heading)

Shear per connection = **106 kips** 

Tensile per connection=300 kips

In this case,

Slip failure occurs when bolt pretension=75 kips and friction coef=0.1 (capacity=74 kips)

Tensile failure occurs when bolt-pretension= 225 kips. (capacity=178 kips)

# (2) At Substructure Footing

We assume that the weight of substructure=1500 kips and the CG is located 130 ft. above MWL. Its wind projected area= 500 ft.^2 and wind CP=CG. We follow the same procedure as Technip for the slip and tensile capacity of the derrick connection by bolts.

In calculating the exact dynamic equation of the upper derrick, the pitch-roll radius of gyration of the upper derrick + substructure is assumed to be 20 ft. The new center of gravity and center of pressure of the upper+lower deck structure are 140.5 ft. and 190 ft. above MWL.

In all cases, the shear loading is much smaller than the bolt shear capacity (per connection=818 kips), therefore there is no chance of bolt shear failure at substructure footing.

# [Dynamic Loading by simple(API4F) formulas]

Shear

API with accel time series:  $m(r \ x \ pit \ accel + hor \ accel) = 63664 \ x \ (0.006 \ x \ 141+8)=17080 \ x$ 9=563 kips (141kips per connection)

Then using API4F with accel time series:

Shear per connection: by wind = 66 kips, by dynamics=141 kips, by grav=2 kips : total=**209 kips** 

Tensile per connection: by wind = 387 kips, by dynamics=262 kips, by grav=-512 kips : total=**137 kips** 

The minus sign means compressional (not tensile) loading.

At the substructure footing, the shear causing slip is increased (about twice) and the tensile loading is decreased compared to the upper-derrick case. This simple formula does not consider phase differences between constituent forces.

# [Exact Method]

By using the exact dynamic equation of upper derrick and acceleration time series of platform, we obtain the following results (see attached table and time series).

Shear per connection = 149 kips

Tensile per connection=-29 kips

Compared to the upper-derrick case, the shear loading causing slip is increased by factor of two but there is no tensile loading on the bolts.

Using the same Shear and Tensile Capacity of Technip (per connection)

Slip failure occurs when (i) bolt pretension=75 kips and friction coef=0.1(capacity=111 kips)

Tensile failure does not occur even for the smallest tensile capacity case (capacity=178 kips)

### [Possible Increase by 45-deg heading]

We can do/repeat the same simulation and analysis for 45-deg heading. Here, we use simple estimation based on the load and arm increase.

It is likely that the wind and dynamic loading are increased by factor of 1.414.

(for 45-deg heading) Shear per connection = **210 kips** In this case,

Slip failure occurs when (i) bolt pretension=75 kips and friction coef=0.1 (capacity=111 kips) and (ii) bolt pretension=150 kips and friction coef=0.1 (capacity=17 1kips).

Tensile failure does not occur.

# 8.1 Platform Acceleration Results

In the following, the platform acceleration results can be summarized as follows

	10yr	100yr	1000yr
SPAR	0.2	0.4	0.51
TLP	0.15	0.2	0.26

Maximum Lateral Acceleration (normalized by g)

Maximum Vertical Acceleration (normalized by g)

	10yr	100yr	1000yr
SPAR	0.01	0.015	0.027
TLP	0.02	0.04	0.05

It is seen that the horizontal acceleration of a TLP is about half of that of spar. The vertical acceleration of a TLP is about twice the spar vertical acceleration. From this comparison, it is expected that spars have greater dynamic (inertia) loading than TLPs. Considering the same wind loading and weight for the identical derrick design, spar derrick is less safe that the TP derrick.

### 8.2 Recommendation based on the present study

If bolt pretension is too small, slip failure is likely to occur. In case bolt pretension is too large, the system is vulnerable to tensile failure. Therefore, maintaining proper middle-range tension especially during the hurricane is important.

It is important to check how much slip capacity can be reduced during the wet weather condition. Can the friction coefficient be as low as 0.1? If so, the safety of the derrick system under this condition should be checked.

Another uncertainty associated with slip failure is to find the actual grip force by bolts to prevent slip. It needs to be checked how much the slip capacity can be reduced by the present bolt-based connection method. If the actual grip force is smaller than the pretension, which value should be used in the derrick design?

Substructure connection is more vulnerable to the slip failure compared to upper-derrick connection, so stronger tightening method needs to be used.

In case of TLP, API4F dynamic loading based on motion amplitude can be significantly smaller than that with accel. time series.

Simple formulas with accel. time series but without considering phase differences between constituent forces tend to be conservative in the case of present example. However, it is not clear whether it is also conservative for other design conditions and other platform types since rotary inertia and centrifugal forces are missing.

A new method using the platform global-motion time series and exact derrick dynamic equations is recommended as a new methodology to check the slip and tensile failure of derrick connection.

# 9.0 REFERENCES

[1] Lee, C.H., Korsmeyer, F.T. (1999), WAMIT User manual, Dept. of Ocean Engineering, MIT.

[2] Kim, M.H. WINPOST User manual, Texas A&M University.

[3] Kim, M.H., Tahar, A. and Kim, Y.B.(2001), "Variability of TLP Motion Analysis Against Various Design Methodologies/Parameters", Proceedings of 11<sup>th</sup> ISOPE conference, Stavanger, vol.III, pp.467-473.

# 10.0 APPENDIX A: FIGURES FOR THE 180 DEGREE CASE



Figure A-1. Incident Wave Time History and Power Spectrum (10 Year Hurricane; Hs=24.9ft, Tp=11.9,  $\gamma = 2.4$ )















Figure A-5. Incident Wave Time History and Power Spectrum (100 Year Hurricane; Hs=24.9ft, Tp=14.0,  $\gamma$  =2.4)





(c) Pitch Figure A-6. Motion Time Series and Spectrum at the Upper Derrick CG for 100 Year Hurricane



(b) Heave








Figure A-9. Incident Wave Time History and Power Spectrum (1000 Year Hurricane; Hs=51.9ft, Tp=15.6,  $\gamma$  =3.0)















(a) Surge Direction



(b) Heave Direction



(c) Pitch Direction

Figure A-13. Resultant Inertia, Gravitational and Wind Forces and Moments Acting on the Upper Derrick for 10 Year Hurricane Condition (Moment is with respect to the Derrick Footing Level)



(a) Surge Direction



(b) Heave Direction



(c) Pitch Direction

Figure A-14. Resultant Inertia, Gravitational and Wind Forces and Moments Acting on the Upper Derrick for 100 Year Hurricane Condition (Moment is with respect to the Derrick Footing Level)



(a) Surge Direction



(b) Heave Direction



(c) Pitch Direction

Figure A-15. Resultant Inertia, Gravitational and Wind Forces and Moments Acting on the Upper Derrick for 1000 Year Hurricane Condition (Moment is with respect to the Derrick Footing Level)



(b) Figure Normal Reaction Force at Footing #1 and #4 (Refer to Figure 5)



(c) Normal Reaction Force at Footing #2 and #3 (Refer to Figure 5)

Figure A-16. Reaction Forces at Derrick Point (Positive sign means upward and negative downward direction in the normal reaction force) for 10 Year Hurricane Condition



(b) Figure Normal Reaction Force at Footing #1 and #4 (Refer to Figure 5)



(c) Normal Reaction Force at Footing #2 and #3 (Refer to Figure 5)

Figure A-17. Reaction Forces at Derrick Footing Point (Positive sign means upward and negative downward direction in the normal reaction force) for 100 Year Hurricane Condition



(b) Figure Normal Reaction Force at Footing #1 and #4 (Refer to Figure 5)



(c) Normal Reaction Force at Footing #2 and #3 (Refer to Figure 5)

Figure A-18. Reaction Forces at Derrick Footing Point (Positive sign means upward and negative downward direction in the normal reaction force) for 1000 Year Hurricane Condition



(a) Surge Direction



(b) Heave Direction



(c) Pitch Direction

Figure A-19. Resultant Inertia, Gravitational and Wind Forces and Moments Acting on the Upper Derrick and Substructure for 10 Year Hurricane Condition (Moment is with respect to the Substructure Footing Level)



(a) Surge Direction



(b) Heave Direction



(c) Pitch Direction

Figure A-20. Resultant Inertia, Gravitational and Wind Forces and Moments Acting on the Upper Derrick and Substructure for 100 Year Hurricane Condition (Moment is with respect to the Substructure Footing Level)



(a) Surge Direction



(b) Heave Direction



(c) Pitch Direction

Figure A-21. Resultant Inertia, Gravitational and Wind Forces and Moments Acting on the Upper Derrick and Substructure for 1000 Year Hurricane Condition (Moment is with respect to the Substructure Footing Level)



(a) Shear Reaction Force acted by the Connection point



(b) Figure Normal Reaction Force at Footing #1 and #4 (Refer to Figure 5)


(c) Normal Reaction Force at Footing #2 and #3 (Refer to Figure 5)

Figure A-22. Reaction Forces at Substructure Footing Point (Positive sign means upward and negative downward direction in the normal reaction force) for 10 Year Hurricane Condition



(a) Shear Reaction Force acted by the Connection point



(b) Figure Normal Reaction Force at Footing #1 and #4 (Refer to Figure 5)



(c) Normal Reaction Force at Footing #2 and #3 (Refer to Figure 5)

Figure A-23. Reaction Forces at Substructure Footing Point (Positive sign means upward and negative downward direction in the normal reaction force) for 100 Year Hurricane Condition



(a) Shear Reaction Force acted by the Connection point



(b) Figure Normal Reaction Force at Footing #1 and #4 (Refer to Figure 5)



(c) Normal Reaction Force at Footing #2 and #3 (Refer to Figure 5)

Figure A-24. Reaction Forces at Substructure Footing Point (Positive sign means upward and negative downward direction in the normal reaction force) for 1000 Year Hurricane Condition

## 11.0 APPENDIX B: 135 DEGREE CASE

The 135 degree case is considered by approximating the motions and the forces from the 180 degree results.

First, the sway motions are assume to be the same as those of the 180 degree case but in the opposite direction. The heave, roll and yaw motions are assumed to be the same as those of the pitch motion of 180 degree case. The wind forces in y-direction is in the opposite direction with the magnitude the same as those of 180 degree case. As the wave, wind and current are from foot #2 to foot #4 in 135 degree case, the foot #2 is to have more tension, while foot #4 has more compression force than the others.

- The horizontal slip at substructure footings may occur at the friction coefficient of 0.1 and the pretension of 75 kips for both 100 year and 1000 year hurricane events.

- The maximum tension is found at the footing #2 and the other footings only experience compression.

- The tensile break may occur at the upper derrick footing for 100 year and 1000 year hurricane conditions, when the pretension is 225 kips.

- The tensile break may occur at the substructure footing for 1000 year hurricane condition, when the bolt pretension is 225 kips.

	Fx	Fy	N1	N2	N3	N4
Max	32.88	6.23	140.22	131.89	140.22	365.41
Min	-6.22	-32.86	134.21	-88.52	134.21	141.38
Mean	11.81	-11.80	137.54	33.57	137.46	241.44

Table B-1. Re	action Forces a	at the Upper	<b>Derrick Footings</b>	(10 Year Hurricane)
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	Fx	Fy	N1	N2	N3	N4
Max	69.77	42.80	602.62	587.89	528.38	890.85
Min	-42.79	-69.76	491.15	141.17	428.69	430.65
Mean	13.81	-13.80	543.23	379.59	481.79	645.43

 Table B-2. Reaction Forces at the Substructure Footings (10 Year Hurricane)

 Table B-3. Reaction Forces at the Upper Derrick Footings (100 Year Hurricane)

	Fx	Fy	N1	N2	N3	N4
Max	58.87	9.99	143.15	91.19	142.94	558.08
Min	-9.97	-58.83	132.47	-284.51	132.33	181.56
Mean	25.78	-25.76	137.60	-89.31	137.38	364.30

Table B-4. Reaction Forces at the Substructure Footings (100 Year Hurricane)

	Fx	Fy	N1	N2	N3	N4
Max	130.95	78.54	676.90	620.36	538.44	1197.44
Min	-79.70	-129.76	478.03	-156.46	362.15	388.91
Mean	31.27	-30.12	579.55	222.39	445.39	802.55

Table B-5. Reaction Forces at the Upper Derrick Footings (1000 Year Hurricane)

	Fx	Fy	N1	N2	N3	N4
Max	69.39	6.38	144.36	92.97	144.09	658.19
Min	-6.36	-69.33	131.77	-384.87	131.39	181.23
Mean	30.17	-30.13	137.77	-127.65	137.46	402.88

 Table B-6. Reaction Forces at the Substructure Footings (1000 Year Hurricane)

	Fx	Fy	N1	N2	N3	N4
Max	147.48	90.44	703.02	588.38	528.77	1311.09
Min	-90.40	-147.44	488.12	-271.79	335.19	433.63
Mean	35.28	-35.23	591.38	173.68	434.44	852.15

 Table B-7. Shear and Slip Safety Factor of the Upper Derrick Footing for 10 year Hurricane Load Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)

			Bolt Shear			
Pretension	Fx (kips)	Fy(kips)	Fact.	Bolt Slip	Fact. Of	Safety
(kips)	SHEAR	SLIP	of Safety	0.1	0.3	0.5
137.3	32.882	32.862	24.879	3.761	11.283	18.804
75	32.882	32.862	24.879	2.244	6.733	11.221
150	32.882	32.862	24.879	4.070	12.210	20.350
225	32.882	32.862	24.879	5.896	17.687	29.479

			Bolt Shear			
Pretension	Fx (kips)	Fy(kips)	Fact.	Bolt Slip	Fact. Of	Safety
(kips)	SLIP	SHEAR	of Safety	0.1	0.3	0.5
137.3	69.774	42.802	19.113	2.309	6.926	11.544
75	69.774	42.802	19.113	1.594	4.783	7.972
150	69.774	42.802	19.113	2.454	7.363	12.272
225	69.774	42.802	19.113	3.314	9.943	16.571

 

 Table B-8. Shear and Slip Safety Factor of the Substructure Footing for 10 year Hurricane Load Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)

Table B-9.	Shear and Slip Safety Factor of the Upper Derrick and the Substructure Footing for 10 year
	Hurricane Load Condition (Evaluated for 4 different pretension condition)

	Fz	Т	Torque(lb-ft)	4576.7	2500	5000	7500
	(kips)	(kips)	T0(in kips) =	137.3	75	150	225
Upper Der	-88.522	-11.065	Safety Factors	-9.950	-15.580	-8.802	-2.024
Substruct	141.173	17.647	-	6.239	9.770	5.519	1.269

• The positive indicates the compression and the negative sign means the tensile force

 Table B-10. Shear and Slip Safety Factor of the Upper Derrick Footing for 100 year Hurricane Load

 Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)

			Bolt Shear			
Pretension	Fx (kips)	Fy(kips)	Fact.	Bolt Slip	Fact. Of	Safety
(kips)	SHEAR	SLIP	of Safety	0.1	0.3	0.5
137.3	58.867	58.830	13.897	2.101	6.302	10.504
75	58.867	58.830	13.897	1.254	3.761	6.268
150	58.867	58.830	13.897	2.273	6.820	11.367
225	58.867	58.830	13.897	3.293	9.880	16.467

Table B-11. Shear and Slip Safety Factor of the	e Substructure Footing for 100 year Hurricane Load	ıd
Condition (Evaluated for 4 different	pretension condition and 3 friction coeff.)	

			Bolt Shear			
Pretension	Fx (kips)	Fy(kips)	Fact.	Bolt Slip	Fact. Of	Safety
(kips)	SLIP	SHEAR	of Safety	0.1	0.3	0.5
137.3	130.950	129.757	6.305	1.230	3.691	6.151
75	130.950	129.757	6.305	0.850	2.549	4.248
150	130.950	129.757	6.305	1.308	3.923	6.539
225	130.950	129.757	6.305	1.766	5.298	8.830

 Table B-12. Shear and Slip Safety Factor of the Upper Derrick and the Substructure Footing for 100 year

 Hurricane Load Condition (Evaluated for 4 different pretension condition)

	Fz	Т	Torque(lb-ft)	4576.7	2500	5000	7500
	(kips)	(kips)	T0(in kips) =	137.3	75	150	225
Upper Der	-284.510	-35.564	Safety Factors	-3.096	-4.848	-2.739	-0.630
Substruct	-156.461	-19.558	-	-5.629	-8.815	-4.980	-1.145

• The positive indicates the compression and the negative sign means the tensile force

			Bolt Shear			
Pretension	Fx (kips)	Fy(kips)	Fact.	Bolt Slip	Fact. Of	Safety
(kips)	SHEAR	SLIP	of Safety	0.1	0.3	0.5
137.3	69.390	69.330	11.789	1.783	5.348	8.913
75	69.390	69.330	11.789	1.064	3.191	5.319
150	69.390	69.330	11.789	1.929	5.788	9.646
225	69.390	69.330	11.789	2.795	8.384	13.973

 Table B-13. Shear and Slip Safety Factor of the Upper Derrick Footing for 1000 year Hurricane Load

 Condition (Evaluated for 4 different pretension condition and 3 friction coeff.)

Table B-14.	Shear and Slip Safety Factor of the	e Substructure Footing for	1000 year Hurricane Load
(	<b>Condition (Evaluated for 4 different</b>	pretension condition and 3	3 friction coeff.)

			Bolt Shear			
Pretension	Fx (kips)	Fy(kips)	Fact.	Bolt Slip	Fact. Of	Safety
(kips)	SLIP	SHEAR	of Safety	0.1	0.3	0.5
137.3	147.484	147.443	5.548	1.092	3.277	5.461
75	147.484	147.443	5.548	0.754	2.263	3.772
150	147.484	147.443	5.548	1.161	3.483	5.806
225	147.484	147.443	5.548	1.568	4.704	7.840

 Table B-15. Shear and Slip Safety Factor of the Upper Derrick and the Substructure Footing for 1000 year

 Hurricane Load Condition (Evaluated for 4 different pretension condition)

	Fz	Т	Torque(lb-ft)	4576.7	2500	5000	7500
	(kips)	(kips)	T0(in kips) =	137.3	75	150	225
Upper Der	-384.872	-48.109	Safety Factors	-2.289	-3.584	-2.025	-0.466
Substruct	-271.793	-33.974		-3.241	-5.074	-2.867	-0.659

• The positive indicates the compression and the negative sign means the tensile force

## **12.0 APPENDIX C: SPRING CONNECTION MODEL**

Assuming that the body rotational motion is small enough, the point at the body is calculated by the following equation.

$$\left\{\underline{x}\right\} = \left\{\underline{X}\right\} + \left[\underline{p}^{\times}\right]\left\{\underline{\theta}\right\}$$
(C-1)

where

 $\{\underline{x}\}$  =column vector of a point at the body at the inertia frame,

 $\{\underline{X}\}$  =column vector of the linear motion of the body reference point,

 $\left[ \underline{p}^{\times} \right]$  = cross product matrix of the local coordinate of the point,

 $\{\underline{\theta}\}$ =rotational motion of the body in the inertia frame.

The displacement due to the forces in section 6 is obtained by the derivative of equation (C-1)

$$\left\{\Delta \underline{x}\right\} = \left\{\Delta \underline{X}\right\} + \left[\underline{p}^{\times}\right] \left\{\Delta \underline{\theta}\right\}$$
(C-2)

The reaction force at the spring is calculated by the spring constant

$$\{Fs\} = -[k]\{\Delta \underline{x}\} = -[k]\{\Delta \underline{X}\} - [k][\underline{p}^{\times}]\{\Delta \underline{\theta}\}$$
(C-3)

The moment due to the spring reaction force is derived by:

$$\{Ns\} = \left[\underline{p}^{\times}\right]\{Fs\} = -\left[\underline{p}^{\times}\right]\left[k\right]\left\{\Delta\underline{X}\right\} - \left[\underline{p}^{\times}\right]\left[k\right]\left[\underline{p}^{\times}\right]\left\{\Delta\underline{\theta}\right\}$$
(C-4)

Resultantly, the global stiffness matrix due to the spring is

$$\begin{bmatrix} K \end{bmatrix} = \begin{bmatrix} [k] & [k] \begin{bmatrix} \underline{p}^{\times} \end{bmatrix} \\ \begin{bmatrix} \underline{p}^{\times} \end{bmatrix} [k] & \begin{bmatrix} \underline{p}^{\times} \end{bmatrix} [k] \begin{bmatrix} \underline{p}^{\times} \end{bmatrix} \end{bmatrix}$$
(C-5)

The body motion can be obtained through the static equilibrium betwen the body forces and the spring force as:

$$\begin{cases} \Delta \underline{X} \\ \Delta \underline{\theta} \end{cases} = -\left[ K \right]^{-1} \begin{cases} \underline{F} \\ \underline{M} \end{cases}$$
 (C-6)

where  $\underline{F}$ ,  $\underline{M}$  are the total forces and moments obtained in section 6.

After then, the spring reaction forces are calculated by equation (C-3).

## 13.0 APPENDIX D: COMPARISON OF HORIZONTAL ACCELERATION BETWEEN EXACT SIMULATION METHOD AND API FORMULA

$$m_0 = \sigma \tag{1}$$

Where  $m_0$  is the zeroth moment of the motion spectrum and  $\sigma$  is the standard deviation of the time dependent motion.

$$x_{1/1000} = 3.72m_0 \tag{2}$$

Assuming the maximum values in 3 hour is  $1/1000^{\text{th}}$  probability, the maximum in 3 hour can be approximated by equation (2)

The acceleration can be obtained by

$$a_{x\max} = \omega^2 x_{1/1000}$$
(3)

We have wave frequency and low frequency motion which are governed by the incident wave and the wind, respectively. Thus, the peak period of the wave frequency motion is at wave peak period, and the low frequency motion follows the wind spectrum. The low frequency motion peak period is assumed as natural period of surge motion (183.5 sec).

The resultant maximum acceleration is summation of the accelerations from wave frequency and the low frequency motion.

		Wave Fre	equency Low Frequency Total		Low Frequency		Total	
			Tp(sec)	$a_{x \max}/g$	RMS	Tnat(sec)	$a_{x \max}/g$	$a_{x \max}/g$
Derrick	10yr	2.915	11.900	0.094	13.483	183.500	0.002	0.096
CG	100yr	8.379	14.000	0.195	15.428	183.500	0.002	0.197
	1000yr	12.484	15.600	0.234	18.463	183.500	0.003	0.237
Substructure	10yr	2.896	11.900	0.093	13.464	183.500	0.002	0.095
CG	100yr	8.349	14.000	0.194	15.399	183.500	0.002	0.197
	1000yr	12.441	15.600	0.233	18.419	183.500	0.002	0.236

## 14.0 APPENDIX E: COMPARISON BETWEEN MHKIM AND TECHNIP FOR TLP MAXIMUM BOLT TENSION

 Table E1. Maximum bolt tension on upper derrick (0-degree heading unit: kips, negative sign=tension on bolt)

	DOIL)	
	MHKIM	TECHNIP
10-year	15	48
100-year	-93	-42
1000-yr	-150	-80

Table E2. Maximum bolt tension on upper derrick (45-degree heading unit: kips, negative sign=tension on bolt)

	MHKIM	TECHNIP
10-year	-88	-38
100-year	-284	-216
1000-yr	-384	-290

Table E3. Maximum bolt tension on sub-structure footing (0-degree heading unit: kips, negative sign=tension on bolt)

	MHKIM	TECHNIP
10-year	275	273
100-year	101	91
1000-yr	30	-8

Table E4. Maximum bolt tension on sub-structure footing (45-degree heading unit: kips, negative
sign=tension on bolt)

	MHKIM	TECHNIP
10-year	141	146
100-year	-156	-132
1000-yr	-271	-283

MHKIM: Direct time domain simulation including all the dynamic forces based on the timedomain motion and acceleration time series results

Technip: Select maximum combined loading from wind force/acceleration force time series and then run statics program STRUCAD.